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The Hoare Calculus

Calculus for reasoning about imperative programs.

- "Hoare triple": {*P*} *c* {*Q*}
 - Logical propositions P and Q, program command c.
 - The Hoare triple is itself a logical proposition.
 - The Hoare calculus gives rules for constructing true Hoare triples.
- Partial correctness interpretation of $\{P\}$ c $\{Q\}$:

"If c is executed in a state in which P holds, then it terminates in a state in which Q holds unless it aborts or runs forever."

- Program does not produce wrong result.
- But program also need not produce any result.
 - Abortion and non-termination are not ruled out.
- Total correctness interpretation of $\{P\}$ c $\{Q\}$:

"If c is executed in a state in which P holds, then it terminates in a state in which Q holds.

Program produces the correct result.

We will use the partial correctness interpretation for the moment.

- 1. The Hoare Calculus for Non-Loop Programs
- 2. Predicate Transformers
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JML and Hoare Triples



JML version of a Hoare triple.

```
//@ assume P;
//@ assert Q:
```

Treated by ESC/Java2 in much the same way as $\{P\}$ c $\{Q\}$.

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Method Contracts as Hoare Triples



Neglect exceptions and frame conditions for the moment.

```
T y; // global variable used by p //@ requires P(x,y); //@ ensures Q(x, \operatorname{old}(y), y, \operatorname{result}); static T p(T x) { T z; c; return z; } \{P(x,y) \wedge \operatorname{old} x = x \wedge \operatorname{old} y = y\} C \{Q(\operatorname{old} x, \operatorname{old} y, y, z)\}
```

- Precondition P may refer to parameter/global variable x and y.
- Both x and y may be changed.
- Postcondition Q may refer to (the old value of) x, both the old and the new value of y, and the result value z.

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Special Commands



Commands modeling "emptiness" and abortion.

$$\{P\}$$
 skip $\{P\}$ $\{\text{true}\}$ abort $\{\text{false}\}$

- The **skip** command does not change the state; if *P* holds before its execution, then *P* thus holds afterwards as well.
- The abort command aborts execution and thus trivially satisfies partial correctness.
 - Axiom implies $\{P\}$ abort $\{Q\}$ for arbitrary P, Q.

Useful commands for reasoning and program transformations.

General Rules



$$\frac{P \Rightarrow Q}{\{P\} \{Q\}} \qquad \frac{P \Rightarrow P' \ \{P'\} \ c \ \{Q'\} \quad Q' \Rightarrow Q}{\{P\} \ c \ \{Q\}}$$

- Logical derivation: $\frac{A_1 A_2}{B}$
 - Forward: If we have shown A_1 and A_2 , then we have also shown B.
 - Backward: To show B_1 , it suffices to show A_1 and A_2 .
- Interpretation of above sentences:
 - To show that, if *P* holds in a state, then *Q* holds in the same state (no command is executed), it suffices to show *P* implies *Q*.
 - Hoare triples are ultimately reduced to classical logic.
 - To show that, if P holds, then Q holds after executing c, it suffices to show this for a P' weaker than P and a Q' stronger than Q.
 - Precondition may be weakened, postcondition may be strengthened.

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Scalar Assignments



$${Q[e/x]} x := e {Q}$$

- Syntax
 - Variable *x*, expression *e*.
 - lacksquare $Q[e/x] \dots Q$ where every free occurrence of x is replaced by e.
- Interpretation
 - To make sure that Q holds for x after the assignment of e to x, it suffices to make sure that Q holds for e before the assignment.
- Partial correctness
 - Evaluation of e may abort.

$$\{x+3<5\}$$
 $x:=x+3$ $\{x<5\}$
 $\{x<2\}$ $x:=x+3$ $\{x<5\}$

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Array Assignments



$$\{Q[a[i\mapsto e]/a]\}\ a[i]:=e\ \{Q\}$$

- An array is modelled as a function $a: I \rightarrow V$
 - Index set *I*, value set *V*.
 - $a[i] = e \dots a$ holds at index i the value e.
- Updated array $a[i \mapsto e]$
 - \blacksquare Array that is constructed from a by mapping index i to value e.
 - Axioms (for all $a: I \rightarrow V, i \in I, j \in I, e \in V$):

$$i = j \Rightarrow a[i \mapsto e][j] = e$$

 $i \neq j \Rightarrow a[i \mapsto e][j] = a[j]$

$$\{a[i \mapsto x][1] > 0\}$$
 $a[i] := x$ $\{a[1] > 0\}$
 $\{(i = 1 \Rightarrow x > 0) \land (i \neq 1 \Rightarrow a[1] > 0)\}$ $a[i] := x$ $\{a[1] > 0\}$

Index violations and pointer semantics of arrays not yet considered.

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Conditionals



$$\frac{\{P \land b\} \ c_1 \ \{Q\} \ \{P \land \neg b\} \ c_2 \ \{Q\}}{\{P\} \ \text{if } b \ \text{then} \ c_1 \ \text{else} \ c_2 \ \{Q\}}$$

$$\frac{\{P \land b\} \ c \ \{Q\} \ (P \land \neg b) \Rightarrow Q}{\{P\} \ \text{if } b \ \text{then } c \ \{Q\}}$$

- Interpretation
 - To show that, if *P* holds before the execution of the conditional, then *Q* holds afterwards.
 - it suffices to show that the same is true for each conditional branch, under the additional assumption that this branch is executed.

$$\frac{\{x \neq 0 \land x \geq 0\} \ y := x \ \{y > 0\} \ \ \{x \neq 0 \land x \not\geq 0\} \ y := -x \ \{y > 0\}}{\{x \neq 0\} \ \text{if} \ x \geq 0 \ \text{then} \ y := x \ \text{else} \ y := -x \ \{y > 0\}}$$

Command Sequences



$$\frac{\{P\}\ c_1\ \{R_1\}\ R_1 \Rightarrow R_2\ \{R_2\}\ c_2\ \{Q\}}{\{P\}\ c_1; c_2\ \{Q\}}$$

- Interpretation
 - To show that, if P holds before the execution of c_1 ; c_2 , then Q holds afterwards, it suffices to show for some R_1 and R_2 with $R_1 \Rightarrow R_2$ that
 - if P holds before c_1 , that R_1 holds afterwards, and that
 - if R_2 holds before c_2 , then Q holds afterwards.
- Problem: find suitable R_1 and R_2
 - Easy in many cases (see later).

$$\frac{\{x+y-1>0\}\ y:=y-1\ \{x+y>0\}\ \{x+y>0\}\ x:=x+y\ \{x>0\}}{\{x+y-1>0\}\ y:=y-1; x:=x+y\ \{x>0\}}$$

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- 1. The Hoare Calculus for Non-Loop Programs
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Backward Reasoning



Implication of rule for command sequences and rule for assignments:

$${P} c {Q[e/x]}$$

$${P} c; x := e {Q}$$

Interpretation

- If the last command of a sequence is an assignment, we can remove the assignment from the proof obligation.
- By multiple application, assignment sequences can be removed from the back to the front.

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Weakest Preconditions



The weakest precondition of each program construct.

```
 \begin{aligned} & \mathsf{wp}(\mathbf{skip}, Q) \Leftrightarrow Q \\ & \mathsf{wp}(\mathbf{abort}, Q) \Leftrightarrow \mathsf{true} \\ & \mathsf{wp}(x := e, Q) \Leftrightarrow Q[e/x] \\ & \mathsf{wp}(c_1; c_2, Q) \Leftrightarrow \mathsf{wp}(c_1, \mathsf{wp}(c_2, Q)) \\ & \mathsf{wp}(\mathbf{if} \ b \ \mathbf{then} \ c_1 \ \mathbf{else} \ c_2, Q) \Leftrightarrow (b \Rightarrow \mathsf{wp}(c_1, Q)) \land (\neg b \Rightarrow \mathsf{wp}(c_2, Q)) \\ & \mathsf{wp}(\mathbf{if} \ b \ \mathbf{then} \ c, Q) \Leftrightarrow (b \Rightarrow \mathsf{wp}(c, Q)) \land (\neg b \Rightarrow Q) \end{aligned}
```

Alternative formulation of a program calculus.

Weakest Preconditions



A calculus for "backward reasoning".

- Predicate transformer wp
 - Function "wp" that takes a command c and a postcondition Q and returns a precondition.
 - Read wp(c, Q) as "the weakest precondition of c w.r.t. Q".
- wp(c, Q) is a precondition for c that ensures Q as a postcondition.
 - Must satisfy $\{wp(c, Q)\}$ c $\{Q\}$.
- = wp(c, Q) is the weakest such precondition.
 - Take any P such that $\{P\}$ c $\{Q\}$.
 - Then $P \Rightarrow wp(P, Q)$.
- Consequence: $\{P\}$ c $\{Q\}$ iff $(P \Rightarrow wp(c, Q))$
 - We want to prove $\{P\}$ c $\{Q\}$.
 - We may prove $P \Rightarrow wp(c, Q)$ instead.

Verification is reduced to the calculation of weakest preconditions.

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Forward Reasoning



Sometimes, we want to derive a postcondition from a given precondition.

$$\{P\} \ x := e \ \{\exists x_0 : P[x_0/x] \land x = e[x_0/x]\}$$

- Forward Reasoning
 - What is the maximum we know about the post-state of an assignment x := e, if the pre-state satisfies P?
 - We know that P holds for some value x_0 (the value of x in the pre-state) and that x equals $e[x_0/x]$.

$$\begin{cases} x \geq 0 \land y = a \} \\ x := x + 1 \end{cases}$$

$$\{ \exists x_0 : x_0 \geq 0 \land y = a \land x = x_0 + 1 \}$$

$$(\Leftrightarrow (\exists x_0 : x_0 \geq 0 \land x = x_0 + 1) \land y = a)$$

$$(\Leftrightarrow x > 0 \land y = a)$$

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Strongest Postcondition



A calculus for forward reasoning.

- Predicate transformer sp
 - Function "sp" that takes a precondition *P* and a command *c* and returns a postcondition.
 - Read sp(P, c) as "the strongest postcondition of c w.r.t. P".
- = sp(P,c) is a postcondition for c that is ensured by precondition P.
 - Must satisfy $\{P\}$ c $\{\operatorname{sp}(P,c)\}$.
- = sp(P, c) is the strongest such postcondition.
 - Take any P, Q such that $\{P\}$ c $\{Q\}$.
 - Then $sp(P, c) \Rightarrow Q$.
- Consequence: $\{P\}$ c $\{Q\}$ iff $(\operatorname{sp}(P,c) \Rightarrow Q)$.
 - We want to prove $\{P\}$ c $\{Q\}$.
 - We may prove $\operatorname{sp}(P,c) \Rightarrow Q$ instead.

Verification is reduced to the calculation of strongest postconditions.

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Strongest Postconditions



The strongest postcondition of each program construct.

$$sp(P, \mathbf{skip}) \Leftrightarrow P$$

$$sp(P, \mathbf{abort}) \Leftrightarrow false$$

$$sp(P, x := e) \Leftrightarrow \exists x_0 : P[x_0/x] \land x = e[x_0/x]$$

$$sp(P, c_1; c_2) \Leftrightarrow sp(sp(P, c_1), c_2)$$

$$sp(P, \mathbf{if} \ b \ \mathbf{then} \ c_1 \ \mathbf{else} \ c_2) \Leftrightarrow (b \Rightarrow sp(P, c_1)) \land (\neg b \Rightarrow sp(P, c_2))$$

$$sp(P, \mathbf{if} \ b \ \mathbf{then} \ c) \Leftrightarrow (b \Rightarrow sp(P, c)) \land (\neg b \Rightarrow P)$$

The use of predicate transformers is an alternative/supplement to the Hoare calculus; this view is due to Dijkstra.

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The Hoare Calculus and Loops



$$\{\mathsf{true}\} \ \textbf{loop} \ \{\mathsf{false}\}$$

$$\frac{P \Rightarrow I \quad \{I \land b\} \ c \ \{I\} \quad (I \land \neg b) \Rightarrow Q}{\{P\} \text{ while } b \text{ do } c \ \{Q\}}$$

- Interpretation:
 - The loop command does not terminate and thus trivially satisfies partial correctness.
 - Axiom implies $\{P\}$ **loop** $\{Q\}$ for arbitrary P, Q.
 - To show that, if before the execution of a **while**-loop the property *P* holds, after its termination the property *Q* holds, it suffices to show for some property *I* (the loop invariant) that
 - *I* holds before the loop is executed (i.e. that *P* implies *I*),
 - if I holds when the loop body is entered (i.e. if also b holds), that after the execution of the loop body I still holds,
 - when the loop terminates (i.e. if b does not hold), I implies Q.
- Problem: find appropriate loop invariant 1.
 - Strongest relationship between all variables modified in loop body.

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Example



$$I :\Leftrightarrow (n \ge 0 \Rightarrow 1 \le i \le n+1) \land s = \sum_{j=1}^{i-1} j$$

$$(i = 1 \land s = 0) \Rightarrow I$$

$$\{I \land i \le 0\} \ s := s+i; i := i+1 \ \{I\}$$

$$(I \land i \le n) \Rightarrow s = \sum_{j=1}^{n} j$$

$$\{i = 1 \land s = 0\} \ \text{while} \ i \le n \ \text{do} \ (s := s+i; i := i+1) \ \{s = \sum_{j=1}^{n} j\}$$

The invariant captures the "essence" of a loop; only by giving its invariant, a true understanding of a loop is demonstrated.

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Practical Aspects



We want to verify the following program:

$$\{P\}\ c_1$$
; while b do c; $c_2\ \{Q\}$

- Assume c_1 and c_2 do not contain loop commands.
- It suffices to prove

$$\{\operatorname{sp}(P,c_1)\}\$$
while b do c $\{\operatorname{wp}(c_2,Q)\}$

Verification of loops is the core of most program verifications.

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Weakest Liberal Preconditions for Loops



$$wp(\mathbf{loop}, Q) \Leftrightarrow true$$

 $wp(\mathbf{while} \ b \ \mathbf{do} \ c, Q) \Leftrightarrow \forall i \in \mathbb{N} : L_i(Q)$

$$L_0(Q) :\Leftrightarrow \mathsf{true}$$

 $L_{i+1}(Q) :\Leftrightarrow (\neg b \Rightarrow Q) \land (b \Rightarrow \mathsf{wp}(c, L_i(Q)))$

- Interpretation
 - Weakest precondition that ensures that loops stops in a state satisfying Q, unless it aborts or runs forever.
- Infinite sequence of predicates $L_i(Q)$:
 - Weakest precondition that ensures that loops stops after less than i iterations in a state satisfying Q, unless it aborts or runs forever.
- Alternative view: $L_i(Q) \Leftrightarrow wp(if_i, Q)$

$$if_0 := loop$$

 $if_{i+1} := if b then (c; if_i)$

Example



wp(while i < n do i := i + 1, Q)

$$L_{0}(Q) \Leftrightarrow \text{true}$$

$$L_{1}(Q) \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow \text{wp}(i := i + 1, \text{true}))$$

$$\Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow \text{true})$$

$$\Leftrightarrow (i \not< n \Rightarrow Q)$$

$$L_{2}(Q) \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow \text{wp}(i := i + 1, i \not< n \Rightarrow Q))$$

$$\Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow Q[i + 1/i])$$

$$L_{3}(Q) \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow \text{wp}(i := i + 1, i \not< n \Rightarrow Q[i + 1/i]))$$

$$L_{3}(Q) \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow \text{wp}(i := i + 1, i \not< n \Rightarrow Q[i + 1/i]))))$$

$$\Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow Q[i + 1/i]) \land (i < n \Rightarrow Q[i + 1/i]) \land (i < n \Rightarrow Q[i + 2/i]))))$$

Weakest Liberal Preconditions for Loops



- Sequence $L_i(Q)$ is monotonically increasing in strength:
 - $\forall i \in \mathbb{N} : L_{i+1}(Q) \Rightarrow L_i(Q).$
- The weakest precondition is the "lowest upper bound":
 - wp(while b do c, Q) $\Rightarrow \forall i \in \mathbb{N} : L_i(Q)$.
 - $\forall P : (P \Rightarrow \forall i \in \mathbb{N} : L_i(Q)) \Rightarrow (P \Rightarrow \mathsf{wp}(\mathsf{while}\ b\ \mathsf{do}\ c, Q)).$
- We can only compute weaker approximation $L_i(Q)$.
 - wp(while b do c, Q) $\Rightarrow L_i(Q)$.
- We want to prove $\{P\}$ while b do c $\{Q\}$.
 - This is equivalent to proving $P \Rightarrow wp(\mathbf{while}\ b\ \mathbf{do}\ c, Q)$.
 - Thus $P \Rightarrow L_i(Q)$ must hold as well.
- If we can prove $\neg(P \Rightarrow L_i(Q)), \ldots$
 - P while b do c $\{Q\}$ does not hold.
 - If we fail, we may try the easier proof $\neg (P \Rightarrow L_{i+1}(Q))$.

Falsification is possible by use of approximation L_i , but verification is not.

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Total Correctness of Loops



Hoare rules for loop and while are replaced as follows:

$$\begin{array}{c} P \Rightarrow I \quad I \land b \Rightarrow t > 0 \\ \hline \{ \text{false} \} \text{ loop } \{ \text{false} \} \\ \hline \{ P \} \text{ while } b \text{ do } c \text{ } \{ Q \} \\ \end{array}$$

- New interpretation of $\{P\}$ c $\{Q\}$.
 - If execution of *c* starts in a state where *P* holds, then execution terminates in a state where *Q* holds, unless it aborts.
 - Non-termination is ruled out, abortion not (yet).
 - The **loop** command thus does not satisfy total correctness.
- Termination term t.
 - Denotes a natural number before and after every loop iteration.
 - If t = N before an iteration, then t < N after the iteration.
 - Consequently, if term denotes zero, loop must terminate.

Instead of the natural numbers, any *well-founded ordering* may be used for the domain of t.



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Example



$$I:\Leftrightarrow (n\geq 0\Rightarrow 1\leq i\leq n+1) \land s=\sum_{j=1}^{i-1}j$$

$$(i=1\land s=0)\Rightarrow I \quad I \land i\leq n\Rightarrow n-i+1>0$$

$$\{I\land i\leq 0\land n-i+1=N\} \ s:=s+i; i:=i+1 \ \{I\land n-i+1< N\}$$

$$(I\land i\nleq n)\Rightarrow s=\sum_{j=1}^{n}j$$

$$\{i=1\land s=0\} \ \text{while} \ i\leq n \ \text{do} \ (s:=s+i; i:=i+1) \ \{s=\sum_{i=1}^{n}j\}$$

In practice, termination is easy to show (compared to partial correctness).

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Weakest Preconditions for Loops



- New interpretation
 - Weakest precondition that ensures that the loop terminates in a state in which *Q* holds, unless it aborts.
- New interpretation of $L_i(Q)$
 - Weakest precondition that ensures that the loop terminates after less than *i* iterations in a state in which *Q* holds, unless it aborts.
- Preserves property: $\{P\}$ c $\{Q\}$ iff $(P \Rightarrow wp(c, Q))$
 - Now for total correctness interpretation of Hoare calculus.
- Preserves alternative view: $L_i(Q) \Leftrightarrow wp(if_i, Q)$

$$if_0 := loop$$

 $if_{i+1} := if b then (c; if_i)$

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Weakest Preconditions for Loops



- Sequence $L_i(Q)$ is now monotonically decreasing in strength:
 - $\forall i \in \mathbb{N} : L_i(Q) \Rightarrow L_{i+1}(Q).$
- The weakest precondition is the "greatest lower bound":
 - $\forall i \in \mathbb{N} : L_i(Q)) \Rightarrow wp(\mathbf{while} \ b \ \mathbf{do} \ c, Q).$
 - $P : ((\forall i \in \mathbb{N} : L_i(Q)) \Rightarrow P) \Rightarrow (\mathsf{wp}(\mathsf{while}\ b\ \mathsf{do}\ c, Q) \Rightarrow P).$
- We can only compute a stronger approximation $L_i(Q)$.
 - $L_i(Q) \Rightarrow wp(\mathbf{while}\ b\ \mathbf{do}\ c, Q)$.
- We want to prove $\{P\}$ c $\{Q\}$.
 - It suffices to prove $P \Rightarrow wp(\mathbf{while}\ b\ \mathbf{do}\ c, Q)$.
 - It thus also suffices to prove $P \Rightarrow L_i(Q)$.
 - If proof fails, we may try the easier proof $P \Rightarrow L_{i+1}(Q)$

Verifications are typically not successful with finite approximation of weakest precondition.

Example



```
\begin{split} & \text{wp}(\textbf{while } i < n \text{ do } i := i+1, Q) \\ & L_0(Q) : \Leftrightarrow \text{false} \\ & L_1(Q) : \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow wp(i := i+1, L_0(Q))) \\ & \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow \text{ false}) \\ & \Leftrightarrow i \not< n \land Q \\ & L_2(Q) : \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow wp(i := i+1, L_1(Q))) \\ & \Leftrightarrow (i \not< n \Rightarrow Q) \land \\ & i < n \Rightarrow (i+1 \not< n \land Q[i+1/i])) \\ & L_3(Q) : \Leftrightarrow (i \not< n \Rightarrow Q) \land (i < n \Rightarrow wp(i := i+1, L_2(Q))) \\ & \Leftrightarrow (i \not< n \Rightarrow Q) \land \\ & (i < n \Rightarrow Q) \land \\ & (i < n \Rightarrow Q[i+1/i]) \land \\ & (i+1 < n \Rightarrow (i+2 \not< n \land Q[i+2/i])))) \\ & \dots \end{split}
```

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Abortion



New rules to prevent abortion.

- New interpretation of $\{P\}$ c $\{Q\}$.
 - If execution of *c* starts in a state, in which property *P* holds, then it does not abort and eventually terminates in a state in which *Q* holds.
- Sources of abortion.
 - Division by zero.
 - Index out of bounds exception.

D(e) makes sure that every subexpression of e is well defined.

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Abortion



Slight modification of existing rules.

$$\frac{\{P \land b \land D(b)\}\ c_1\ \{Q\}\ \{P \land \neg b \land D(b)\}\ c_2\ \{Q\}\}}{\{P\}\ \textbf{if}\ b\ \textbf{then}\ c_1\ \textbf{else}\ c_2\ \{Q\}}$$

$$\frac{\{P \land b \land D(b)\}\ c\ \{Q\}\ (P \land \neg b \land D(b)) \Rightarrow Q}{\{P\}\ \textbf{if}\ b\ \textbf{then}\ c\ \{Q\}}$$

$$P \Rightarrow I\ I \Rightarrow (T \in \mathbb{N} \land D(b))$$

$$\frac{\{I \land b \land T = t\}\ c\ \{I \land T < t\}\ (I \land \neg b) \Rightarrow Q}{\{P\}\ \textbf{while}\ b\ \textbf{do}\ c\ \{Q\}}$$

Expressions must be defined in any context.

Definedness of Expressions



```
D(0) : \Leftrightarrow true.
D(1) : \Leftrightarrow true.
D(x) : \Leftrightarrow \text{true}.
D(a[i]) : \Leftrightarrow D(i) \land 0 < i < \text{length}(a).
D(e_1 + e_2) :\Leftrightarrow D(e_1) \wedge D(e_2).
D(e_1 * e_2) :\Leftrightarrow D(e_1) \wedge D(e_2).
D(e_1/e_2) : \Leftrightarrow D(e_1) \wedge D(e_2) \wedge e_2 \neq 0.
D(true) : \Leftrightarrow true.
D(false) : \Leftrightarrow true.
D(\neg b) : \Leftrightarrow D(b).
D(b_1 \wedge b_2) :\Leftrightarrow D(b_1) \wedge D(b_2).
D(b_1 \vee b_2) :\Leftrightarrow D(b_1) \wedge D(b_2).
D(e_1 < e_2) :\Leftrightarrow D(e_1) \wedge D(e_2).
D(e_1 \leq e_2) :\Leftrightarrow D(e_1) \wedge D(e_2).
D(e_1 > e_2) :\Leftrightarrow D(e_1) \wedge D(e_2).
D(e_1 > e_2) :\Leftrightarrow D(e_1) \wedge D(e_2).
```

Assumes that expressions have already been type-checked.

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Abortion



Similar modifications of weakest preconditions.

```
 \begin{array}{l} \mathsf{wp}(\mathbf{abort}, Q) \Leftrightarrow \mathsf{false} \\ \mathsf{wp}(x := e, Q) \Leftrightarrow Q[e/x] \wedge D(e) \\ \mathsf{wp}(\mathbf{if} \ b \ \mathbf{then} \ c_1 \ \mathbf{else} \ c_2, Q) \Leftrightarrow \\ D(b) \wedge (b \Rightarrow \mathsf{wp}(c_1, Q)) \wedge (\neg b \Rightarrow \mathsf{wp}(c_2, Q)) \\ \mathsf{wp}(\mathbf{if} \ b \ \mathbf{then} \ c, Q) \Leftrightarrow D(b) \wedge (b \Rightarrow \mathsf{wp}(c, Q)) \wedge (\neg b \Rightarrow Q) \\ \mathsf{wp}(\mathbf{while} \ b \ \mathbf{do} \ c, Q) \Leftrightarrow \exists i \in \mathbb{N} : L_i(Q) \\ \\ L_0(Q) :\Leftrightarrow \mathsf{false} \\ L_{i+1}(Q) :\Leftrightarrow D(b) \wedge (\neg b \Rightarrow Q) \wedge (b \Rightarrow \mathsf{wp}(c, L_i(Q))) \end{array}
```

wp(c, Q) now makes sure that the execution of c does not abort but eventually terminates in a state in which Q holds.

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- 1. The Hoare Calculus for Non-Loop Programs
- 2. Predicate Transformers
- 3. Partial Correctness of Loop Programs
- 4. Total Correctness of Loop Programs
- 5. Abortion
- 6. Procedures

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Procedure Calls



First let us give an alternative (equivalent) version of the assignment rule.

Original:

$$\{D(e) \land Q[e/x]\}$$

$$x := e$$

$$\{Q\}$$

Alternative:

$$\{D(e) \land \forall x' : x' = e \Rightarrow Q[x'/x]\}$$

$$x := e$$

$$\{Q\}$$

The new value of x is given name x' in the precondition.

Procedure Specifications



```
global F;
requires Pre;
ensures Post;
p(i, t, o) \{ c \}
```

- Specification of procedure p(i, t, o).
 - Input parameter i, transient parameter t, output parameter o.
 - A call has form p(e, x, y) for expression e and variables x and y.
 - Set of global variables ("frame") F.
 - Those global variables that p may read/write (in addition to i, t, o).
 - Let f denote all variables in F; let g denote all variables not in F.
 - Precondition *Pre* (may refer to i, t, f).
 - Postcondition *Post* (may refer to i, t, t_0, f, f_0, o).
- Proof obligation

$$\{Pre \land i_0 = i \land t_0 = t \land f_0 = f\} \ c \ \{Post[i_0/i]\}$$

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Procedure Calls



From this, we can derive a rule for the correctness of procedure calls.

$$\begin{cases} D(e) \land Pre[e/i, x/t] \land \\ \forall x', y', f' : Post[e/i, x/t_0, x'/t, y'/o, f/f_0, f'/f] \Rightarrow Q[x'/x, y'/y, f'/f] \rbrace \\ \rho(e, x, y) \\ \{Q\} \end{cases}$$

- Pre[e/i, x/t] refers to the values of the actual arguments e and x (rather than to the formal parameters i and t).
- x', y', f' denote the values of the vars x, y, and f after the call.
- Post[...] refers to the argument values before and after the call.
- Q[x'/x, y'/y, f'/f] refers to the argument values after the call.

Modular reasoning: rule only relies on the *specification* of p, not on its implementation.

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Corresponding Predicate Transformers



```
\begin{split} & \mathsf{wp}(p(e,x,y),Q) \Leftrightarrow \\ & D(e) \land Pre[e/i,x/t] \land \\ & \forall x',y',f': \\ & Post[e/i,x/t_0,x'/t,y'/o,f/f_0,f'/f] \Rightarrow Q[x'/x,y'/y,f'/f] \\ & \mathsf{sp}(P,p(e,x,y)) \Leftrightarrow \\ & \exists x_0,y_0,f_0: \\ & P[x_0/x,y_0/y,f_0/f] \land \\ & Post[e[x_0/x,y_0/y,f_0/f]/i,x_0/t_0,x/t,y/o] \end{split}
```

Explicit naming of old/new values required.

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Not Yet Covered



- Primitive data types.
 - int values are actually finite precision integers.
- More data and control structures.
 - switch, do-while (easy); continue, break, return (more complicated).
 - Records can be handled similar to arrays.
- Recursion.
 - Procedures may not terminate due to recursive calls.
- Exceptions and Exception Handling.
 - Short discussion in the context of ESC/Java2 later.
- Pointers and Objects.
 - Here reasoning gets complicated.
-

The more features are covered, the more complicated reasoning becomes.

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Procedure Calls Example



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Procedure specification:

```
global f
requires f \ge 0 \land i > 0
ensures f_0 = f \cdot i + o \land 0 \le o < i
dividesF(i, o)
```

Procedure call:

$$\begin{cases} f \ge 0 \land f = N \land b \ge 0 \\ \text{divides} F(b+1, y) \\ \{ f \cdot (b+1) \le N < (f+1) \cdot (b+1) \} \end{cases}$$

■ To be ultimately proved:

$$\begin{split} f &\geq 0 \land f = N \land b \geq 0 \Rightarrow \\ D(b+1) \land f &\geq 0 \land b+1 > 0 \land \\ \forall y', f': \\ f &= f' \cdot (b+1) + y' \land 0 \leq y' < b+1 \Rightarrow \\ f' \cdot (b+1) &\leq N < (f'+1) \cdot (b+1) \end{split}$$

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