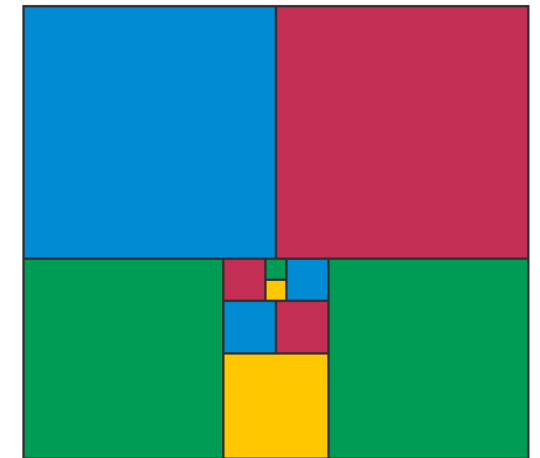
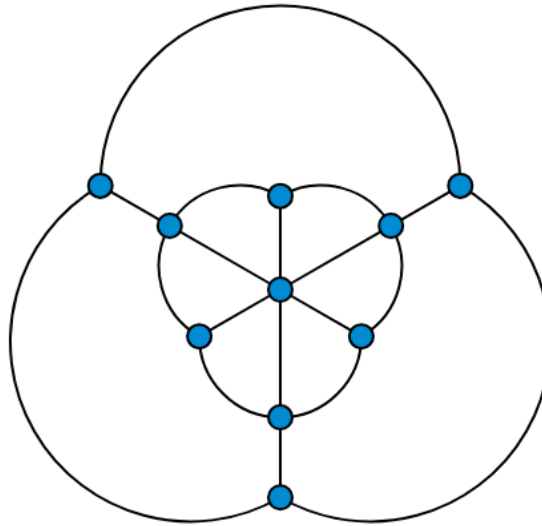
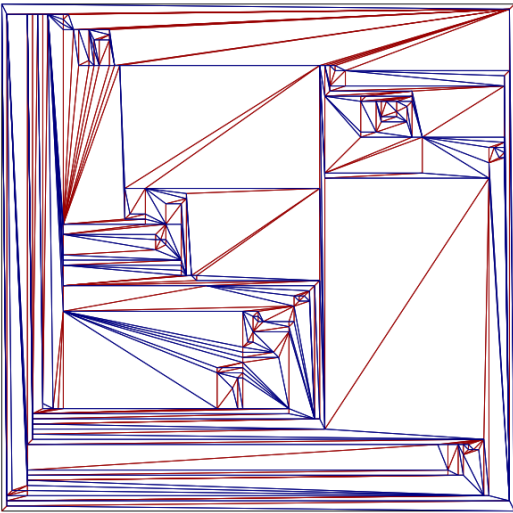
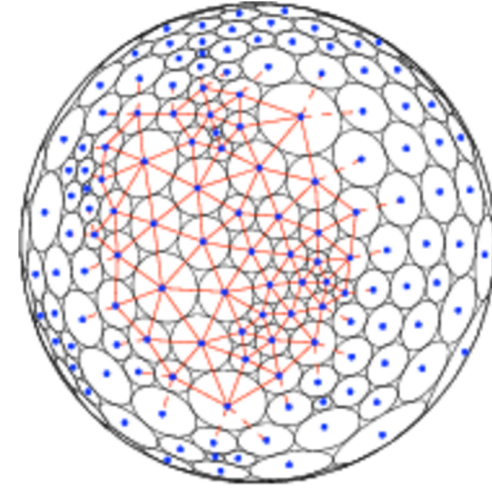
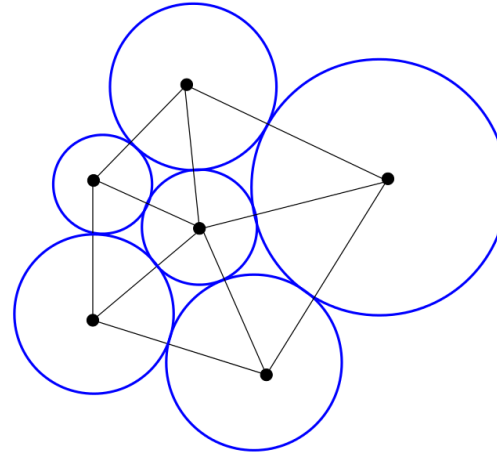
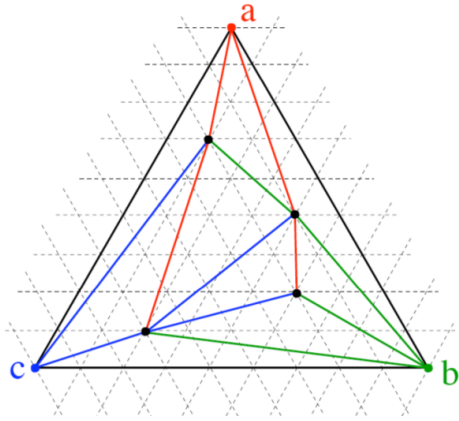
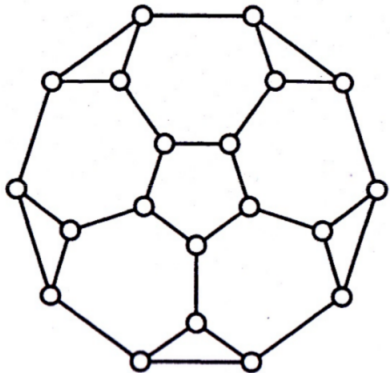


# Planar maps: bijections and applications

Éric Fusy (CNRS/LIX)

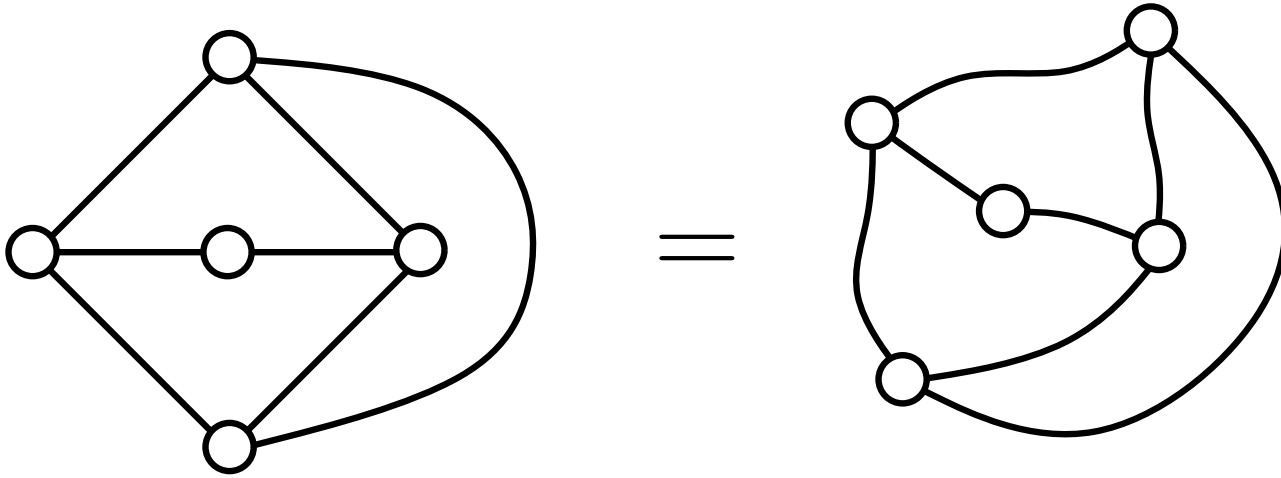
# Geometric representation of planar maps

Various methods can be used to draw a map on the plane/sphere



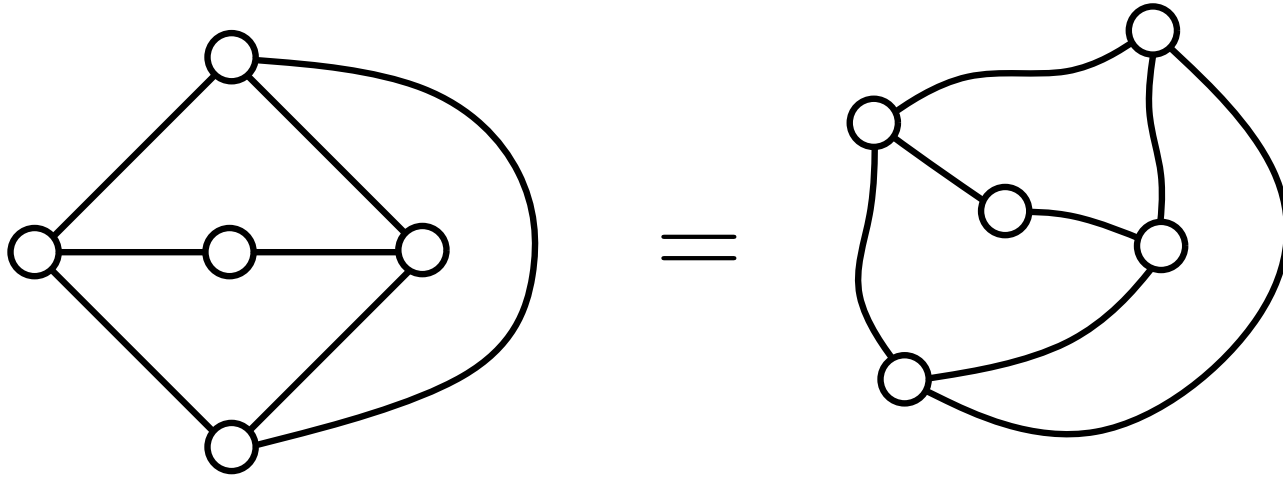
# Existence question

planar map (with outer face) = equivalence class of planar drawings of graphs up to continuous deformation



# Existence question

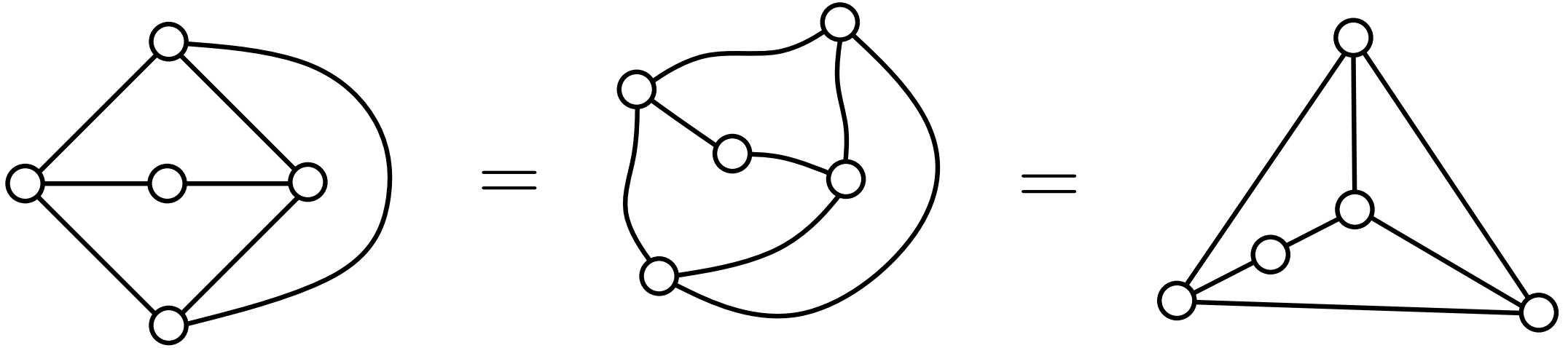
planar map (with outer face) = equivalence class of planar drawings of graphs up to continuous deformation



**Question:** Does there always exist an equivalent planar drawing such that all edges are drawn as segments ?

# Existence question

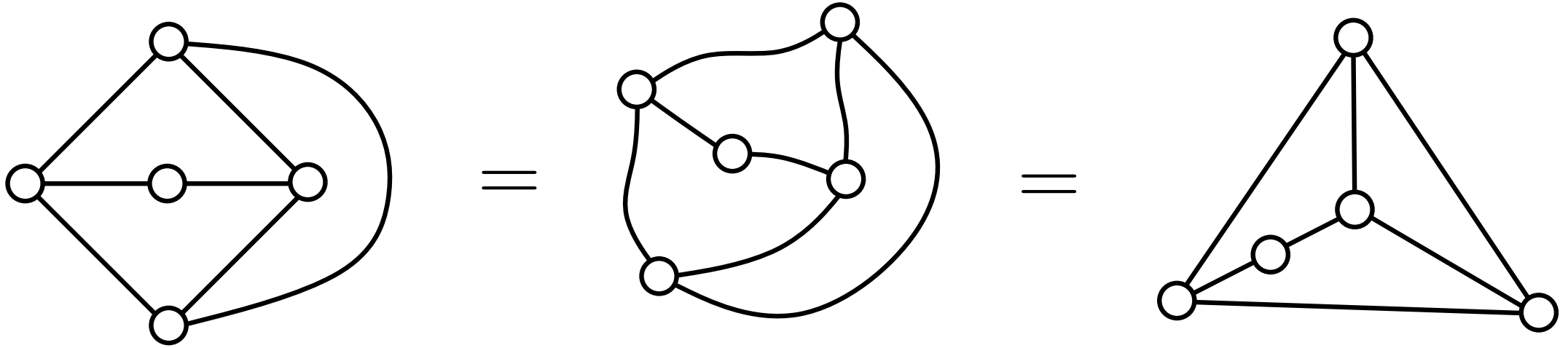
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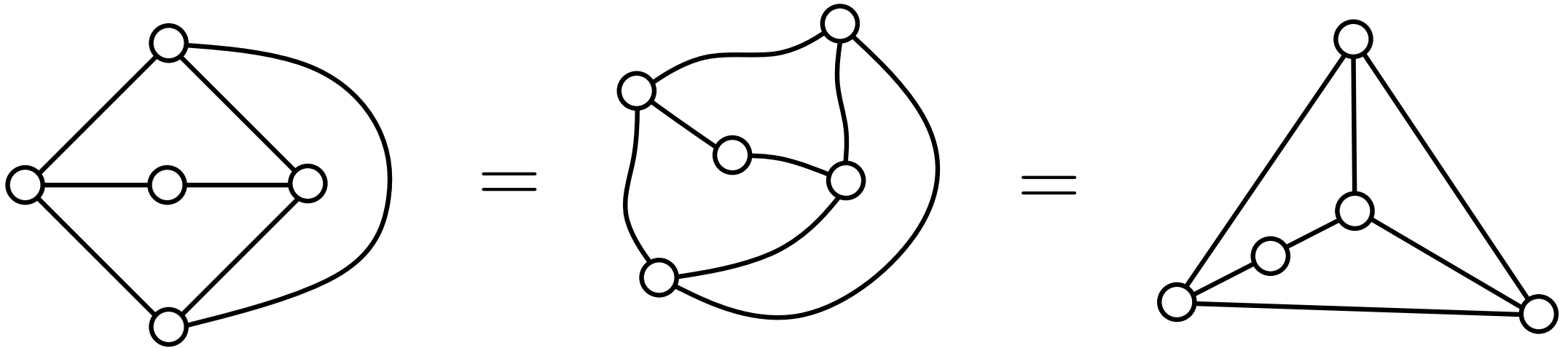


**Question:** Does there always exist an equivalent planar drawing such that all edges are drawn as segments ?

(such as drawing is called a (planar) **straight-line drawing**)

# Existence question

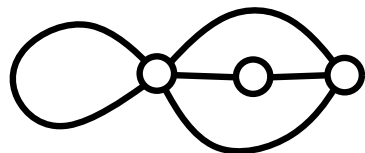
planar map (with outer face) = equivalence class of planar drawings of graphs up to continuous deformation



**Question:** Does there always exist an equivalent planar drawing such that all edges are drawn as segments ?

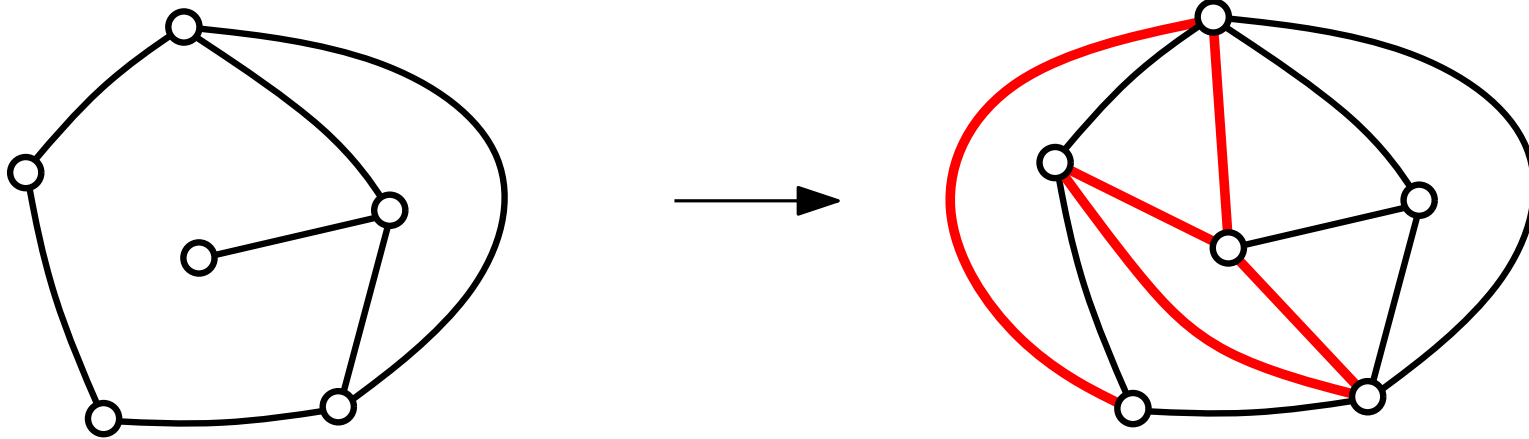
(such a drawing is called a (planar) **straight-line drawing**)

**Remark:** For such a drawing to exist, the map needs to be simple



# Existence proof (reduction to triangulations)

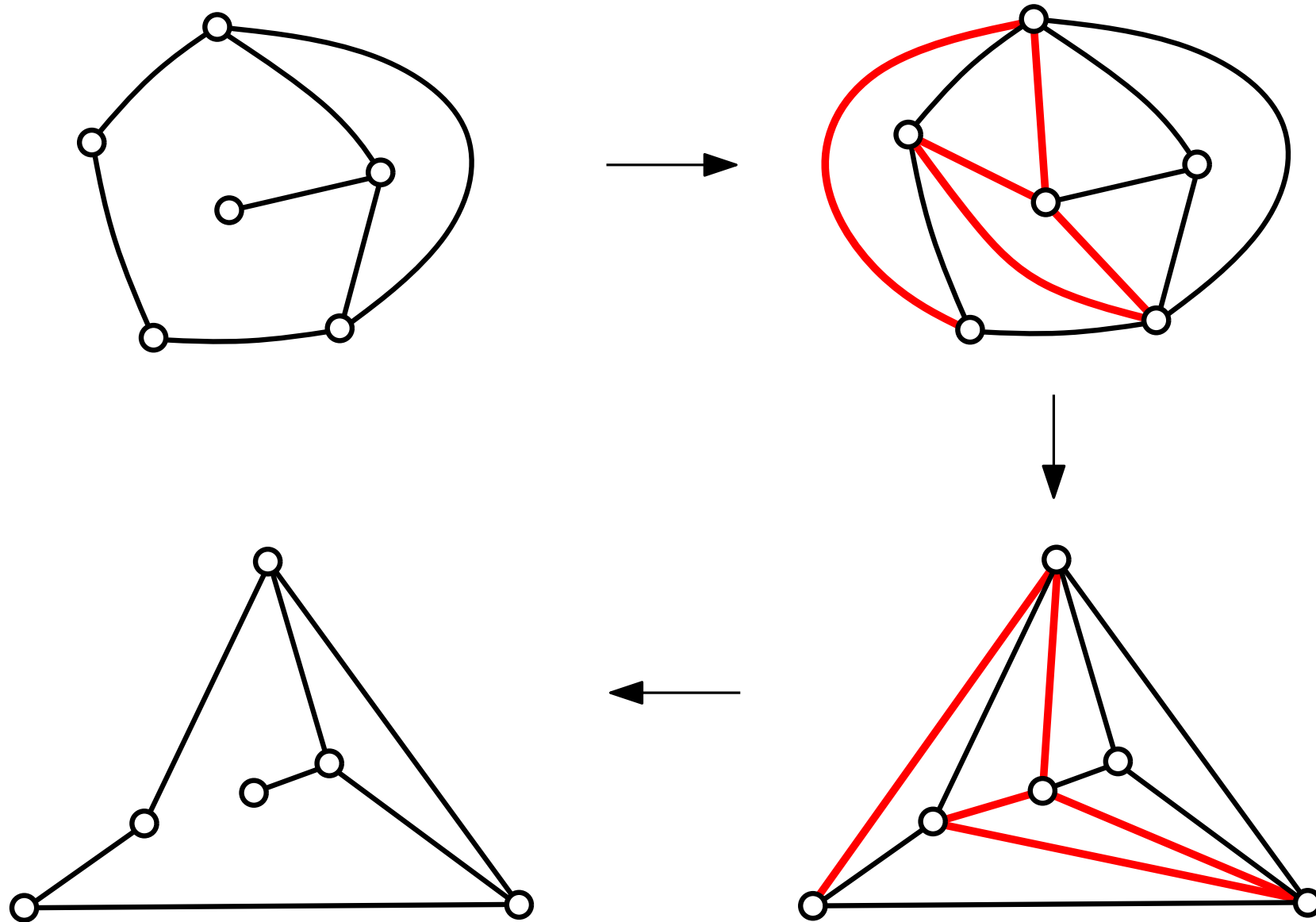
- Any simple planar map  $M$  can be completed to a simple triangulation  $T$





# Existence proof (reduction to triangulations)

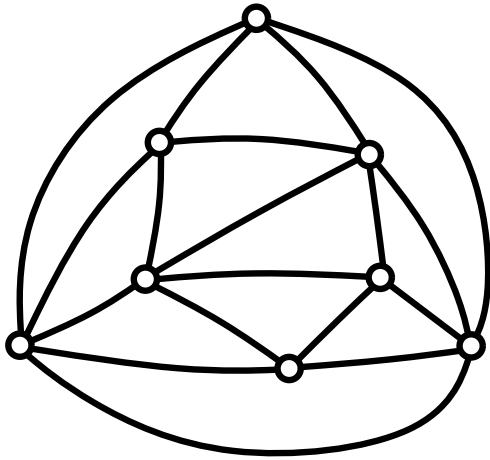
- Any simple planar map  $M$  can be completed to a simple triangulation  $T$
- A straight-line drawing of  $T$  yields a straight-line drawing of  $M$



# Existence proof (for triangulations)

**First proof:** induction on the number of vertices

Let  $T$  be a triangulation with  $n$  vertices

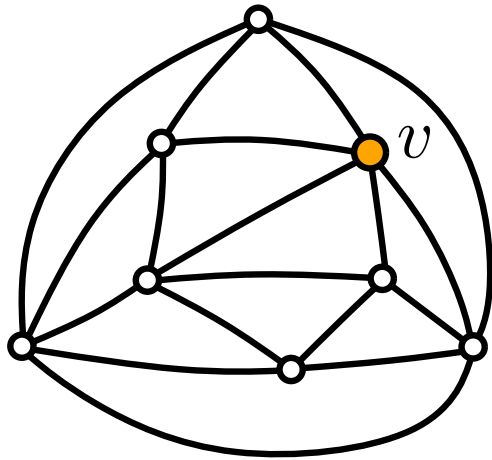


# Existence proof (for triangulations)

**First proof:** induction on the number of vertices

Let  $T$  be a triangulation with  $n$  vertices

**Exercise:**  $T$  has at least one inner vertex  $v$  of degree  $\leq 5$

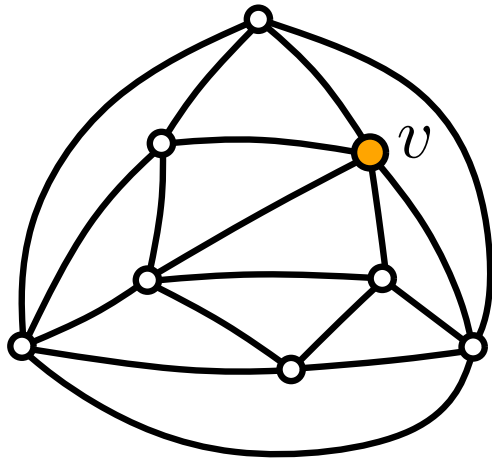


# Existence proof (for triangulations)

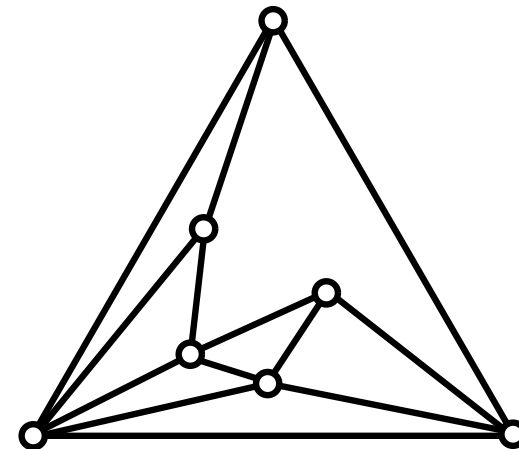
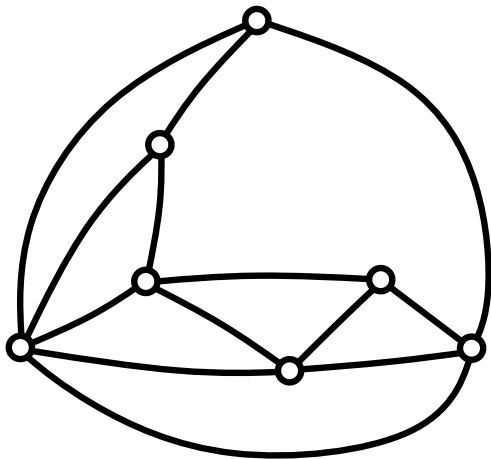
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Let  $T$  be a triangulation with  $n$  vertices

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$T \setminus v$



**induction**

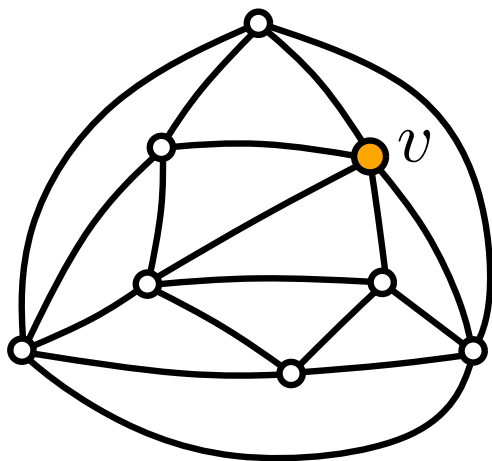
$T \setminus v$  has a straight-line drawing

# Existence proof (for triangulations)

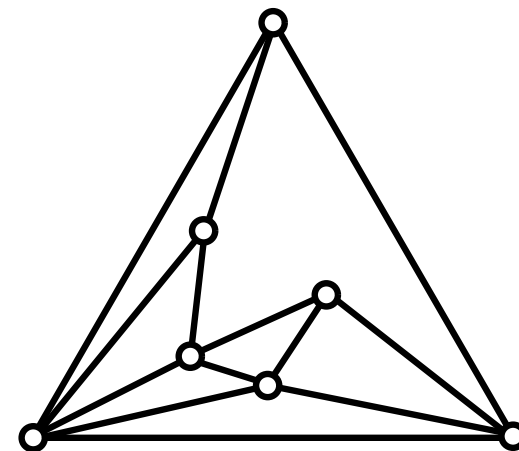
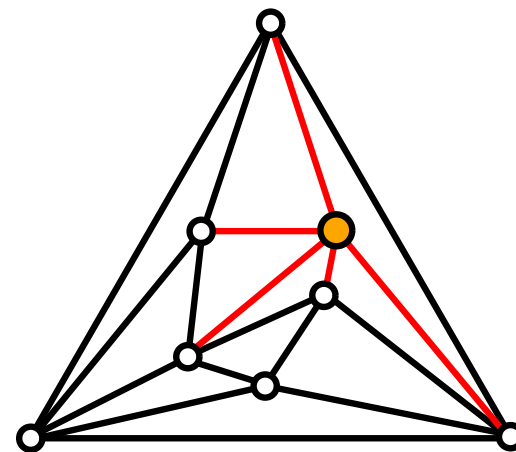
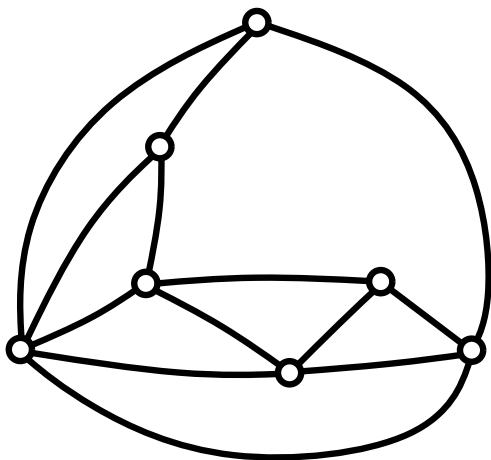
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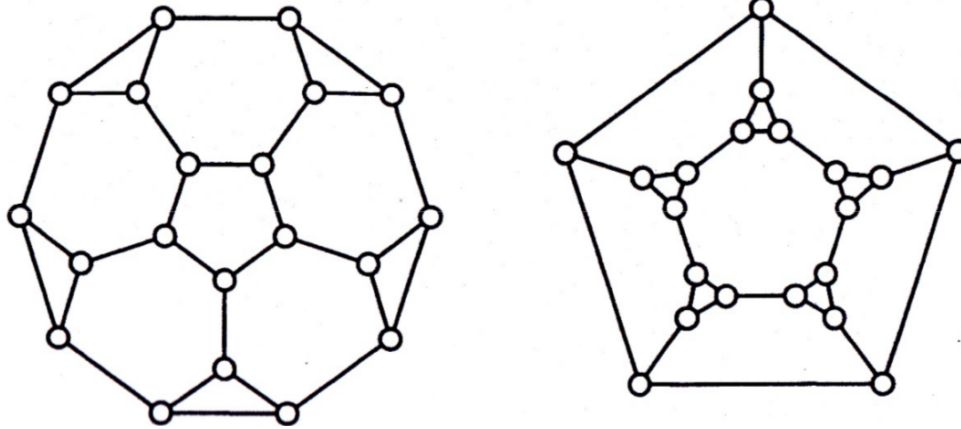
**induction**

$T \setminus v$  has a straight-line drawing

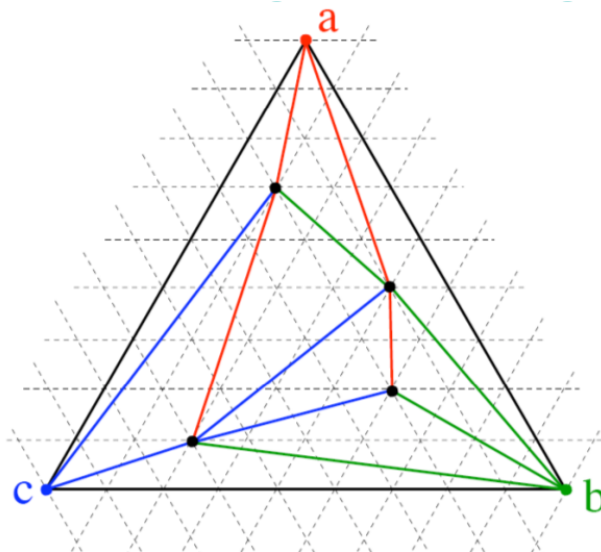
# Straight-line drawing algorithms

We present two classical algorithms

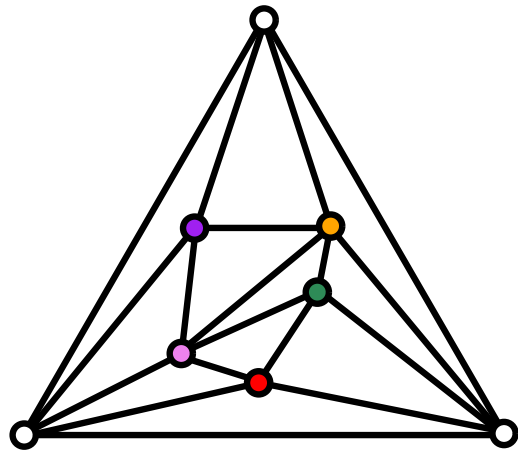
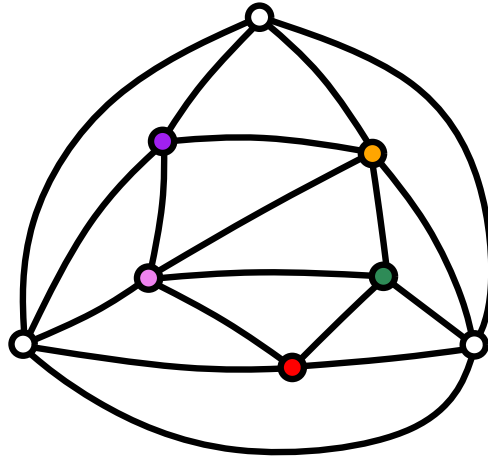
- Tutte's barycentric method



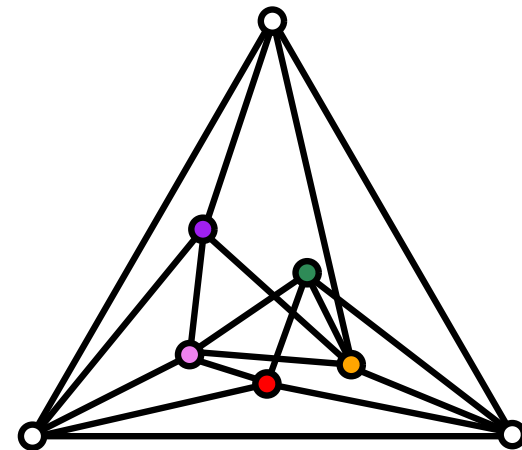
- Schnyder's face-counting algorithm



# Planarity criterion for straight-line drawings

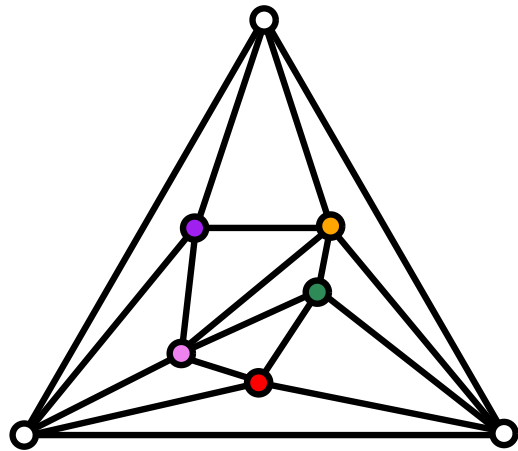
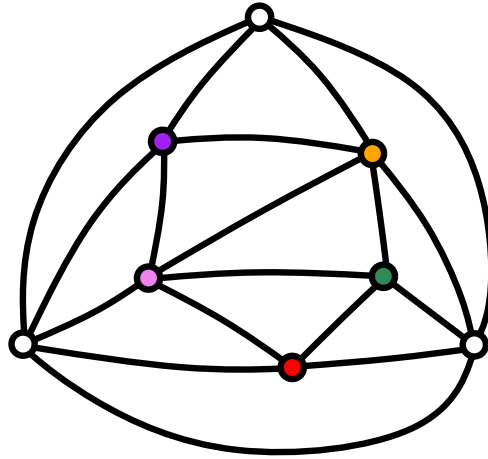


planar

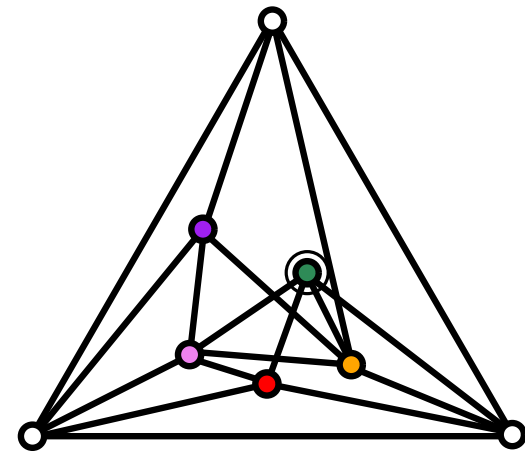


non-planar

# Planarity criterion for straight-line drawings



planar



non-planar

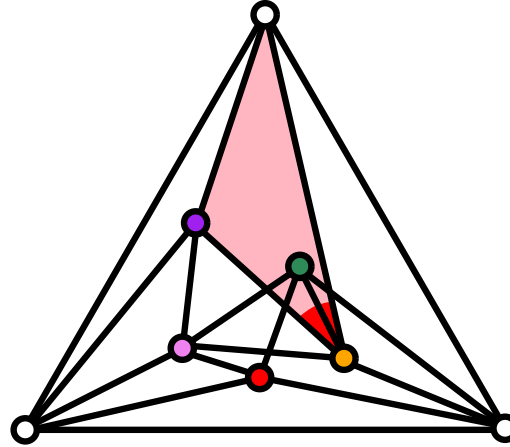
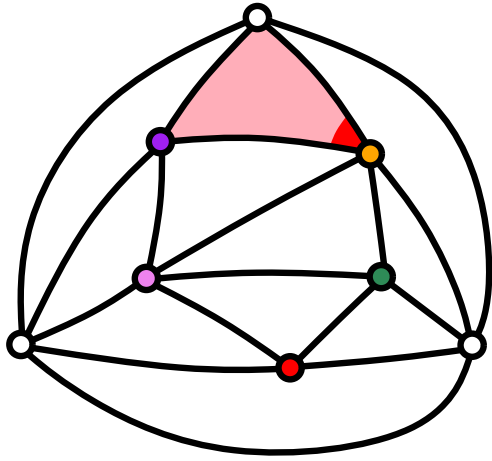
**Theorem:** a straight-line drawing is planar iff every inner vertex is inside the **convex hull** of its neighbours

(works for triangulations and more generally for 3-connected planar graphs)



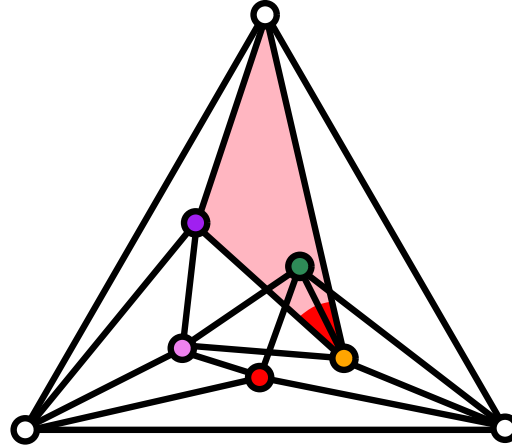
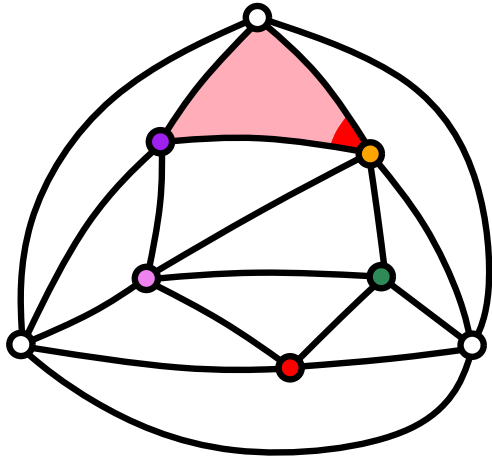
# Proof idea

- For each corner  $c \in T$  let  $\theta(c)$  be the angle of  $c$  in the drawing



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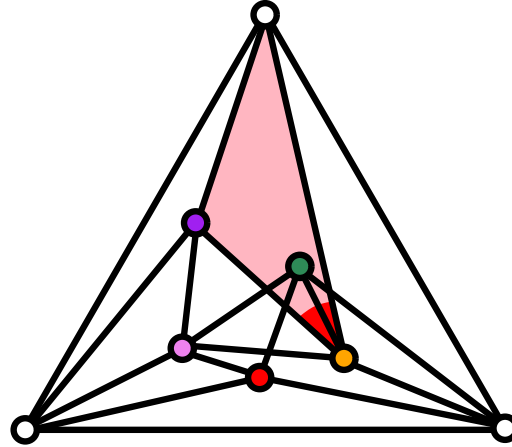
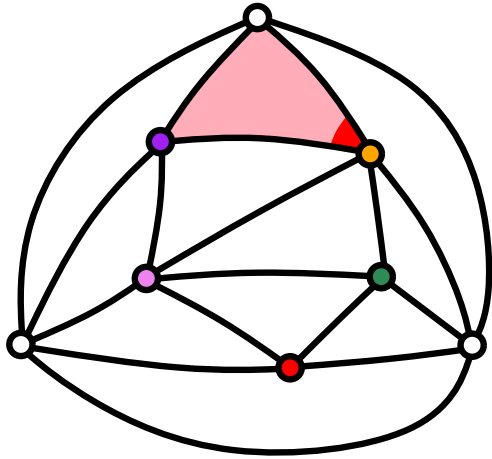
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- For each vertex  $v$ , let  $\Theta(v) = \sum_{c \in v} \theta(c)$

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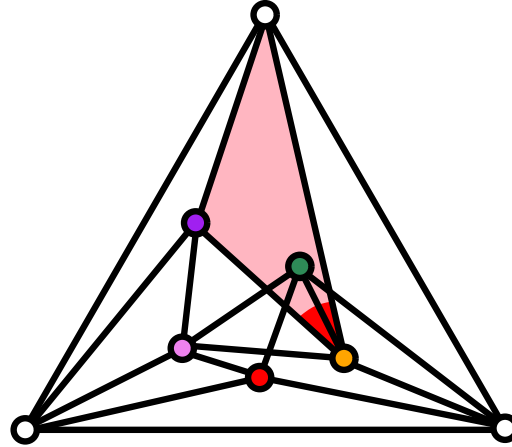
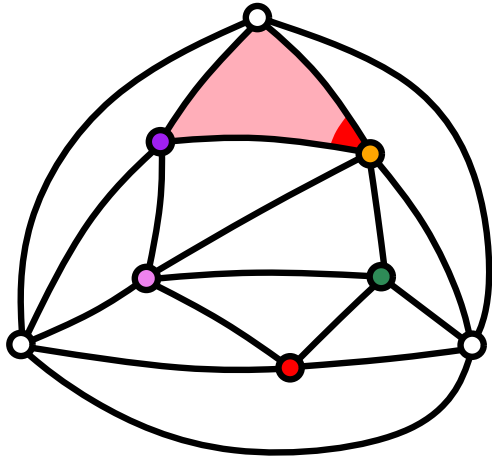
- Whatever the drawing we always have

$$\sum_v \Theta(v) = 2\pi|V|$$

from the Euler relation

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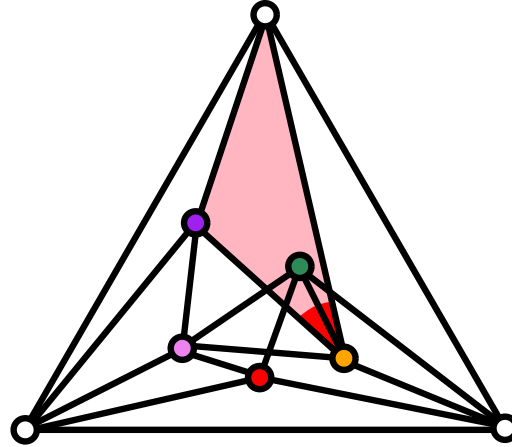
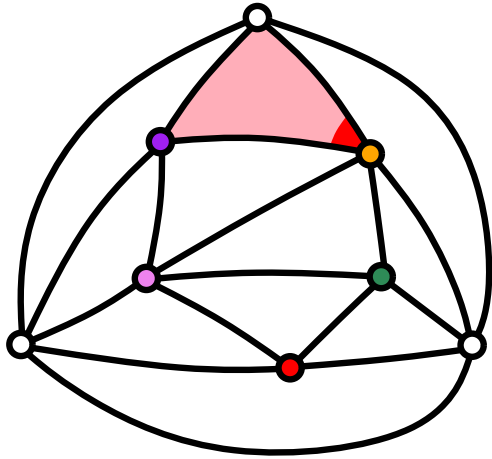


- For each vertex  $v$ , let  $\Theta(v) = \sum_{c \in v} \theta(c)$
- Whatever the drawing we always have  $\sum_v \Theta(v) = 2\pi|V|$
- If convex hull condition holds, then  $\Theta(v) \geq 2\pi$  for each  $v$

from the  
Euler relation

# Proof idea

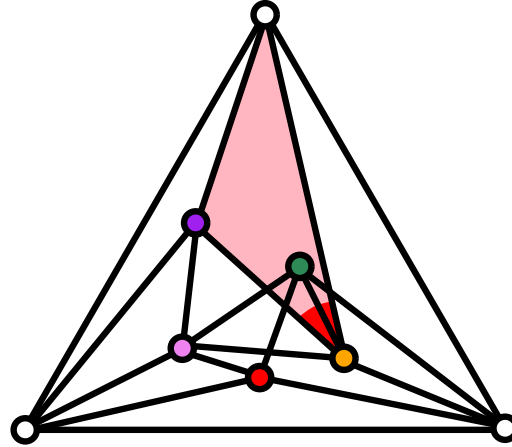
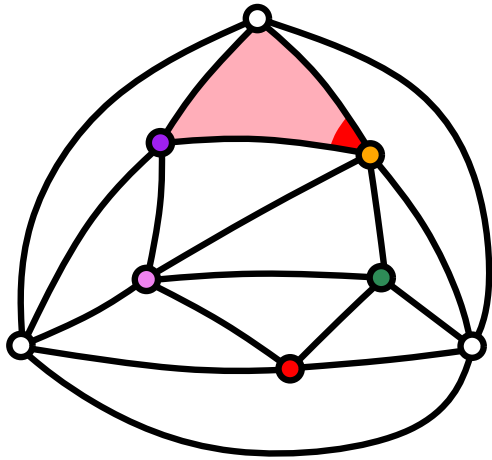
- For each corner  $c \in T$  let  $\theta(c)$  be the angle of  $c$  in the drawing



- For each vertex  $v$ , let  $\Theta(v) = \sum_{c \in v} \theta(c)$
- Whatever the drawing we always have  $\sum_v \Theta(v) = 2\pi|V|$  from the Euler relation
- If convex hull condition holds, then  $\Theta(v) \geq 2\pi$  for each  $v$  and since  $\sum_v \Theta(v) = 2\pi|V|$ , must have  $\Theta(v) = 2\pi$  for each  $v$

# Proof idea

- For each corner  $c \in T$  let  $\theta(c)$  be the angle of  $c$  in the drawing



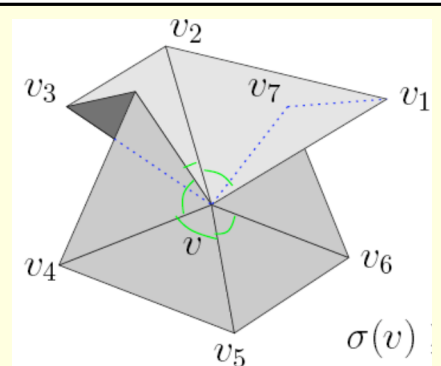
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- Whatever the drawing we always have  $\sum_v \Theta(v) = 2\pi|V|$  from the Euler relation

- If convex hull condition holds, then  $\Theta(v) \geq 2\pi$  for each  $v$  and since  $\sum_v \Theta(v) = 2\pi|V|$ , must have  $\Theta(v) = 2\pi$  for each  $v$

Hence locally planar at each vertex  
(no “folding” of triangles at a vertex)

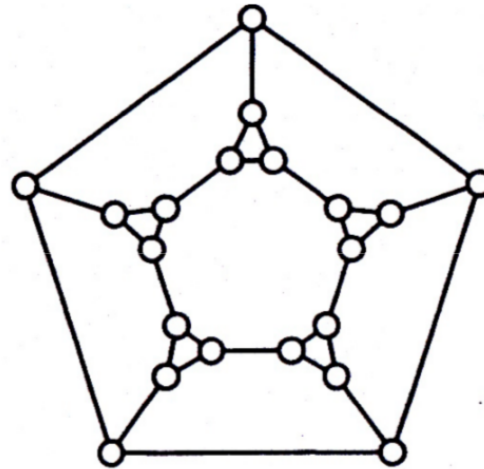
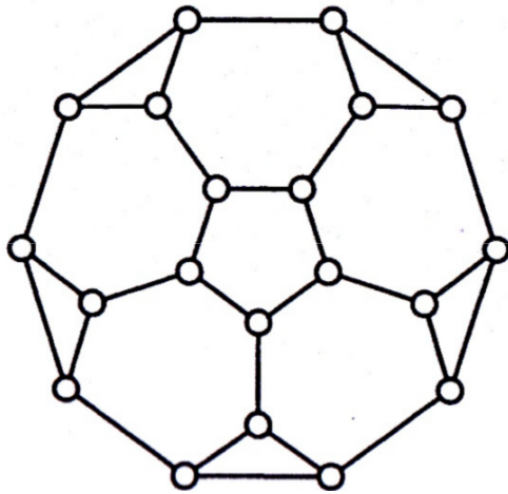
$\Rightarrow$  the drawing is planar



# Tutte's barycentric method

- Outer vertices  $v_1, \dots, v_d$  are fixed at fixed positions (nailed)
- Each inner vertex is at the **barycenter of its neighbours**

$$x_i = \frac{1}{\Delta_i} \sum_{j \sim i} x_j \quad y_i = \frac{1}{\Delta_i} \sum_{j \sim i} y_j \quad \text{for } i \geq 4$$

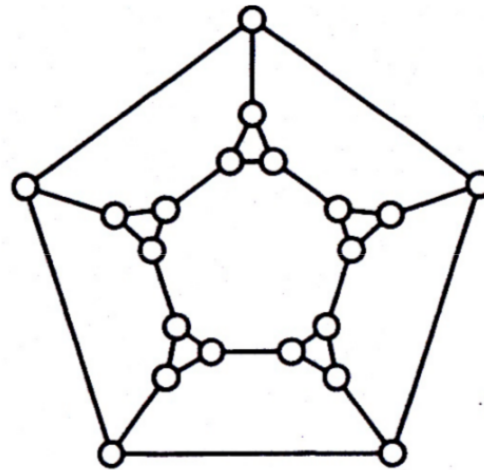
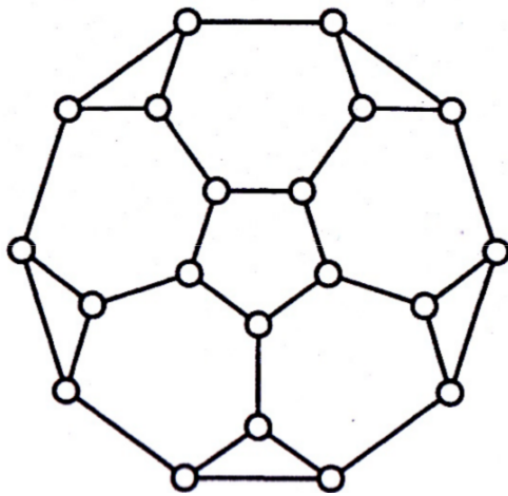


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$$\Leftrightarrow \sum_{j \sim i} x_i - x_j = 0 \quad \text{and} \quad \sum_{j \sim i} y_i - y_j = 0 \quad \text{for each } i \geq 4$$



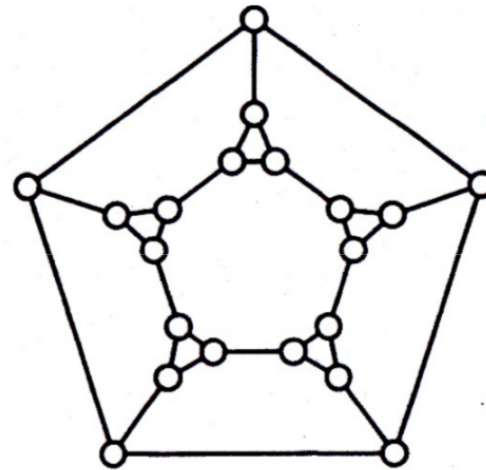
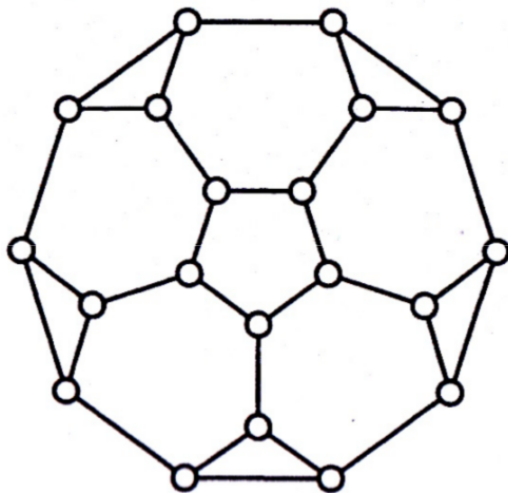


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- This drawing **exists and is unique**. It minimizes the energy

$$\mathcal{P} = \sum_e \ell(e)^2 = \sum_{\{i,j\} \in T} (x_i - x_j)^2 + (y_i - y_j)^2$$

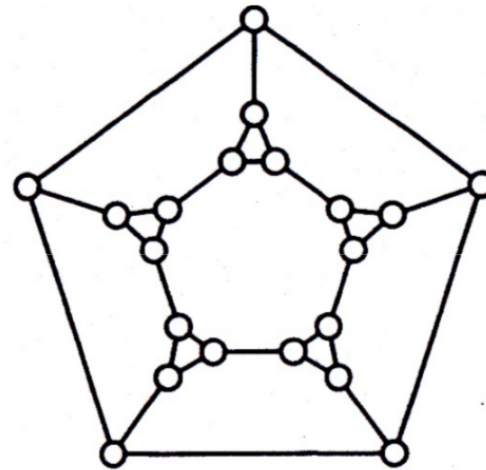
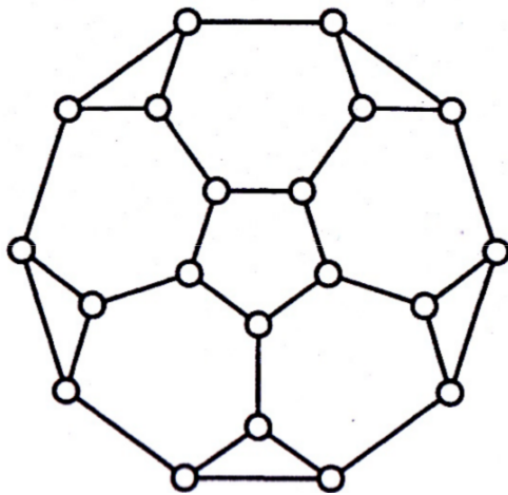
under the constraint of fixed  $x_1, \dots, x_d, y_1, \dots, y_d$

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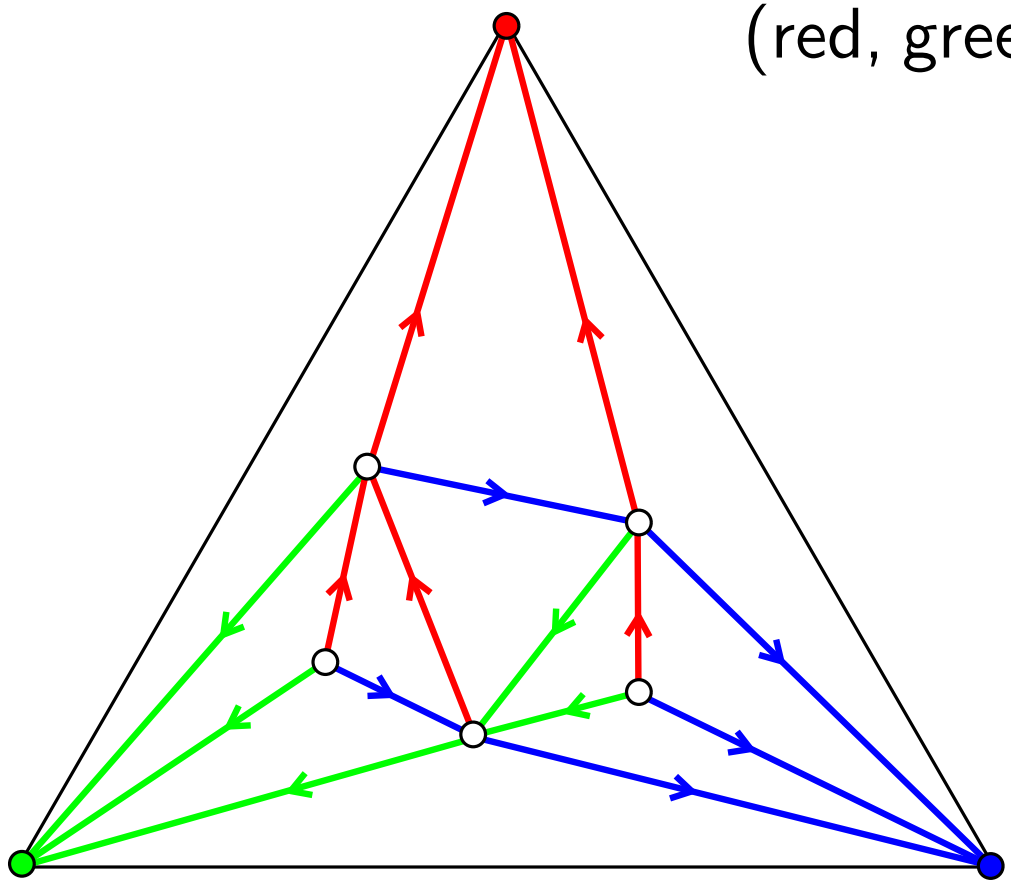
under the constraint of fixed  $x_1, \dots, x_d, y_1, \dots, y_d$

- also called **spring embedding** (each edge is a spring of energy  $\ell(e)^2$ )

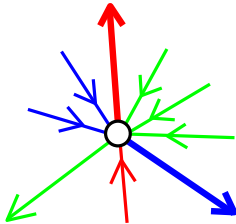
# Schnyder woods on triangulations

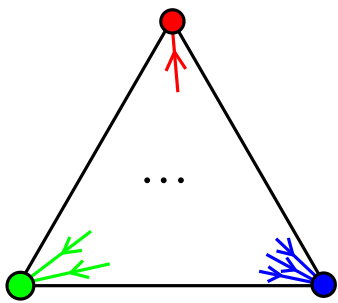
[Schnyder'89]

Schnyder wood = choice of a direction and color (red, green, or blue) for each inner edge, such that:

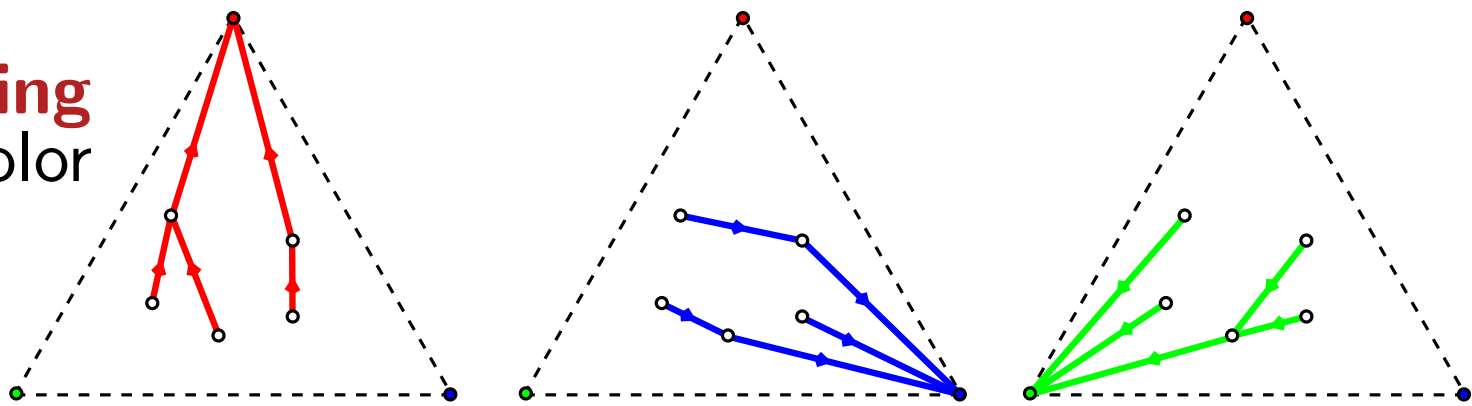


**Local conditions:**

at each inner vertex 

at the outer vertices 

yields a **spanning tree** in each color

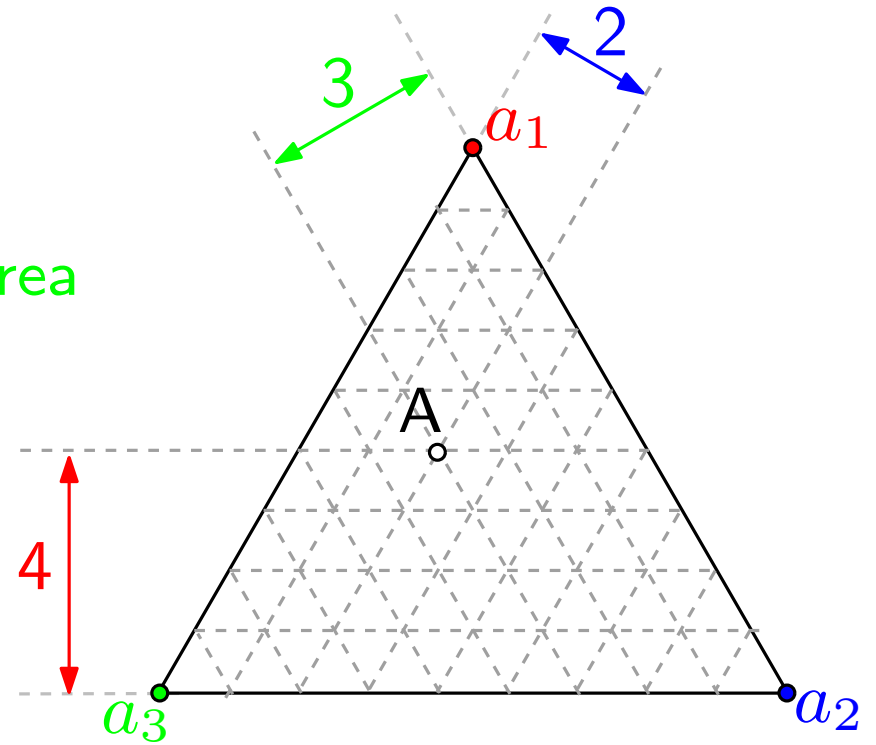
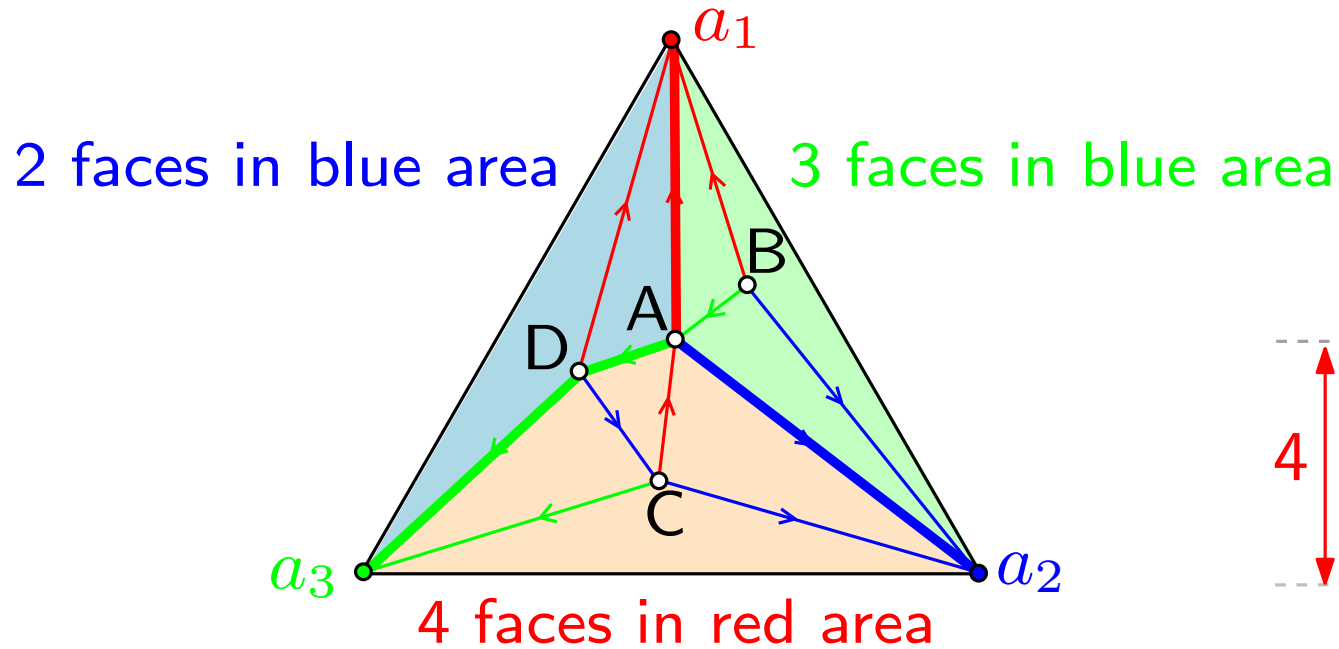


# Schnyder's face-counting algorithm

[Schnyder'90]

**Outer vertices:** equilateral triangle

**Inner vertices:** barycentric placement



place  $A$  at  $\frac{4}{9}a_1 + \frac{2}{9}a_2 + \frac{3}{9}a_3$

# Schnyder's face-counting algorithm

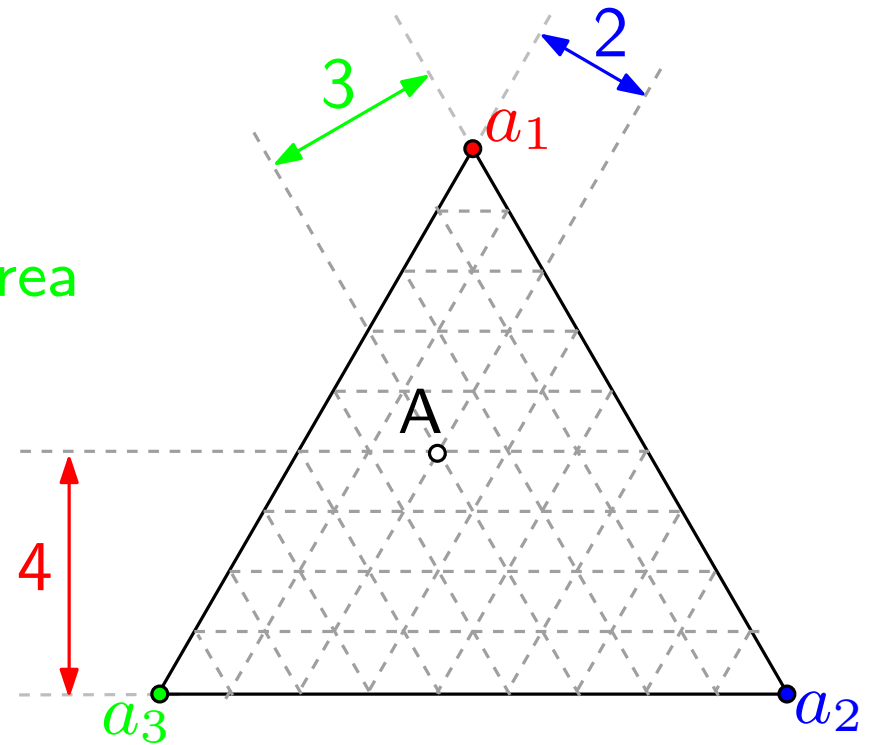
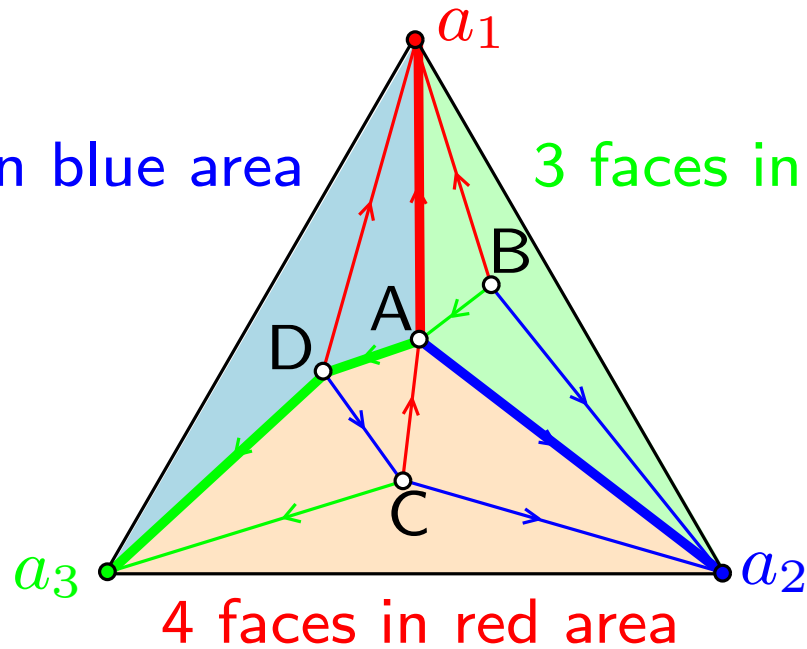
[Schnyder'90]

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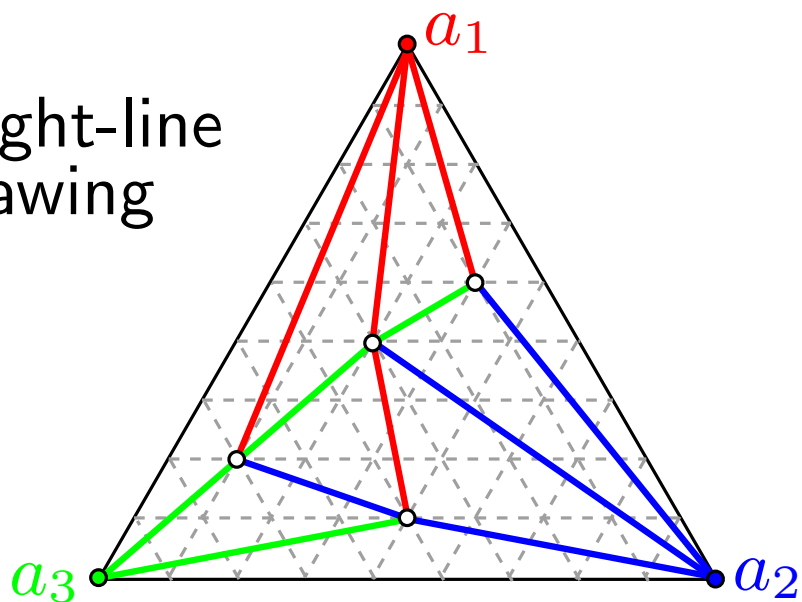
2 faces in blue area

3 faces in green area



place  $A$  at  $\frac{4}{9}a_1 + \frac{2}{9}a_2 + \frac{3}{9}a_3$

straight-line drawing



# Schnyder's face-counting algorithm

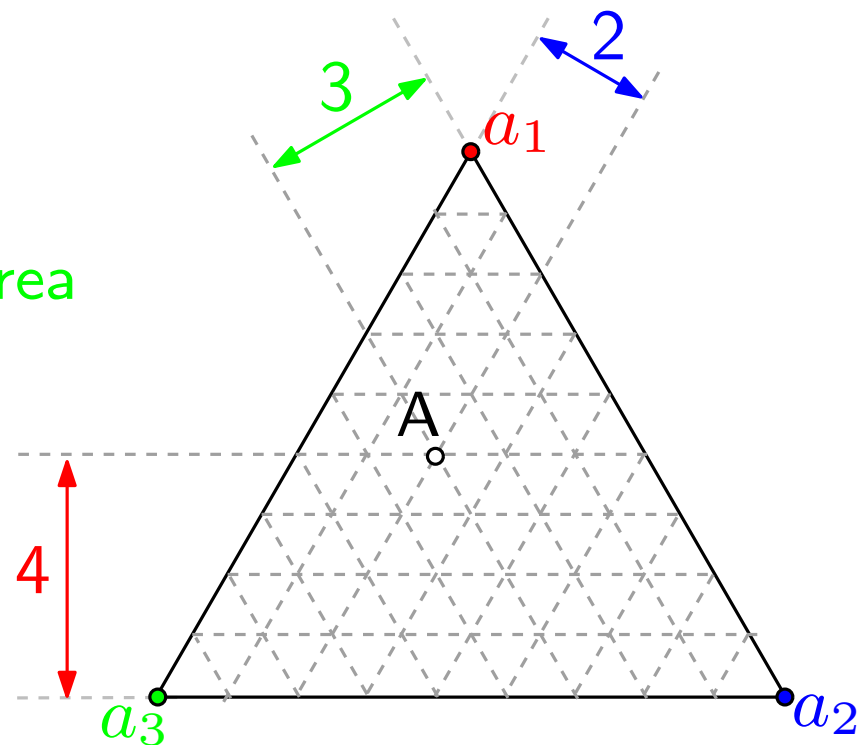
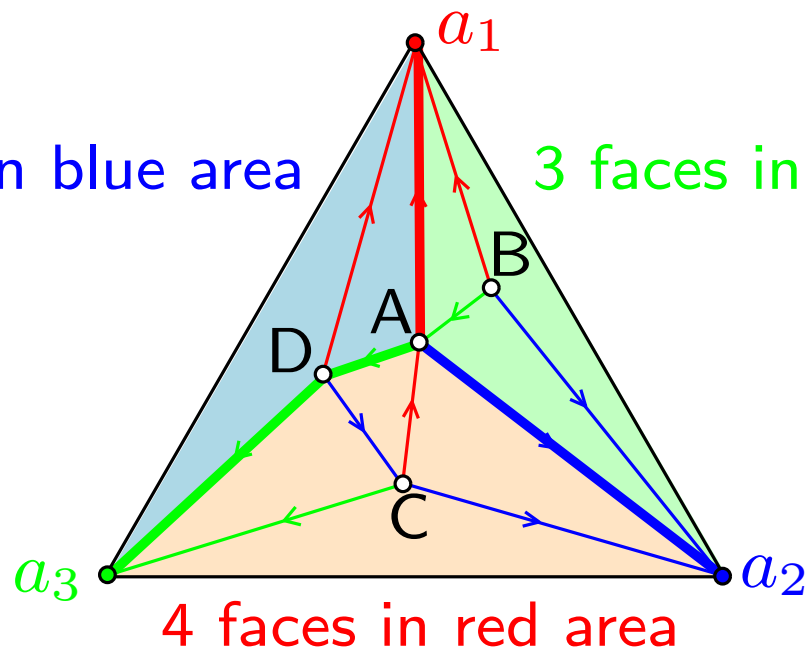
[Schnyder'90]

**Outer vertices:** equilateral triangle

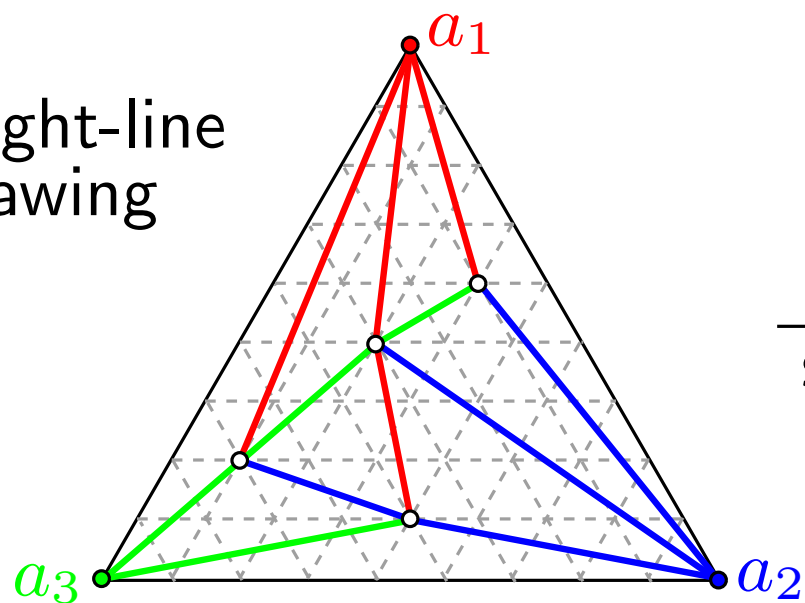
**Inner vertices:** barycentric placement

2 faces in blue area

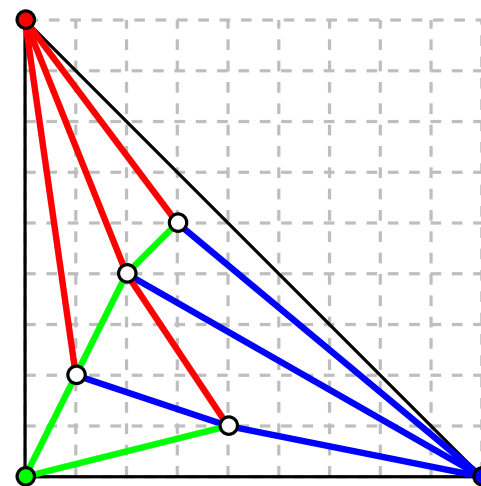
3 faces in green area



straight-line drawing

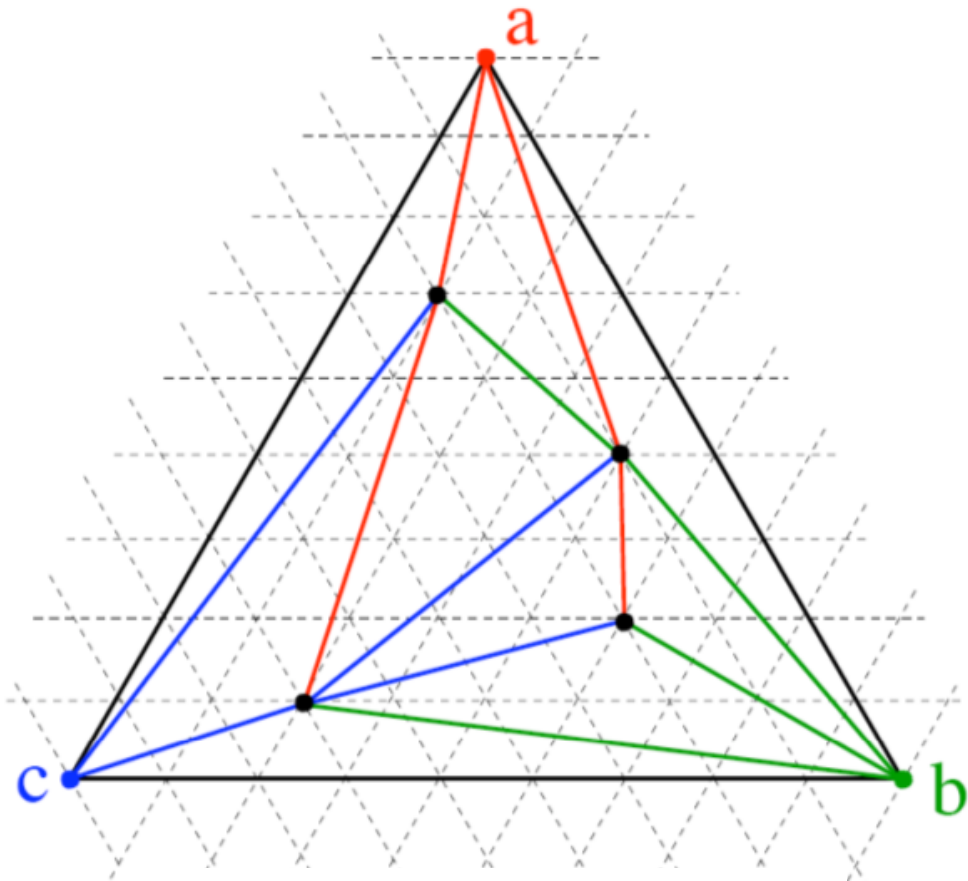


shear

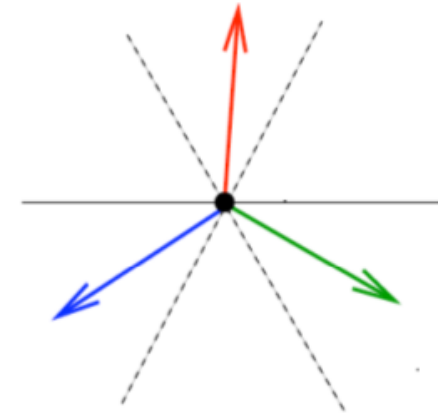


$n$  vertices  
grid  $(2n-5) \times (2n-5)$

# Proof of planarity



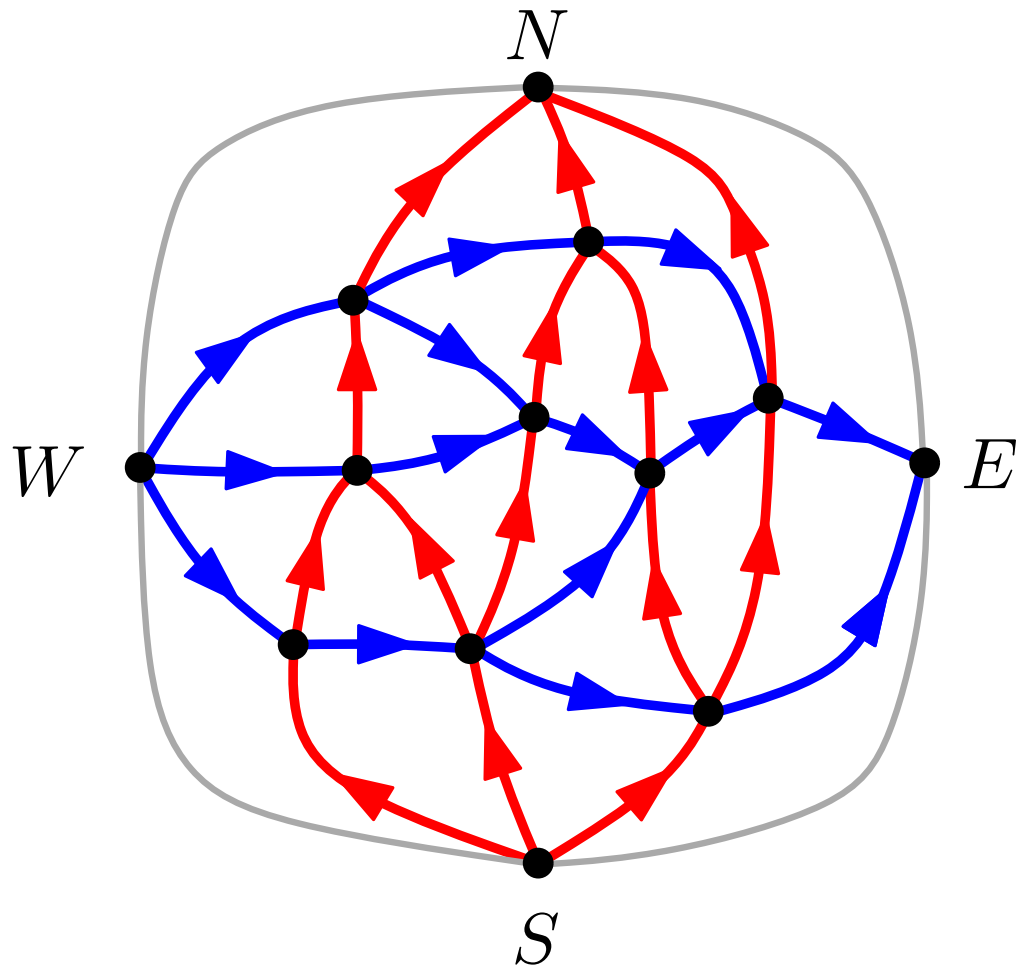
at each inner vertex:



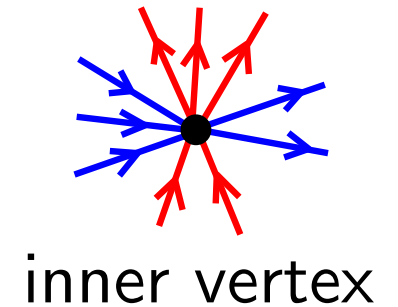
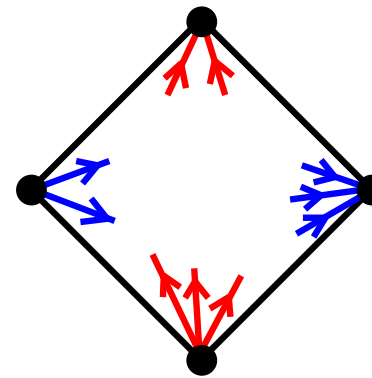
(hence inside the convex hull of neighbours)

# Transversal structures

For  $T$  a triangulation of the 4-gon, a transversal structure is a partition of the inner edges into 2 transversal Hasse diagrams



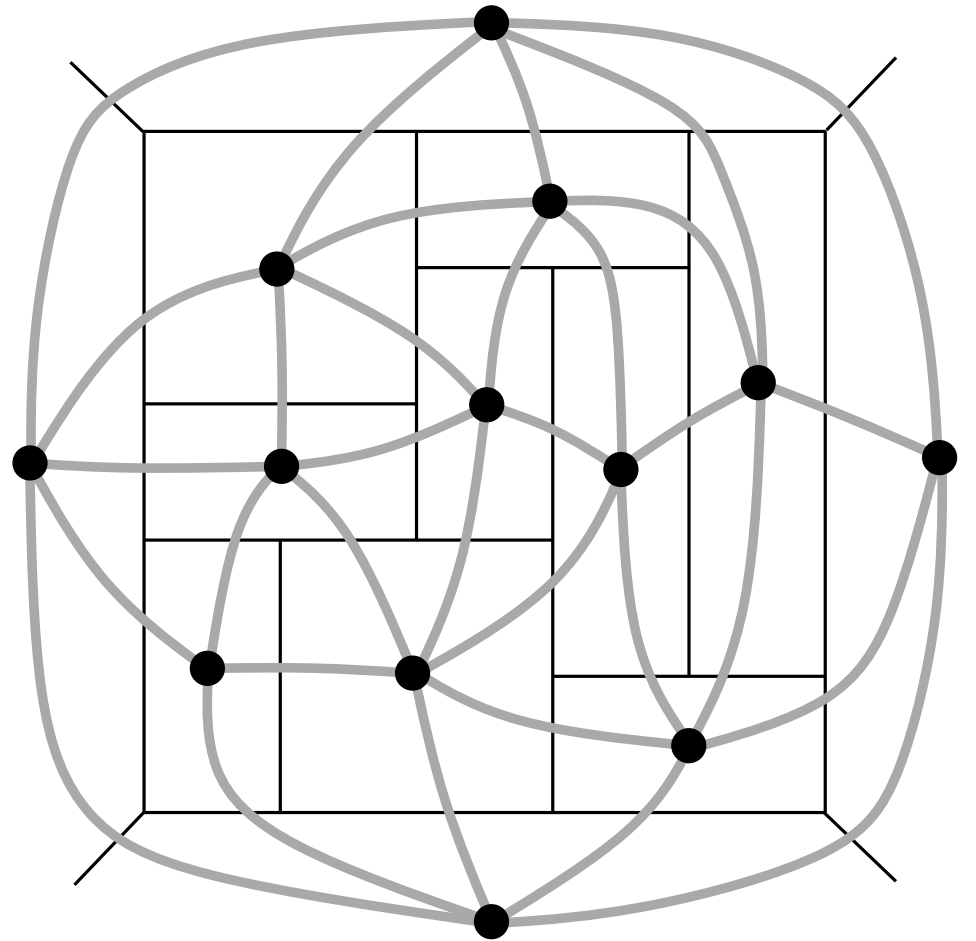
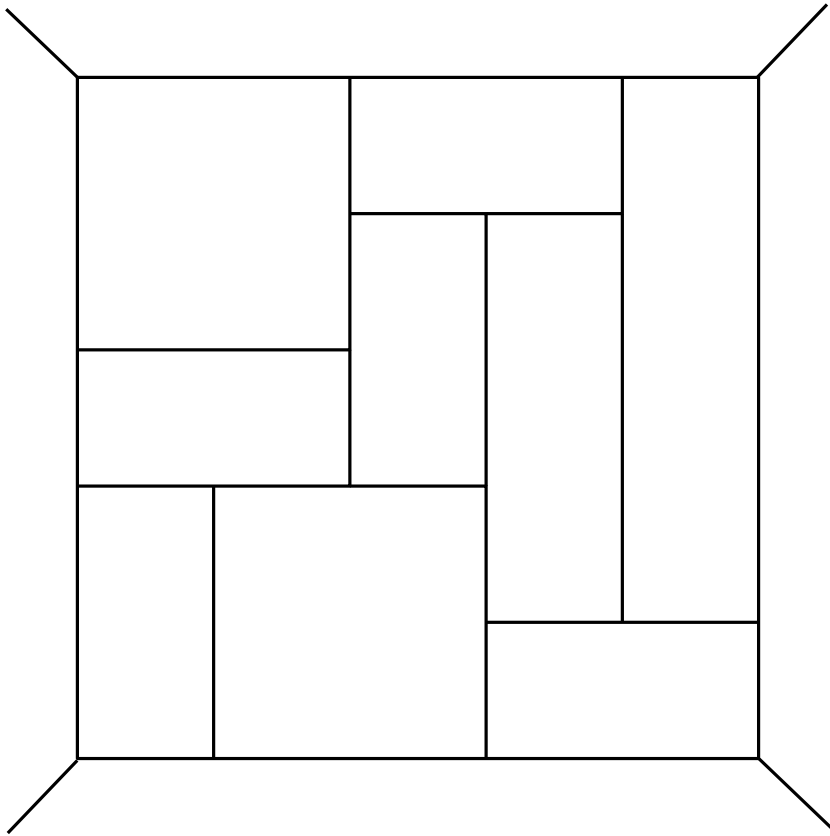
characterized by local conditions:



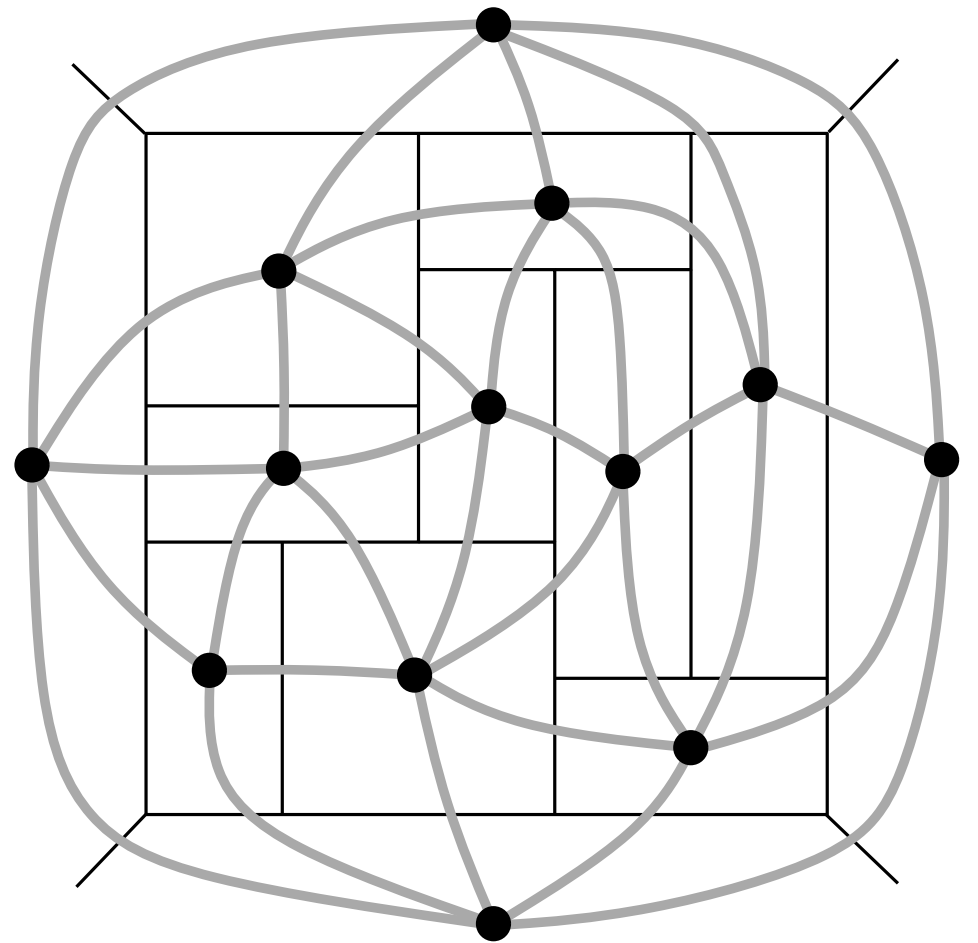
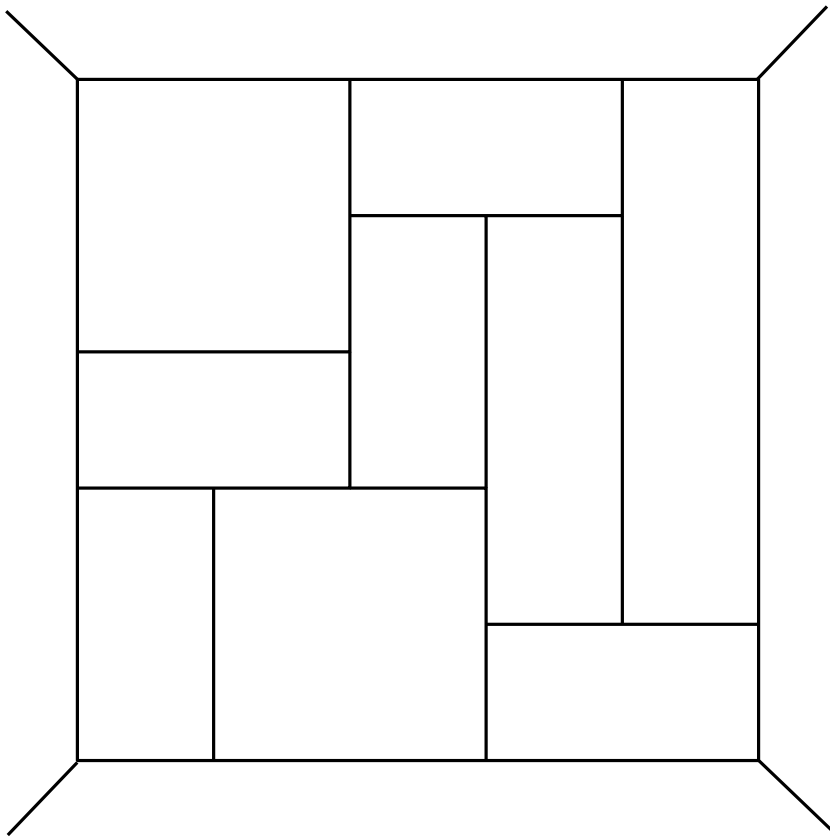
$T$  admits a transversal structure iff every 3-cycle is facial



# Rectangle tilings and dual triangulation



# Rectangle tilings and dual triangulation

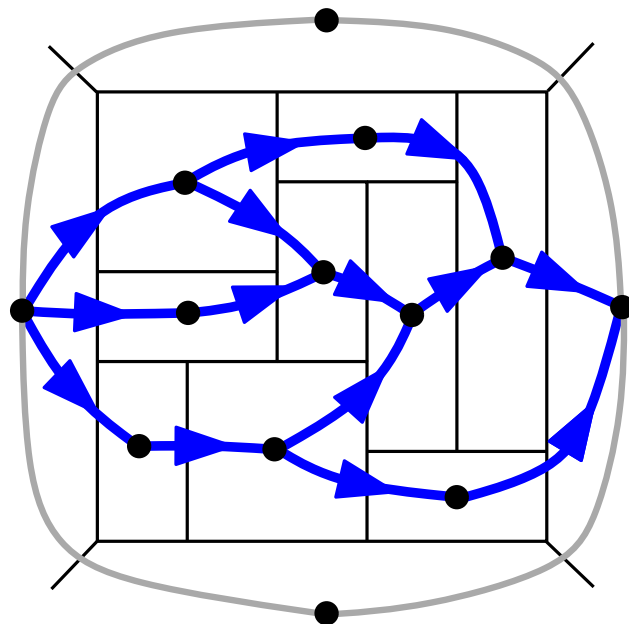


The dual map is a triangulation of the 4-gon, where every 3-cycle is facial

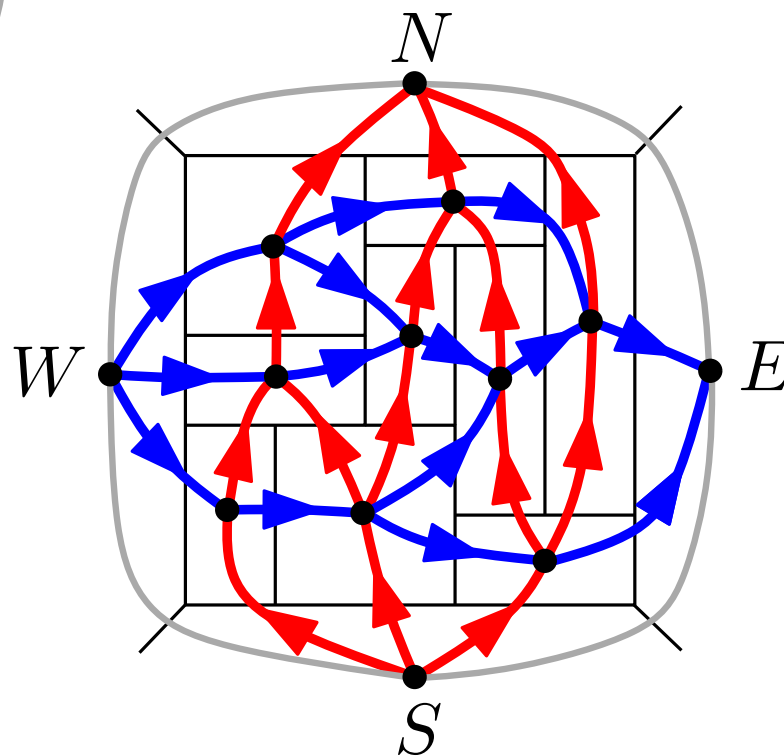
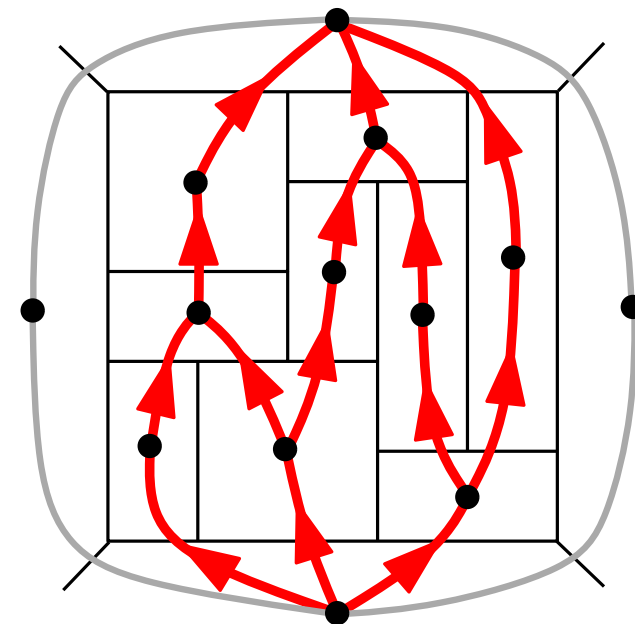
# Rectangle tilings and dual triangulation

The dual is naturally endowed with a transversal structure

dual for vertical edges



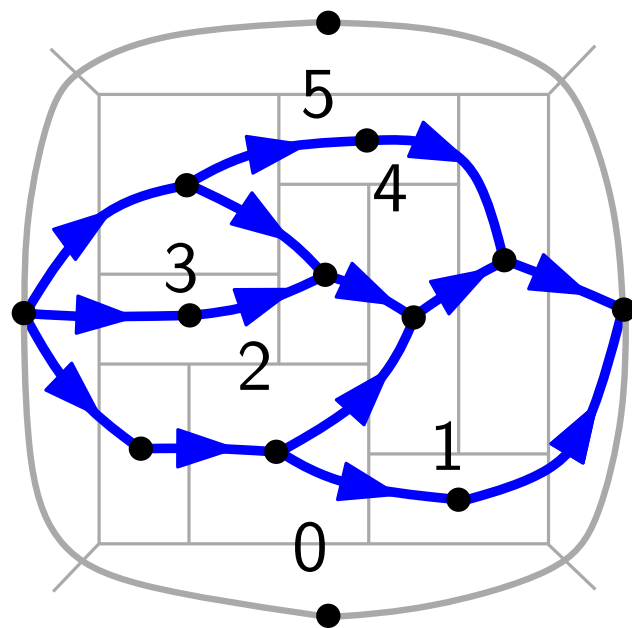
dual for horizontal edges



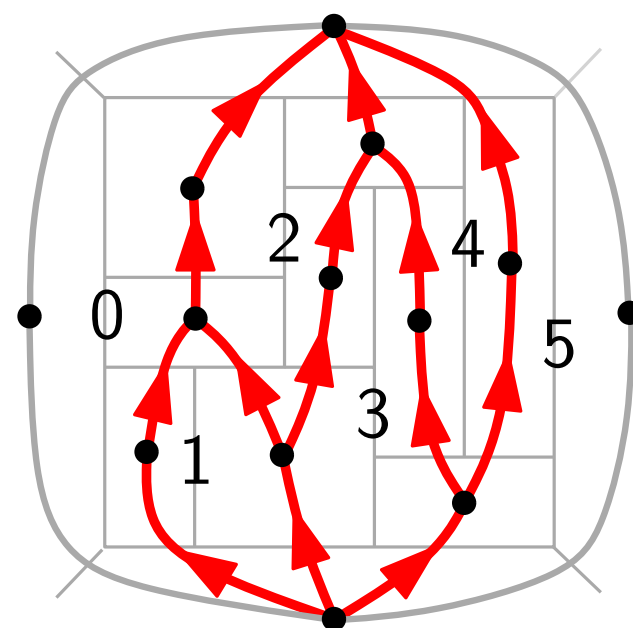


# Face-labelling of the two Hasse diagrams

dual for vertical edges

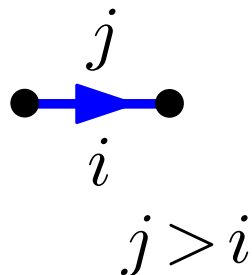


dual for horizontal edges



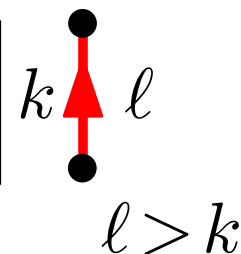
a horizontal segment in each face

label the face by the  $y$ -coordinate of segment



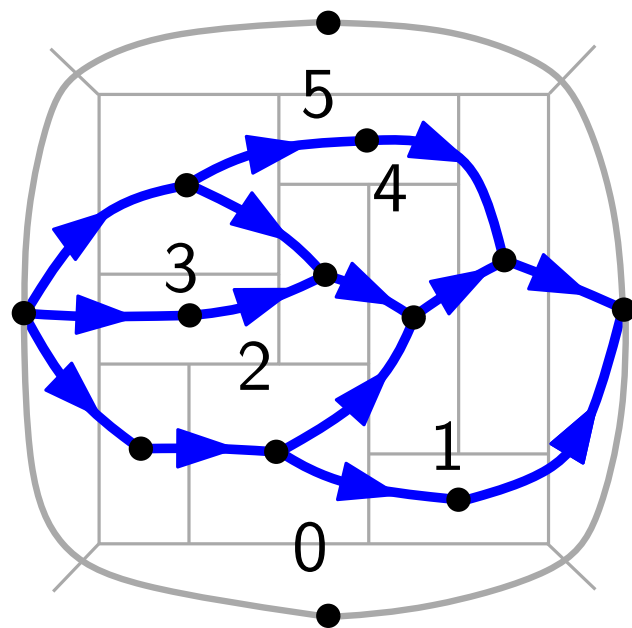
a vertical segment in each face

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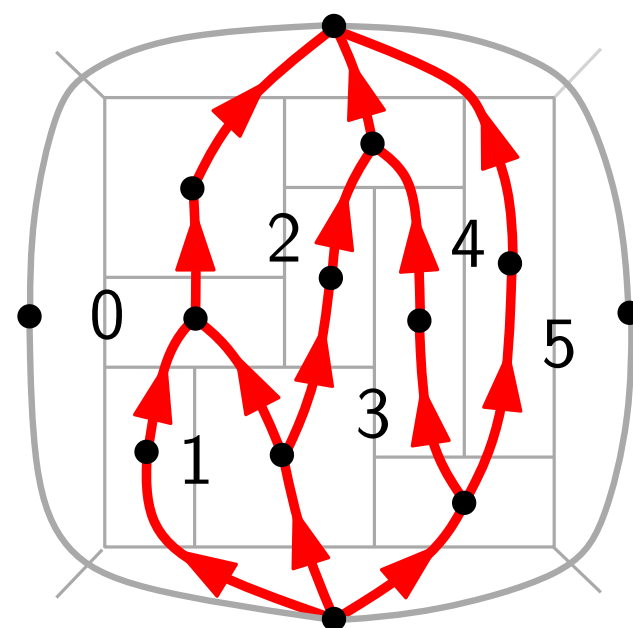


# Face-labelling of the two Hasse diagrams

dual for vertical edges

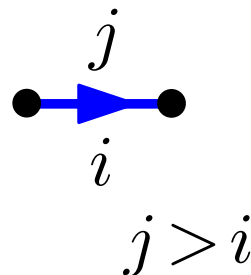


dual for horizontal edges



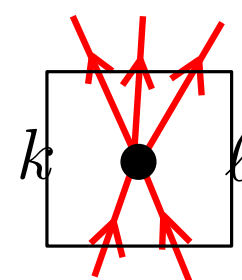
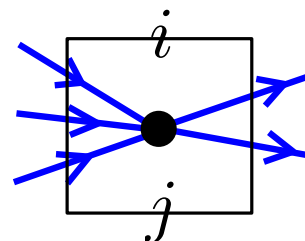
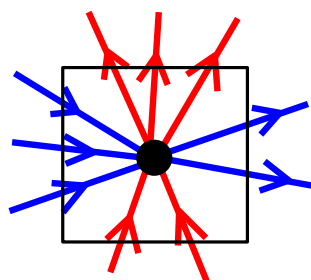
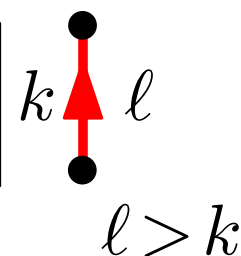
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label the face by the  $y$ -coordinate of segment



a vertical segment in each face

label the face by the  $x$ -coordinate of segment



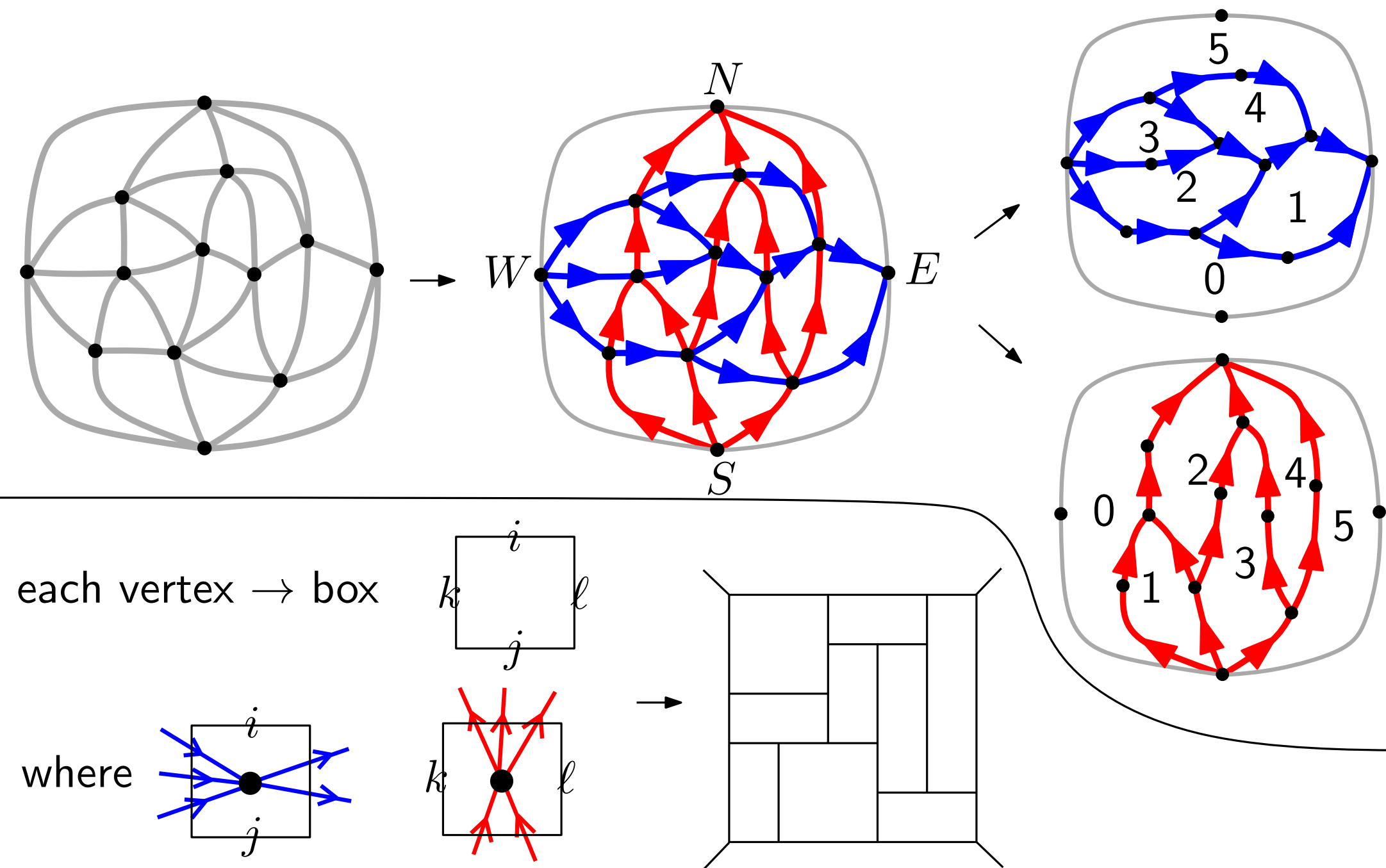
vertex  $v \leftrightarrow$  rectangle  $R(v)$

bounding  $x, y$ -coordinates given by labels

# Algorithm by reverse-engineering

[Kant, He'92]

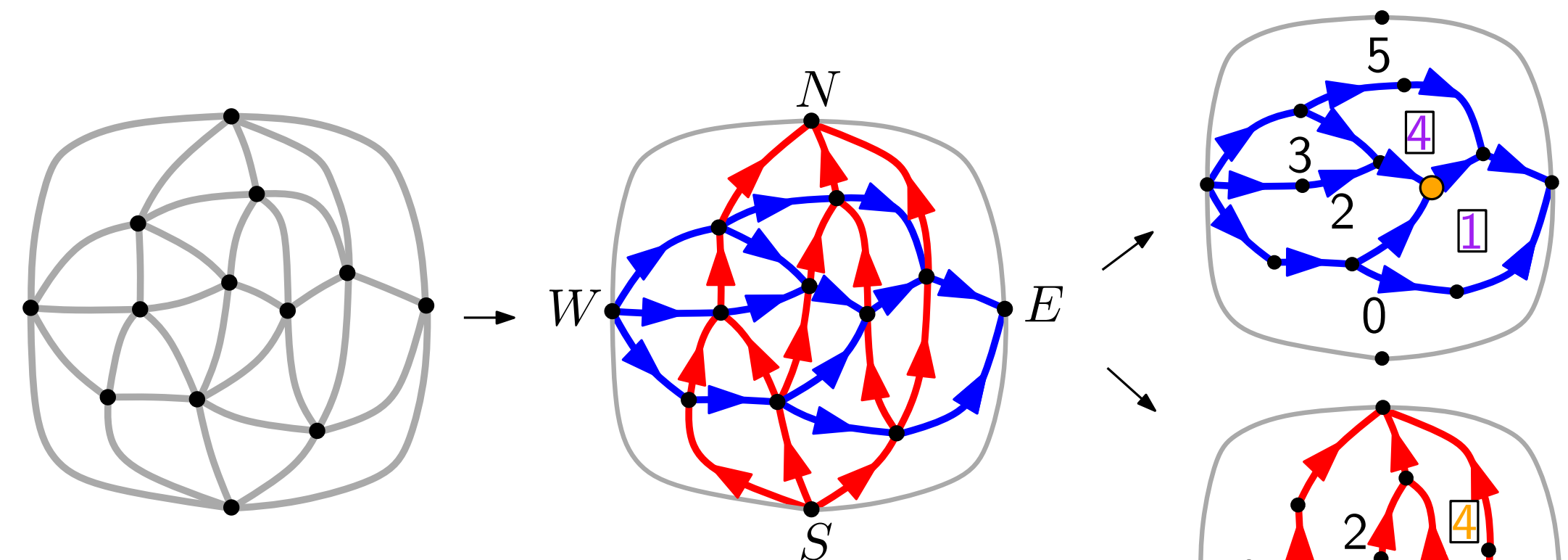
For  $T$  a triangulation of the 4-gon without separating 3-cycle



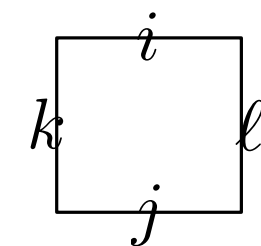
# Algorithm by reverse-engineering

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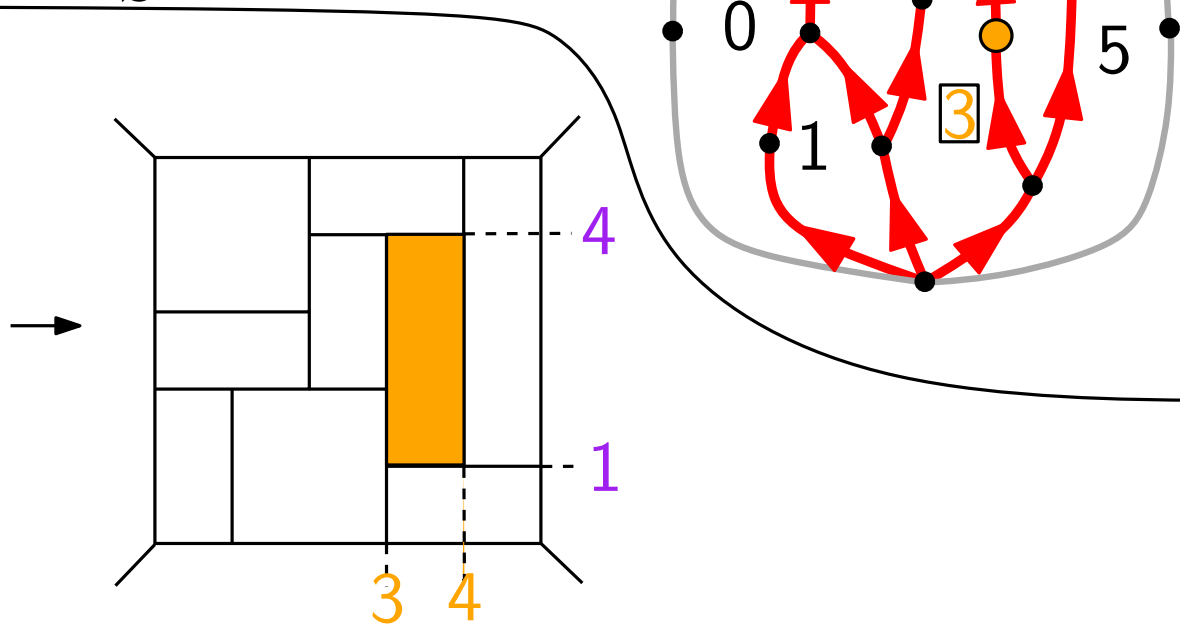
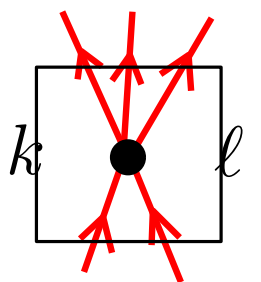
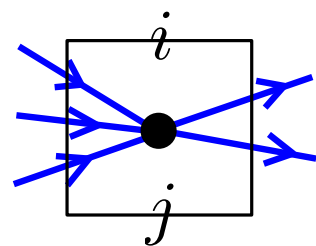
For  $T$  a triangulation of the 4-gon without separating 3-cycle



each vertex  $\rightarrow$  box



where

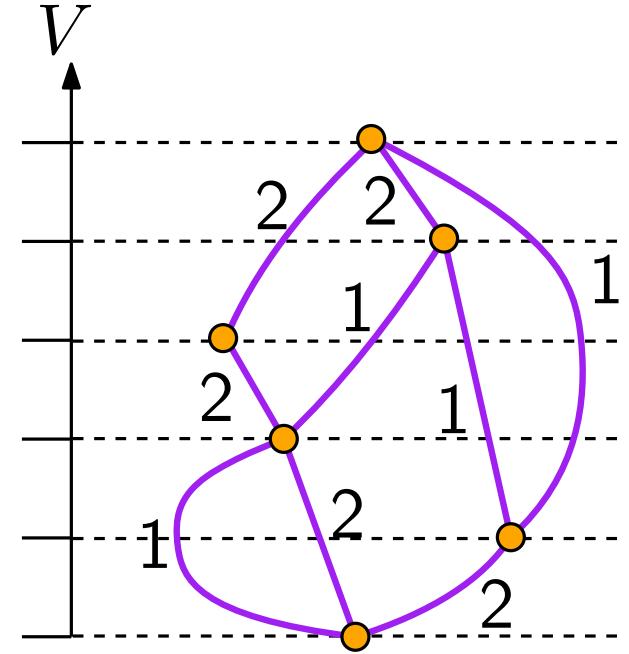
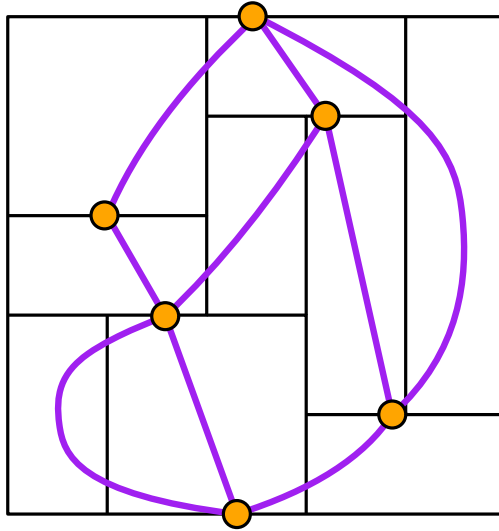
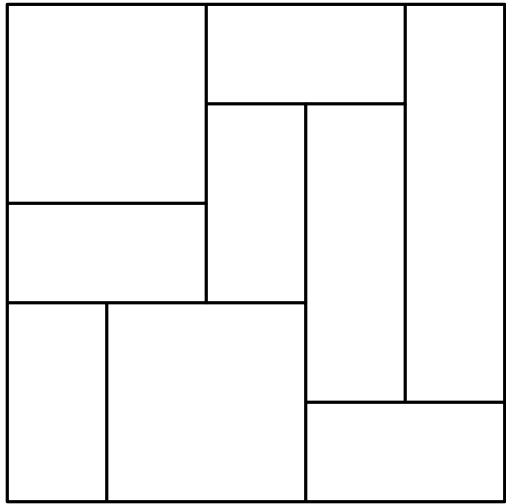




# Rectangle tilings and electrical networks

other way of associating a planar map to a rectangle tiling

nice way to visualize Kirchhoff's laws

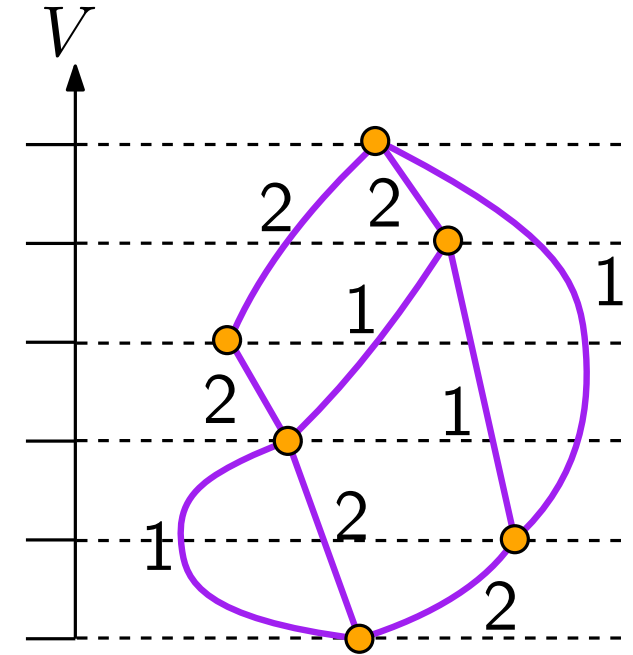
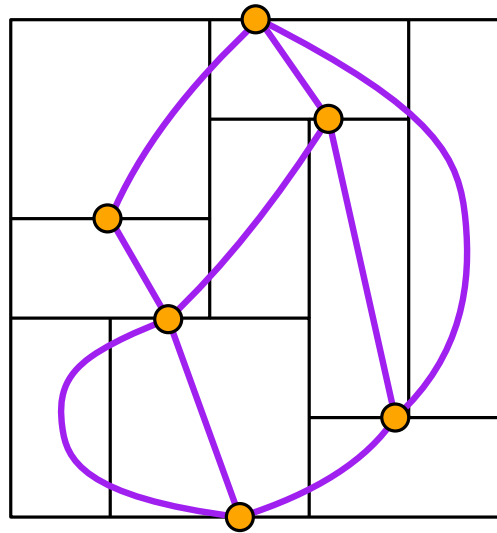
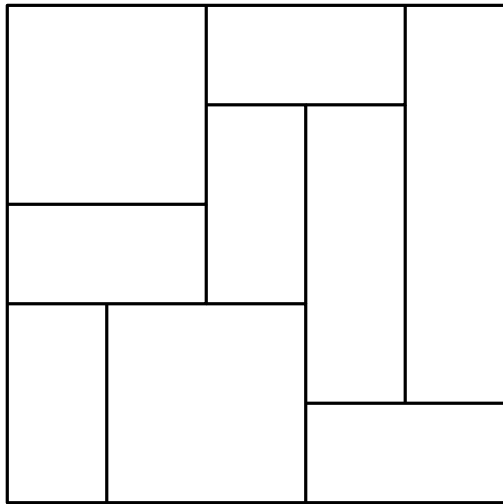


**Rk:** aspect ratio of a rectangle  $\leftrightarrow$  resistance of corresponding link in the network

# Rectangle tilings and electrical networks

other way of associating a planar map to a rectangle tiling

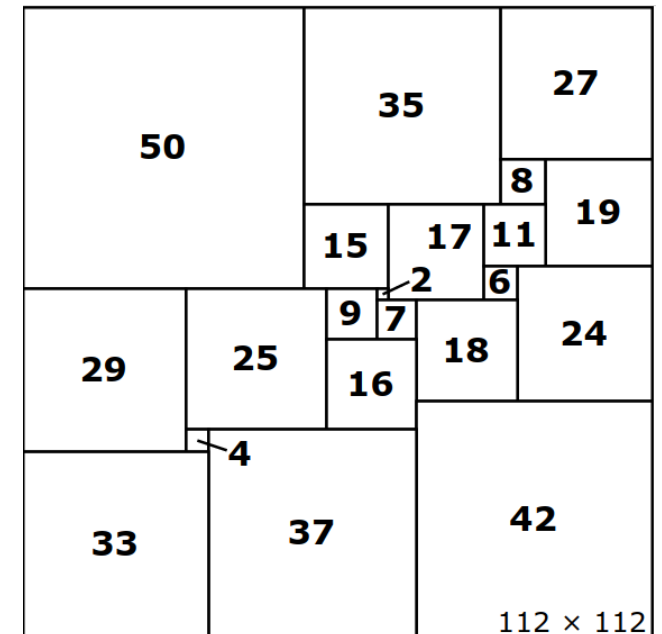
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**Rk:** aspect ratio of a rectangle  $\leftrightarrow$  resistance of corresponding link in the network

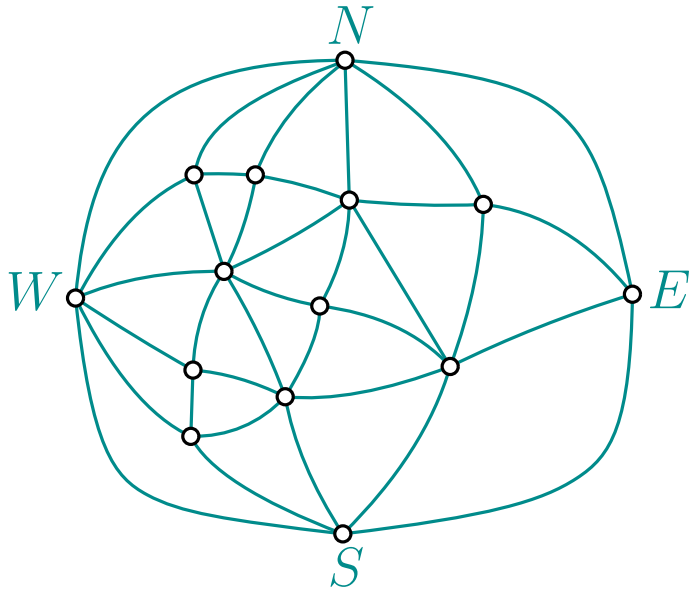
Given a network with resistances = 1  
one gets a square tiling representation  
by solving the Kirchhoff's laws

cf 'squaring the square'



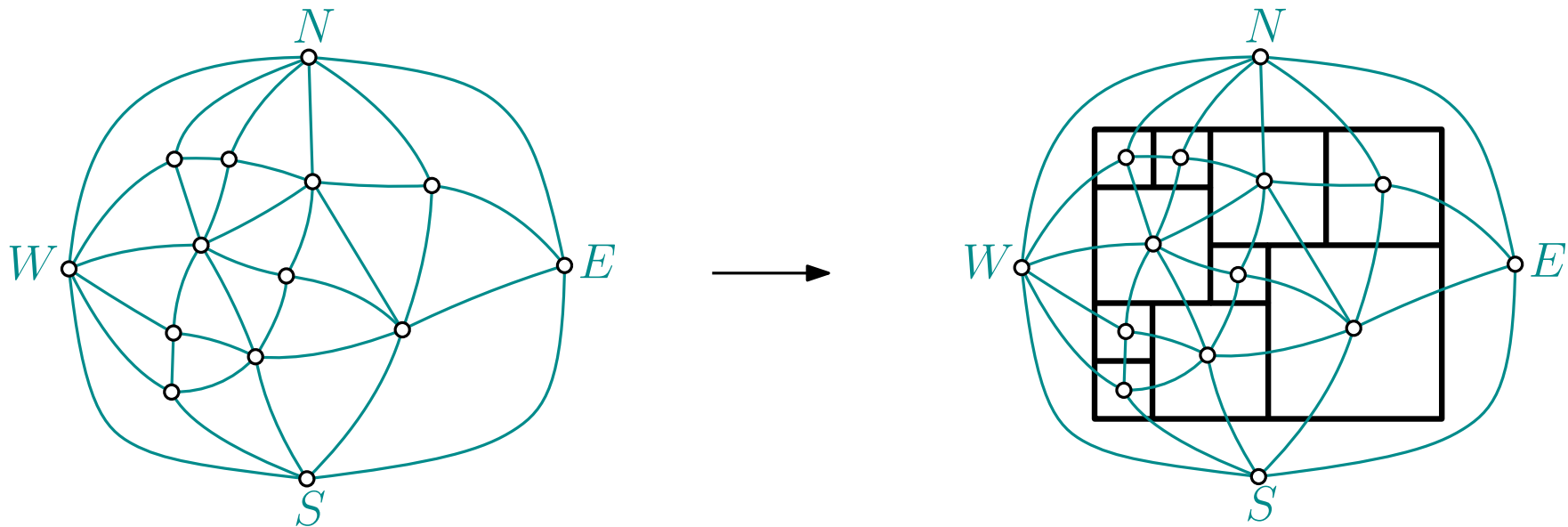
# Square tilings dual to triangulations [Schramm'93]

**Question:** Given  $T$  a triangulation of the 4-gon, does there always exist a square tiling whose dual is  $T$ ?



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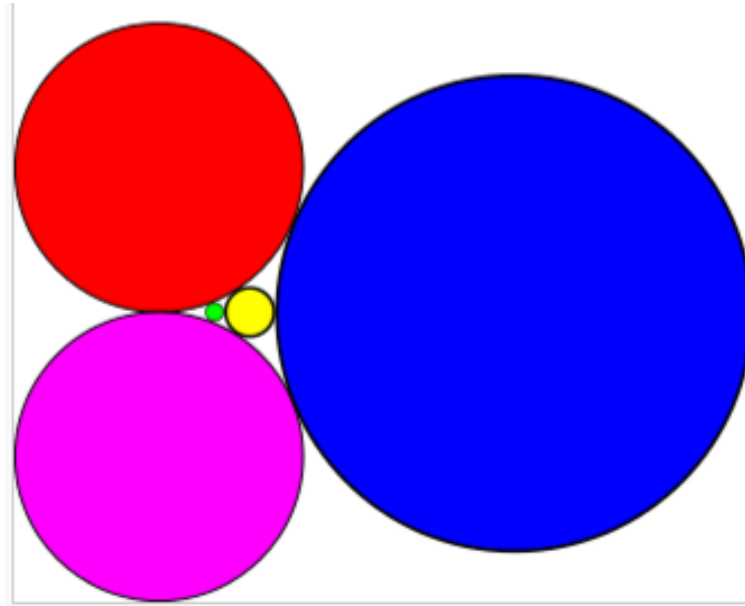
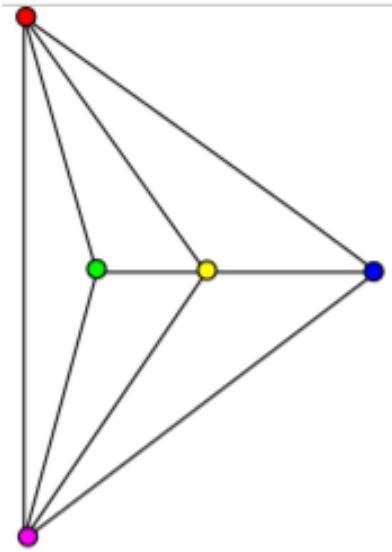


Yes ! up to allowing for degeneracies (empty squares)  
solution via computing the 'optimal metric' of  $T$   
(no known algorithm by solving linear equation systems)

# Circle packing

**[Koebe'36, Andreev'70, Thurston'85]:** every planar triangulation admits a contact representation by disks

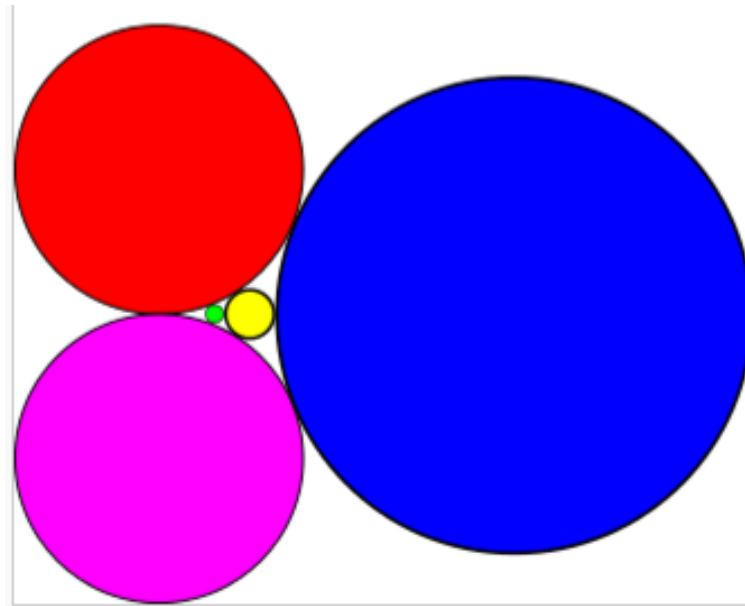
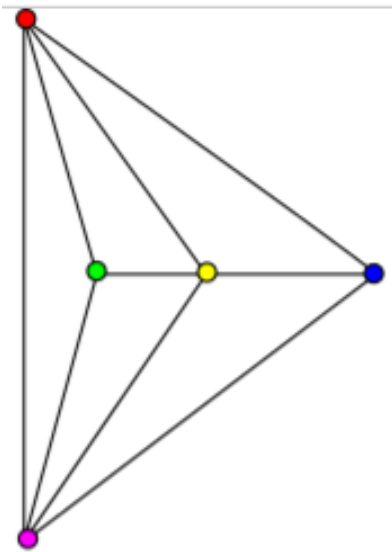
The representation is unique if the 3 outer disks have prescribed radius



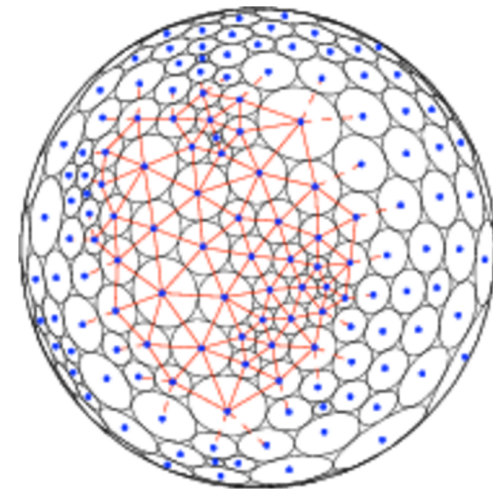
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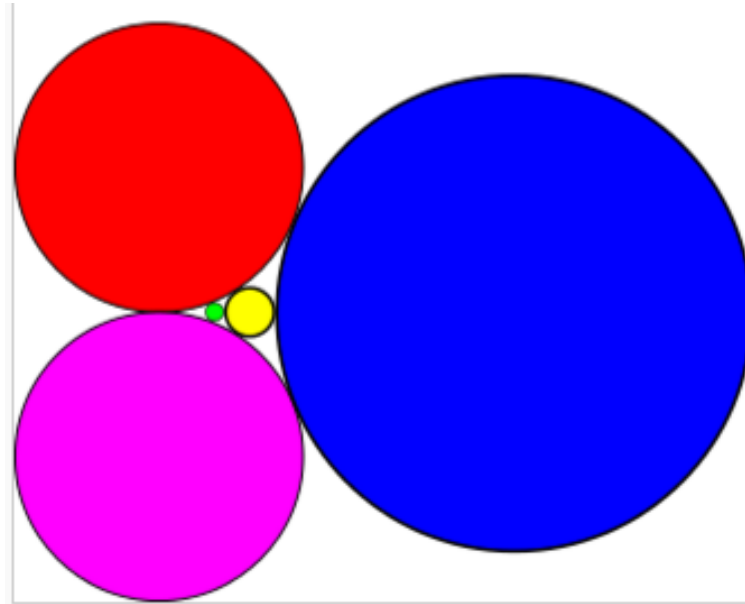
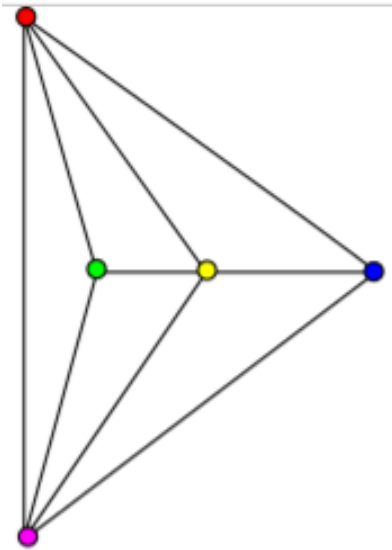
**Exercise:** the stereographic projection maps circles to circles (considering lines as circle of radius  $+\infty$ ).



# Circle packing

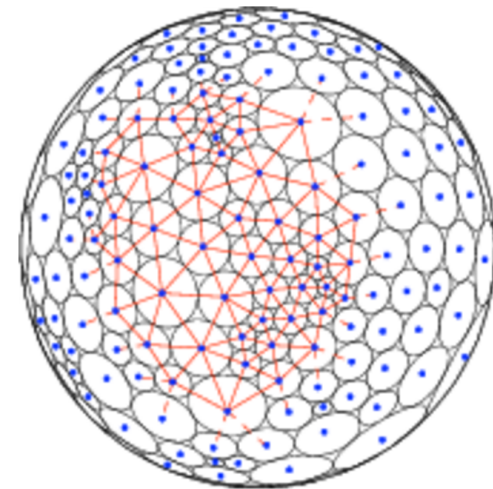
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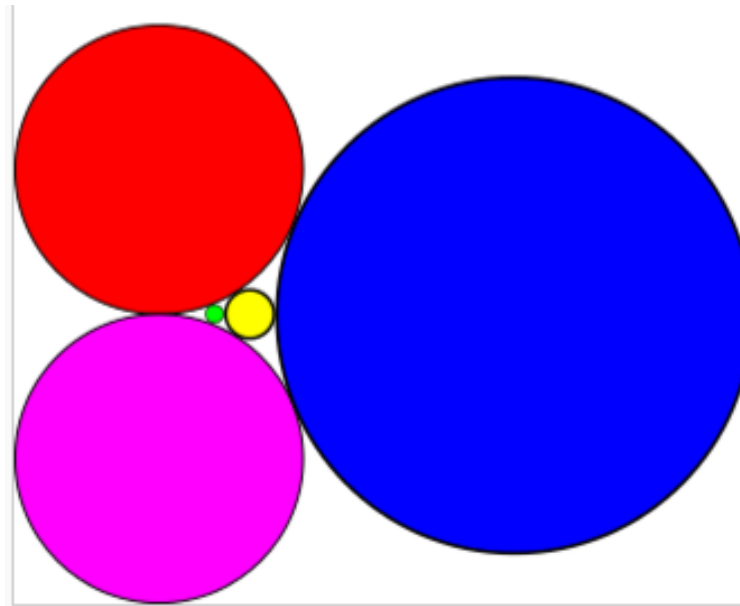
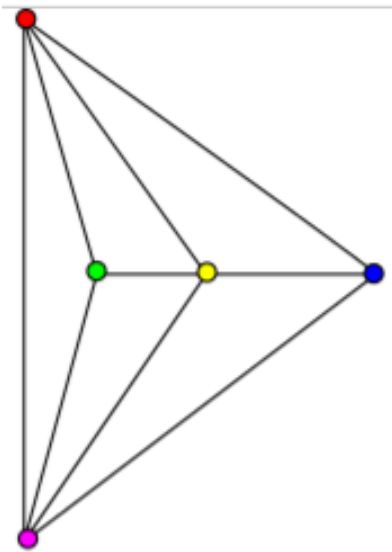
Hence one can lift to a circle packing on the sphere



# Circle packing

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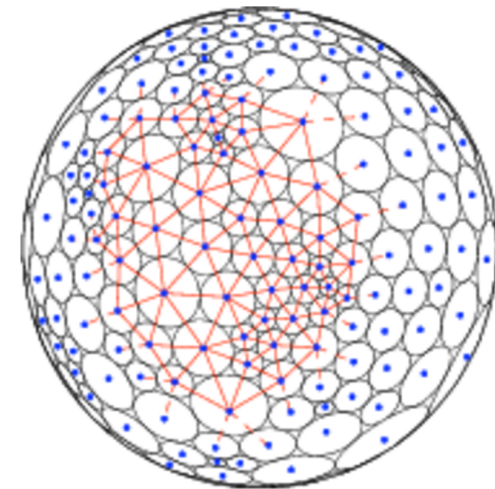
The representation is unique if the 3 outer disks have prescribed radius



**Exercise:** the stereographic projection maps circles to circles (considering lines as circle of radius  $+\infty$ ).

Hence one can lift to a circle packing on the sphere

There is a unique representation where the centre of the sphere is the barycenter of the contact points





# Contact representations with prescribed shapes

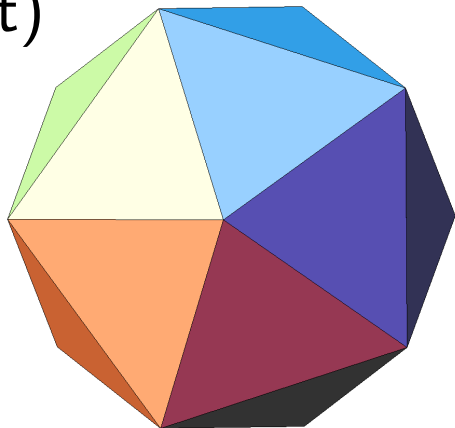
Generalized statement:

[Schramm's PHD 1990]

for any triangulation  $T$  and a prescribed convex shape for each vertex  
there exists a contact representation of  $T$

(possibility of degeneracies if shapes are not smooth)

**Example** (Eppstein's blog post)



isocahedron

