

PROOF-CARRYING-CODE

APPLYING FORMAL METHODS IN A DISTRIBUTED WORLD

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- 2 PROGRAM LOGICS
- 3 TCB SIZE
- 4 PCC IN ACTION: CCURED

MEETING THE CHALLENGES

The previous lecture explained the concepts behind PCC, its strengths and weaknesses:

- 😊 Unforgable certificates
- 😊 Separation of code safety and trust
- 😞 High overhead in terms of certificate size and/or trusted code base (TCB)

In this lecture we will look into the details of making the components work.

LF TERMS

The Logical Framework (LF) is a generic description of logics.
 Entities on three levels: objects, families of types, and kinds.

$$\begin{array}{l}
 \text{Kinds} \quad K ::= \text{Type} \mid \Pi x : A. K \\
 \text{Families} \quad A ::= a \mid \Pi x : A. B \mid \lambda x : A. B \mid A \ M \\
 \text{Objects} \quad M ::= c \mid x \mid \lambda x : A. M \mid M \ N
 \end{array}$$

Signatures: mappings of constants to types and kinds

Contexts: mappings of variables to types

$$\begin{array}{l}
 \text{Signatures} \quad \Sigma ::= \langle \rangle \mid \Sigma, a : K \mid \Sigma, c : A \\
 \text{Contexts} \quad \Gamma ::= \langle \rangle \mid \Gamma, x : A
 \end{array}$$

LF TYPE SYSTEM

Judgements:

$$\Gamma \vdash_{\Sigma} A : K$$

meaning A has kind K in context Γ and signature Σ .

$$\Gamma \vdash_{\Sigma} M : A$$

meaning M has type A in context Γ and signature Σ .

LF TYPE SYSTEM (OBJECTS)

$$\frac{\vdash_{\Sigma} \Gamma \quad c : A \in \Sigma}{\Gamma \vdash_{\Sigma} c : A} \quad (\text{CONST-OBJ})$$

$$\frac{\vdash_{\Sigma} \Gamma \quad x : A \in \Gamma}{\Gamma \vdash_{\Sigma} x : A} \quad (\text{VAR-OBJ})$$

$$\frac{\Gamma, x : A \vdash_{\Sigma} M : B}{\Gamma \vdash_{\Sigma} \lambda x : A. M : \Pi x : A. B} \quad (\text{ABS-OBJ})$$

$$\frac{\Gamma \vdash_{\Sigma} M : \Pi x : A. B \quad \Gamma \vdash_{\Sigma} N : A}{\Gamma \vdash_{\Sigma} M N : [N/x]B} \quad (\text{APP-OBJ})$$

$$\frac{\Gamma \vdash_{\Sigma} M : A \quad \Gamma \vdash_{\Sigma} A' : \text{type} \quad \Gamma \vdash_{\Sigma} A \equiv A'}{\Gamma \vdash_{\Sigma} M : A'} \quad (\text{CONV-OBJ})$$

ENCODING THE LOGIC INTO LF

3 LF-level types are used: `exp` for expressions, `pred` for predicates, and `tp` for types.

Encoding constants and terms:

```
+ : exp → exp → exp
true : pred
impl : pred → pred → pred
all : (pred → pred) → pred
...
```

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Note that `all` is higher order. We can use the application of LF-level types to encode substitution.

ENCODING THE LOGIC INTO LF

Encoding proofs: $\text{pf} : \text{pred} \rightarrow \text{Type}$

```
and_i :  $\prod p: \text{pred}. \prod r: \text{pred}.$   
         $\text{pf } p \rightarrow \text{pf } r \rightarrow \text{pf } (\text{and } p r)$   
all_i  :  $\prod p \text{exp} \rightarrow \text{pred}.$   
         $(\prod v : \text{exp}. \text{pf}(p v)) \rightarrow \text{pf } (\text{all } p)$ 
```

CERTIFICATE SIZE: EMPIRICAL DATA

One of the major problems with PCC is the size of the certificates.
Size of proof terms in Isabelle/HOL:

Example	Size of proof term (lines)	Size of proof term (constructors)	Size of proof script (lines)
AllImpl	6	31	8
AllExists	6	26	7
Arith	295	1250	2

AllImpl : $\forall AB. (A \wedge B \longrightarrow B \wedge A)$

AllExists : $(\forall P. (\exists x. \forall y. P \ x \ y) \longrightarrow (\forall y. \exists x. P \ x \ y))$

Arith : $\forall(m :: \text{nat}). m < m + 1$

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Example	Size of proof term (lines)	Size of proof term (constructors)	Size of proof script (lines)
const	6	16	3
cons with clarsimp	31	136	3
swap	34819	137671	15
count-down	8584	25334	17
list-reversal	44082	162813	114

```

const :  $\triangleright$  expr.Int 1 :  $\{(E, h, h', v, p). h' = h \wedge v = \text{IVal } 1 \wedge p = \langle\langle \text{Suc } 0 \rangle\rangle 0 0 0\}$ 
swap :  $\triangleright$  CALL swap : spectable swap
count :  $\triangleright$  MH_InvokeStatic KountClass kount : Mspectable KountClass kount
rev :  $\triangleright$  CALL rev : spectable rev

```

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```

Define an evaluation function that interprets an assertion

$eval : state \Rightarrow assn \Rightarrow value$

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type assn = state \Rightarrow *value*

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- **Shallow Embedding:** define assertions as functions over the state

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Deep embeddings are usually easier to deal with.

Meta-properties over assertions may be harder to prove, though.

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- Hoare-style logics: $\{P\}e\{Q\}$

Assertions are parameterised over the “current” state.

Example: Specification of an exponential function

$$\{0 \leq y \wedge x = X \wedge y = Y\} \text{exp}(x, y) \{r = X^Y\}$$

Note: X, Y are **auxiliary variables** and must not appear in e

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- VDM-style logics: $e : P$

Assertions are parameterised over pre- and post-state.

Because we have both pre- and post-state in the post-condition we do not need a separate pre-condition.

Example: Specification of an exponential function

$$\{0 \leq y\} \text{exp}(x, y) \{r = \dot{x}^{\dot{y}}\}$$

A SIMPLE WHILE-LANGUAGE

Language:

```
e ::= skip
   | x := t
   | e1;e2
   | if b then e1 else e2
   | while b do e
   | call
```

A SIMPLE WHILE-LANGUAGE

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 | \text{if } b \text{ then } e_1 \text{ else } e_2 \\
 | \text{while } b \text{ do } e \\
 | \text{call}
 \end{array}$$

A judgement has this form (for now!)

$$\vdash \{P\} e \{Q\}$$

A judgement is valid if the following holds

$$\forall z s t. s \xrightarrow{e} t \Rightarrow P z s \Rightarrow Q z t$$

A SIMPLE HOARE-STYLE LOGIC

$$\frac{}{\vdash \{P\} \text{ skip } \{P\}} \quad (\text{SKIP}) \quad \frac{}{\vdash \{\lambda z s. P z s[t/x]\} x := t \{P\}} \quad (\text{ASSIGN})$$

$$\frac{\vdash \{P\} e_1 \{R\} \quad \{R\} e_2 \{Q\}}{\vdash \{P\} e_1; e_2 \{Q\}} \quad (\text{COMP})$$

$$\frac{\vdash \{\lambda z s. P z s \wedge b s\} e_1 \{Q\} \quad \vdash \{\lambda z s. P z s \wedge \neg(b s)\} e_2 \{Q\}}{\vdash \{P\} \text{ if } b \text{ then } e_1 \text{ else } e_2 \{Q\}} \quad (\text{IF})$$

$$\frac{\vdash \{\lambda z s. P z s \wedge b s\} e \{P\}}{\vdash \{P\} \text{ while } b \text{ do } e \{\lambda z s. P z s \wedge \neg(b s)\}} \quad (\text{WHILE})$$

$$\frac{\vdash \{P\} \text{ body } \{Q\}}{\vdash \{P\} \text{ CALL } \{Q\}} \quad (\text{CALL})$$

A SIMPLE HOARE-STYLE LOGIC (STRUCTURAL RULES)

The consequence rule allows us to weaken the pre-condition and to strengthen the post-condition:

$$\frac{\forall s t. (\forall z. P' z s \Rightarrow P z s) \quad \vdash \{P'\} e \{Q'\} \quad \forall s t. (\forall z. Q z s \Rightarrow Q' z s)}{\vdash \{P\} e \{Q\}} \quad (\text{CONSEQ})$$

RECURSIVE FUNCTIONS

In order to deal with recursive functions, we need to collect the knowledge about the behaviour of the functions.

We extend the judgement with a context Γ , mapping expressions to Hoare-Triples:

$$\Gamma \vdash \{P\} e \{Q\}$$

where Γ has the form $\{\dots, (P', e', Q'), \dots\}$.

RECURSIVE FUNCTIONS

Now, the call rule for recursive, parameter-less functions looks like this:

$$\frac{\Gamma \cup \{(P, \text{CALL}, Q)\} \vdash \{P\} \text{ body } \{Q\}}{\Gamma \vdash \{P\} \text{ CALL } \{Q\}} \quad (\text{CALL})$$

We collect the knowledge about the (one) function in the context, and prove the body.

Note: This is a rule for partial correctness: for total correctness we need some form of measure.

RECURSIVE FUNCTIONS

To extract information out of the context we need and axiom rule

$$\frac{(P, e, Q) \in \Gamma}{\Gamma \vdash \{P\} e \{Q\}} \quad (\text{AX})$$

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Note that we now use a **Gentzen-style** logic (one with contexts) rather than a Hilbert-style logic.

MORE TROUBLES WITH RECURSIVE FUNCTIONS

Assume we have this simple recursive program:

```
if i=0 then skip else i := i-1 ; call ; i := i+1
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But how can we prove $\{i = N - 1\} \text{CALL} \{i = N - 1\}$ from $\{i = N\} \text{CALL} \{i = N\}$?

MORE TROUBLES WITH RECURSIVE FUNCTIONS

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But how can we prove $\{i = N - 1\} \text{ CALL } \{i = N - 1\}$ from $\{i = N\} \text{ CALL } \{i = N\}$?

We need to **instantiate** N with $N - 1$!

RECURSIVE FUNCTIONS

To be able to instantiate auxiliary variables we need a more powerful consequence rule:

$$\frac{\Gamma \vdash \{P'\} e \{Q'\} \quad \forall s t. (\forall z. P' z s \Rightarrow Q' z t) \Rightarrow (\forall z. P z s \Rightarrow Q z t)}{\Gamma \vdash \{P\} e \{Q\}} \quad (\text{CONSEQ})$$

Now we are allowed to proof $P \Rightarrow Q$ under the knowledge that we can choose z freely as long as $P' \Rightarrow Q'$ is true.

This complex rule for **adaptation** is one of the main disadvantages of Hoare-style logics.

EXTENDING THE LOGIC WITH TERMINATION

The Call and While rules need to use a well-founded ordering $<$ and a side condition saying that the body is smaller w.r.t. this ordering:

$$\frac{\begin{array}{c} wf < \\ \forall s'. \{(\lambda z s.P \ z \ s \wedge \ s < s', \text{CALL}, Q)\} \\ \vdash_T \{\lambda z s.P \ z \ s \wedge \ s = s'\} \text{body} \{Q\} \end{array}}{\vdash_T \{P\} \text{CALL}\{Q\}}$$

Note the explicit quantification over the state s' . Read it like this

The pre-state s must be smaller than a state s' , which is the post-state.

EXTENDING THE LOGIC WITH MUTUAL RECURSION

To cover mutual recursion a different derivation system \vdash_M is defined.

Judgements in \vdash_M are extended to sets of Hoare triples, informally:

$$\Gamma \vdash_M \{(P_1, e_1, Q_1), \dots, (P_n, e_n, Q_n)\}$$

The Call rule is generalised as follows

$$\frac{\bigcup p. \{(P \ p, \text{CALL } p, Q \ p)\} \vdash_M \bigcup p. \{(P \ p, \text{body } p, Q \ p)\}}{\emptyset \vdash_M \bigcup p. \{(P \ p, \text{CALL } p, Q \ p)\}}$$

FURTHER READING



Thomas Kleymann, *Hoare Logic and VDM: Machine-Checked Soundness and Completeness Proofs*, Lab. for Foundations of Computer Science, Univ of Edinburgh, LFCS report ECS-LFCS-98-392, 1999.

<http://www.lfcs.informatics.ed.ac.uk/reports/98/ECS-LFCS-98-392>



Tobias Nipkow, *Hoare Logics for Recursive Procedures and Unbounded Nondeterminism*, in CSL 2002 — Computer Science Logic, LNCS 2471, pp. 103–119, Springer, 2002.

CHALLENGE: MINIMISING THE TCB

This aspect is the emphasis of the **Foundational PCC** approach.

An infrastructure developed by the group of Andrew Appel at Princeton [1].

Motivation: With complex logics and VCGs, there is a big danger of introducing bugs in software that needs to be trusted.

THE PHILOSOPHY OF FOUNDATIONAL PCC

Define safety policy directly on the **operational semantics** of the code.

Certificates are proofs over the operational semantics.

It minimises the TCB because no trusted verification condition generator is needed.

Pros and cons:

- 😊 **more flexible**: not restricted to a particular type system as the language in which the proofs are phrased;
- 😊 **more secure**: no reliance on VCG.
- 😞 **larger proofs**

CONVENTIONAL VS FOUNDATIONAL PCC

Re-examine the logic for memory safety, eg.

$$\frac{m \vdash e : \tau \text{ list} \quad e \neq 0}{m \vdash e : \text{addr} \wedge m \vdash e + 4 : \text{addr} \wedge m \vdash \text{sel}(m, e) : \tau \wedge m \vdash \text{sel}(m, e + 4) : \tau \text{ list}} \quad (\text{LISTELIM})$$

The rule has **built-in knowledge about the type-system**, in this case representing the data layout of the compiler (“*Type specialised PCC*”) \implies dangerous if soundness of the logic is not checked mechanically!

LOGIC RULES IN FOUNDATIONAL PCC

In foundational PCC the rules work on the operational semantics:

$$\frac{m \models e : \tau \text{ list} \quad e \neq 0}{m \models e : \text{addr} \wedge m \models e + 4 : \text{addr} \wedge m \models \text{sel}(m, e) : \tau \wedge m \models \text{sel}(m, e + 4) : \tau \text{ list}} \quad (\text{LISTELIM})$$

This looks similar to the previous rule but has a very different meaning: \models is a predicate over the formal model of the computation, and the above rule can be proven as a lemma, \vdash is an encoding of a type-system on top of the operational semantics and thus needs a **soundness proof**.

COMPONENTS OF A FOUNDATIONAL PCC INFRASTRUCTURE

Operational semantics and safety properties are directly encoded in a **higher-order logic**.

As language for the certificates, the LF metalogic framework is used.

For development and for proof-checking the Twelf theorem proofer is used.

SPECIFYING SAFETY

To specify safety, the operational semantics is written in such a way, that it gets stuck whenever the safety condition is violated.

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Example: operational semantics on assembler code.

Safety policy: “only readable addresses are loaded”.

Define a predicate: $readable(x) \equiv 0 \leq x \leq 1000$

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The semantics of a load operation $LD\ r_i, c(r_j)$ is now written as follows:

$$\begin{aligned}
 load(i, j, c) &\equiv \lambda r\ m\ r'\ m'. \\
 &\quad r'(i) = m(r(j) + c) \wedge readable(r(j) + c) \wedge \\
 &\quad (\forall x \neq i. r'(x) = r(x)) \wedge m' = m
 \end{aligned}$$

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 \end{aligned}$$

Note: the clause for nothing else changes, quickly becomes awkward when doing these proofs

\implies Separation Logic (Reynolds'02) tackles this problem.

MAIN ISSUES IN FPCC

The main task in this framework becomes the **semantic modelling of types**: indexed semantic model to describe contravariant types, eg. $e = \text{APP of } e \ e \mid \text{LAM of } e \rightarrow e$


Naive model: type = set of values

Indexed model: type = set of $\langle k, v \rangle$, where k is an approximation index, v is a value

$\langle k, v \rangle \in \tau$ means v has approximate type τ and programs running less than k steps can't tell a difference

\implies induction principle over steps of execution

FURTHER READING

-  Andrew Appel, *Foundational Proof-Carrying Code* in LICS'01 — Symposium on Logic in Computer Science, 2001.
<http://www.cs.princeton.edu/~appel/papers/fpcc.pdf>

CCURED

A system for checking **pointer-safety** of C programs, developed by the group of George Necula at Berkeley.

Uses a hybrid mechanism of static type checking and run-time checks.

Goal: Prove pointer safety statically, where possible, and minimise required run-time checks.

THE CCURED TYPE SYSTEM

Extension of the standard C type system with extension for **pointers into arrays and dynamic types**.

Efficient type inference is possible and demonstrated for this type system.

THE CORE LANGUAGE

Mini-C language:

$$\begin{aligned} e &::= x \mid n \mid e_1 \text{ op } e_2 \mid (\tau)e \mid e_1 \oplus e_2 \mid !e \\ c &::= \text{skip} \mid c_1; c_2 \mid e_1 := e_2 \end{aligned}$$

THE CCURED TYPE SYSTEM: POINTERS

C contains 2 evil pointer operations: arithmetic and casts.

The type system distinguishes between 3 kinds of pointers:

- **Safe pointers**: no arithmetic or casts; represented as an address
- **Sequence pointers**: arithmetic but **no casts**; represented as a region
- **Dynamic pointers**: **casts**, all bets are off! represented as a region

EXAMPLE PROGRAM

Sum over an array of boxed integers:

```
int **a; /* array */      int i;      // index
int acc; /* accumulator */ int **p;     // elem ptr
int *e;  /* unboxer */
acc = 0;
for (i=0; i<100; i++) {
    p = a + i;             // ptr arithm
    e = *p;               // read elem
    while ((int)e % 2 == 0) { // check tag
        e = *(int **)e;   // unbox
    }
    acc += ((int)e >> 1); // strip tag
}
```

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a and p point into an array with elems of type int *

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a is subject to pointer arithm (“sequence pointer”)

⇒ check for out of bounds

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```

p has no arithmetic (“safe pointer”)

\implies no bounds check needed

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```

e is subject to a type cast (“dynamic pointer”)

\implies nothing known about underlying type

SAFE POINTERS

Invariant for SAFE pointers:

*A **SAFE** pointer to type T is either 0 or else it points to a valid area of memory containing an object of type T . Furthermore, all other pointers to the same area are also SAFE and agree on the type T of the stored object.*

Run-time check: null-pointer reference.

SEQUENCE POINTERS

Invariants for Sequence pointers:

- Cannot be cast (passing actual arguments and returning are implicit casts).
- Can be subject to pointer arithmetic (adding or subtracting an integer from it).
- Can be set to any integer value.
- Can be cast to an integer and can be subtracted from another pointer (useful for comparisons).
- Sequence pointers are represented using three words.

Run-time checks: null-pointer check and bounds check.

OPERATIONAL SEMANTICS

The value of an integer, or a safe pointer is an integer n ; the value of a sequence or dynamic pointer is a **home**, modelled as a pair $\mathbb{N} \times \mathbb{N}$ of start address and offset.

$$v ::= n \mid \langle h, n \rangle$$

OPERATIONAL SEMANTICS

The value of an integer, or a safe pointer is an integer n ; the value of a sequence or dynamic pointer is a **home**, modelled as a pair $\mathbb{N} \times \mathbb{N}$ of start address and offset.

$$v ::= n \mid \langle h, n \rangle$$

Each home is tagged as being an integer or a pointer, and has an associated **kind** and **size** functions. The semantic domain for pointers:

$$\begin{aligned} \llbracket \text{int} \rrbracket_H &= \mathbb{N} \\ \llbracket \text{DYNAMIC} \rrbracket_H &= \{ \langle h, n \rangle \mid h \in H \wedge (h = 0 \vee \text{kind}(h) = \text{untyped}) \} \\ \llbracket \tau \text{ ref SEQ} \rrbracket_H &= \{ \langle h, n \rangle \mid h \in H \wedge (h = 0 \vee \text{kind}(h) = \text{typed}(\tau)) \} \\ \llbracket \tau \text{ ref SAFE} \rrbracket_H &= \{ h + i \mid h \in H \wedge 0 \leq i \leq \text{size}(h) \wedge \\ &\quad (h = 0 \vee \text{kind}(h) = \text{typed}(\tau)) \} \end{aligned}$$

OPERATIONAL SEMANTICS (POINTERS)

$$\frac{\Sigma, M \vdash e_1 \Downarrow \langle h, n_1 \rangle \quad \Sigma, M \vdash e_2 \Downarrow n_2}{\Sigma, M \vdash e_1 \oplus e_2 \Downarrow \langle h_1, n_1 + n_2 \rangle} \quad (\text{POINTER ARITHM})$$

$$\frac{\Sigma, M \vdash e \Downarrow \langle h, n \rangle}{\Sigma, M \vdash (\text{int})e \Downarrow h + n} \quad (\text{CASTTOINT})$$

$$\frac{\Sigma, M \vdash e \Downarrow n}{\Sigma, M \vdash (\tau \text{ ref SEQ})e \Downarrow \langle 0, n \rangle} \quad (\text{CASTTOSEQ})$$

$$\frac{\Sigma, M \vdash e \Downarrow \langle h, n \rangle \quad \mathbf{0} \leq \mathbf{n} \leq \mathbf{size(h)}}{\Sigma, M \vdash (\tau \text{ ref SAFE})e \Downarrow h + n} \quad (\text{CASTTOSAFE})$$

OPERATIONAL SEMANTICS (READ OPERATIONS)

Two kinds of reads, with different obligations for run-time checks:

$$\frac{\Sigma, M \vdash e \Downarrow n \quad \mathbf{n} \neq \mathbf{0}}{\Sigma, M \vdash !e \Downarrow M(n)} \quad (\text{SAFERD})$$

$$\frac{\Sigma, M \vdash e \Downarrow \langle h, n \rangle \quad \mathbf{h} \neq \mathbf{0} \quad 0 \leq n \leq \text{size}(h)}{\Sigma, M \vdash !e \Downarrow M(h + n)} \quad (\text{DYNRD})$$

$$\frac{\Sigma, M \vdash e_1 \Downarrow n \quad \mathbf{n} \neq \mathbf{0} \quad \Sigma, M \vdash e_2 \Downarrow v}{\Sigma, M \vdash e_1 := e_2 \Downarrow M(n \mapsto v)} \quad (\text{SAFEWR})$$

$$\frac{\Sigma, M \vdash e_1 \Downarrow \langle h, n \rangle \quad \mathbf{h} \neq \mathbf{0} \quad 0 \leq n \leq \text{size}(h) \quad \Sigma, M \vdash e_2 \Downarrow v}{\Sigma, M \vdash e_1 := e_2 \Downarrow M(h + n \mapsto v)} \quad (\text{DYNWR})$$

THE CCURED TYPE SYSTEM: RULES

The type system keeps track of the kind of pointers.
Rules for converting pointers:

$$\frac{}{\tau \leq \tau}$$

$$\frac{}{\tau \leq \text{int}}$$

$$\frac{}{\text{int} \leq \tau \text{ ref SEQ}}$$

$$\frac{}{\text{int} \leq \text{DYNAMIC}}$$

$$\frac{}{\tau \text{ ref SEQ} \leq \tau \text{ ref SAFE}}$$

TYPING RULES FOR COMMANDS

$$\frac{}{\Gamma \vdash \text{skip}}$$

$$\frac{\Gamma \vdash c_1 \quad \Gamma \vdash c_2}{\Gamma \vdash c_1; c_2}$$

$$\frac{\Gamma \vdash e : \tau \text{ ref SAFE} \quad \Gamma \vdash e' : \tau}{\Gamma \vdash e := e'}$$

$$\frac{\Gamma \vdash e : \text{DYNAMIC} \quad \Gamma \vdash e' : \text{DYNAMIC}}{\Gamma \vdash e := e'}$$

TYPING RULES FOR EXPRESSIONS

$$\frac{\Gamma(x) = \tau}{\Gamma \vdash x : \tau}$$

$$\frac{\Gamma \vdash e_1 : \text{int} \quad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 \text{ op } e_2 : \text{int}}$$

$$\frac{\Gamma \vdash e : \tau' \quad \tau' \leq \tau}{\Gamma \vdash (\tau)e : \tau}$$

$$\frac{}{\Gamma \vdash (\tau \text{ ref SAFE})0 : \tau \text{ ref SAFE}}$$

$$\frac{\Gamma \vdash e_1 : \tau \text{ ref SEQ} \quad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 \oplus e_2 : \tau \text{ ref SEQ}}$$

$$\frac{\Gamma \vdash e_1 : \text{DYNAMIC} \quad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 \oplus e_2 : \text{DYNAMIC}}$$

$$\frac{\Gamma \vdash e : \tau \text{ ref SAFE}}{\Gamma \vdash !e : \tau}$$

$$\frac{\Gamma \vdash e : \text{DYNAMIC}}{\Gamma \vdash !e : \text{DYNAMIC}}$$

THEOREMS

$\Sigma, M_H \vdash e \Downarrow \text{CheckFailed}$ means a run-time check failed during the execution of expression e .

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$\Sigma, M_H \vdash e \Downarrow \text{CheckFailed}$ means a run-time check failed during the execution of expression e .

THEOREM (PROGRESS AND TYPE PRESERVATION)

If $\Gamma \vdash e : \tau$ and $\Sigma \in \llbracket \Gamma \rrbracket_H$ and M is well-formed, then either $\Sigma, M_H \vdash e \Downarrow \text{CheckFailed}$ or $\Sigma, M_H \vdash e \Downarrow v$ and $v \in \llbracket \tau \rrbracket_H$.

THEOREMS

$\Sigma, M_H \vdash c \implies \text{CheckFailed}$ means a run-time check failed during the execution of command c .

THEOREMS

$\Sigma, M_H \vdash c \implies \text{CheckFailed}$ means a run-time check failed during the execution of command c .


THEOREM (PROGRESS FOR COMMANDS)

If $\Gamma \vdash c$ and $\Sigma \in \|\Gamma\|_h$ and M_H is well-formed then either $\Sigma, M_H \vdash c \implies \text{CheckFailed}$ or $\Sigma, M_H \vdash c \implies M'_H$ and M'_H is well-formed.

MAIN RESULTS

- An efficient inference algorithm attaches `ref SEQ`, `ref SAFE`, `DYNAMIC` annotations to plain C code.
- Most of the checks can be done statically.
- The performance overhead of the remaining run-time checks is moderate: 0–150%

FURTHER READING

-  *CCured: Type-Safe Retrofitting of Legacy Code*, in POPL'02 — ACM Symposium on Principles of Programming Languages, 2002.