

## More on Relations 3

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## Overview

- Directed Graphs
- Paths and Reachability
- Trees

## Directed Graphs

## Directed Graphs

**Definition:** A directed graph is a pair  $\langle V, E \rangle$  of a set  $V$  of vertices/nodes and a set of  $E$  of edges/arcs where  $E$  is binary relation on  $V$ :

$G$  is directed graph  $:\Leftrightarrow$

$\exists V, E :$

$$G = \langle V, E \rangle \wedge$$

$$E \subseteq V \times V.$$

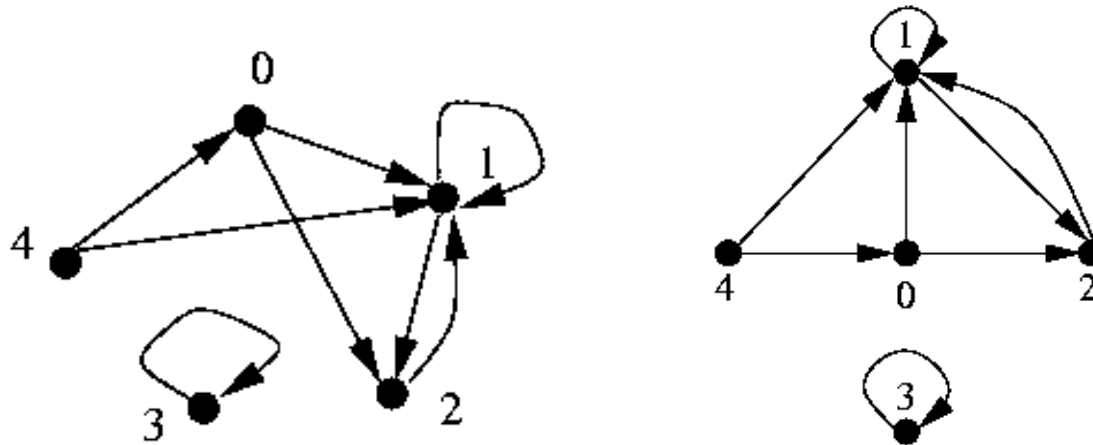
**Interpretation:**  $\langle x, y \rangle \in E$

- $x$  is connected to  $y$  in  $G$ ,
- $x$  is initial node of edge,
- $y$  is terminal node of edge.

## Example

Graph  $\langle \mathbb{N}_5, E \rangle$

$$E = \{ \langle 0, 1 \rangle, \langle 0, 2 \rangle, \langle 1, 1 \rangle, \langle 1, 2 \rangle, \langle 2, 1 \rangle, \langle 3, 3 \rangle, \langle 4, 0 \rangle, \langle 4, 1 \rangle \}$$



The visual representation of a graph is not unique.

## Example

Graph  $\langle \mathbb{N}_5, E \rangle$

$$E = \{\langle 0, 1 \rangle, \langle 0, 2 \rangle, \langle 1, 1 \rangle, \langle 1, 2 \rangle, \langle 2, 1 \rangle, \langle 3, 3 \rangle, \langle 4, 0 \rangle, \langle 4, 1 \rangle\}$$

	0	1	2	3	4
0	false	true	true	false	false
1	false	true	true	false	false
2	false	true	false	false	false
3	false	false	false	true	false
4	true	true	false	false	false

Matrix representation is used for computing.

## Adjacency Matrix

**Definition:** Let  $G = \langle V, E \rangle$  be a directed graph with  $|V| = n$ . The **adjacency matrix** of  $G$  is the boolean  $n \times n$  matrix  $M$  where  $M(x, y) = \text{true}$  if and only if  $\langle x, y \rangle \in E$ :

$$\begin{aligned} \text{adjacency}(G) &:= \\ &\text{let } V = G_0, E = G_1 : \\ &\text{such } M \in V \times V \rightarrow \{\text{true}, \text{false}\} : \\ &(\forall x \in V, y \in V : M(x, y) = \text{true} \Leftrightarrow \langle x, y \rangle \in E). \end{aligned}$$

Matrix representation from graph.

## Undirected Graph

**Definition:** An **undirected graph** is a directed graph whose edge relation is symmetric:

$$\begin{aligned} G \text{ is undirected graph} &:\Leftrightarrow \\ &\exists V, E : \\ &G = \langle V, E \rangle, \\ &E \subseteq V \times V, \\ &E \text{ is symmetric on } V. \end{aligned}$$

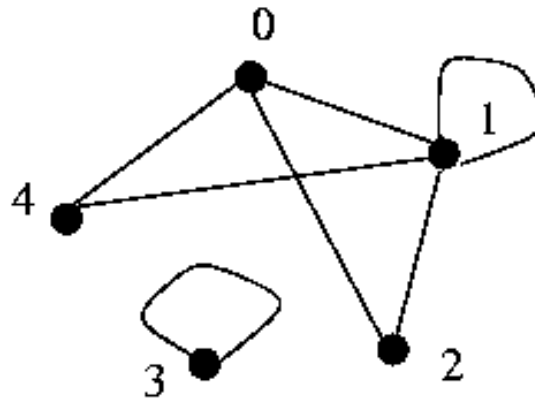
Special kind of directed graph.



## Example

Graph  $\langle \mathbb{N}_5, E \rangle$

$$E = \{ \langle 0, 1 \rangle, \langle 1, 0 \rangle, \langle 0, 2 \rangle, \langle 2, 0 \rangle, \langle 1, 1 \rangle, \langle 1, 2 \rangle, \\ \langle 2, 1 \rangle, \langle 3, 3 \rangle, \langle 0, 4 \rangle, \langle 4, 0 \rangle, \langle 1, 4 \rangle, \langle 4, 1 \rangle \}$$



Draw single undirected edge instead of pair of directed edges.

## Example

Graph  $\langle \mathbb{N}_5, E \rangle$

$$E = \{ \langle 0, 1 \rangle, \langle 1, 0 \rangle, \langle 0, 2 \rangle, \langle 2, 0 \rangle, \langle 1, 1 \rangle, \langle 1, 2 \rangle, \langle 2, 1 \rangle, \langle 3, 3 \rangle, \langle 0, 4 \rangle, \langle 4, 0 \rangle, \langle 1, 4 \rangle, \langle 4, 1 \rangle \}$$

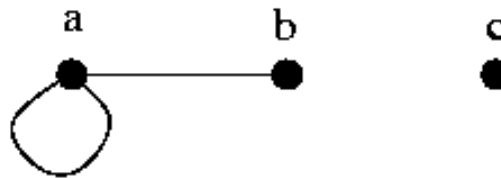
	0	1	2	3	4
0	false	true	true	false	true
1		true	true	false	true
2			false	false	false
3				true	false
4					false

Missing matrix elements are determined by symmetry.

## Example

Graph  $\langle \{a, b, c\}, E \rangle$

$$E = \{ \langle a, a \rangle, \langle a, b \rangle, \langle b, a \rangle \}$$



	a	b	c
a	true	true	false
b		false	false
c			false

## Degree

**Definition:** In a directed graph, the **indegree** of  $x$  is the number of edges whose terminal node is  $x$ :

$$\text{indeg}_G(x) := |\{y \in V : \langle y, x \rangle \in E\}|$$

**where**  $V = G_0, E = G_1$ .

The **outdegree** of  $x$  is the number of edges whose initial node is  $x$ :

$$\text{outdeg}_G(x) := |\{y \in V : \langle x, y \rangle \in E\}|$$

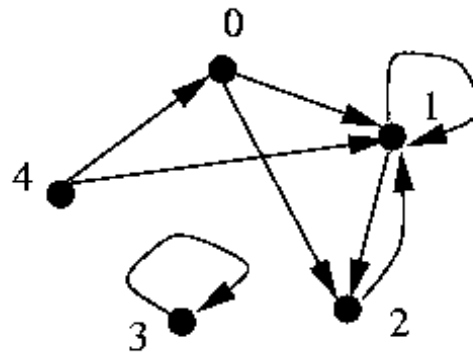
**where**  $V = G_0, E = G_1$ .

The **total degree** of  $x$  is the sum of its indegree and its outdegree:

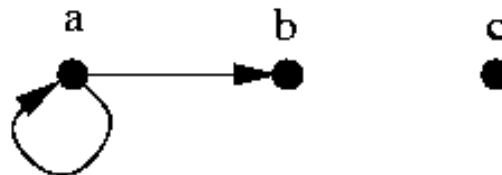
$$\text{deg}_G(x) := \text{indeg}_G(x) + \text{outdeg}_G(x).$$

## Example

- Indegree of node 1 is 4 and its outdegree is 2:



- Indegree and the outdegree of node c are both 0.



## Graph Isomorphisms

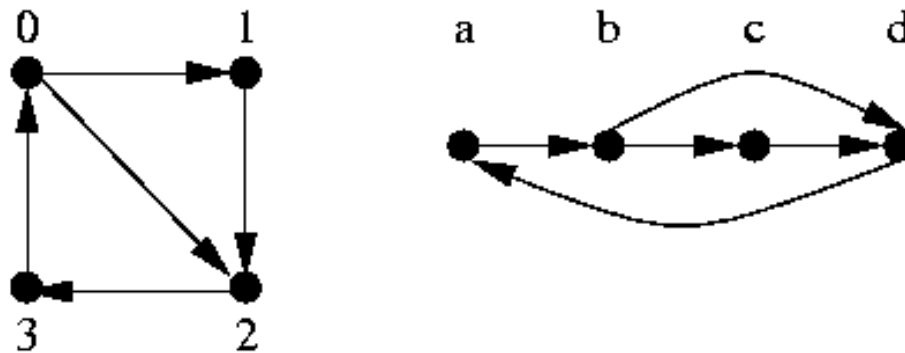
**Definition:** Two graphs are **isomorphic** if there exists a bijection between the nodes of the two graphs that preserves the edge structure:

$$\begin{aligned}
 &G \text{ and } G' \text{ are isomorphic} :\Leftrightarrow \\
 &G \text{ is directed graph} \wedge G' \text{ is directed graph} \wedge \\
 &\exists f : f : V \xrightarrow{\text{iso}(E, E')} V' \\
 &\quad \textbf{where } V = G_0, E = G_1, V' = G'_0, E' = G'_1.
 \end{aligned}$$

Different graphs may have same structure.

## Example

The graphs

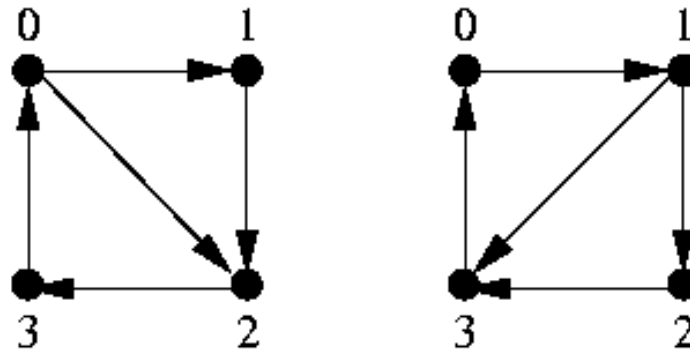


are isomorphic with isomorphism

$$f = \{\langle 0, b \rangle, \langle 1, c \rangle, \langle 2, d \rangle, \langle 3, a \rangle\}.$$

## Example

The graphs



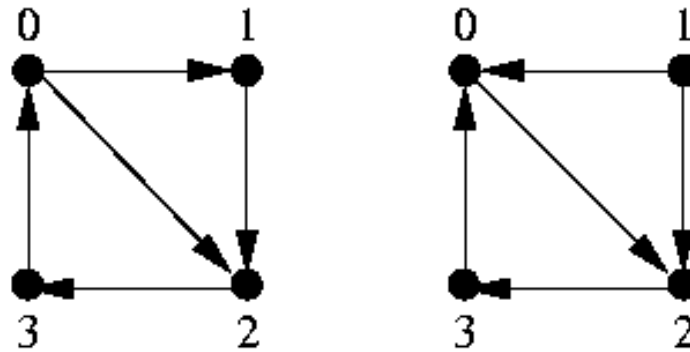
are isomorphic with isomorphism

$$f = \{\langle 0, 1 \rangle, \langle 1, 2 \rangle, \langle 2, 3 \rangle, \langle 3, 0 \rangle\}.$$



## Example

The graphs



are not isomorphic.

## Paths and Reachability

## Path

**Definition:** A **path** is a sequence of nodes connected by edges:

$$p \text{ is path in } G :\Leftrightarrow \\ (\exists n \in \mathbb{N}_{>0} : p : \mathbb{N}_n \rightarrow V \wedge \\ \forall i \in \mathbb{N}_{n-1} : \langle p_i, p_{i+1} \rangle \in E) \textbf{ where } V = G_0, E = G_1.$$

The **length** of a path is the number of edges it contains:

$$\text{length}(p) := \textbf{such } n \in \mathbb{N} : \exists V : p : \mathbb{N}_{n+1} \rightarrow V.$$

A path **from**  $x$  to  $y$  has initial node  $x$  and terminal node  $y$

$$p \text{ is path from } x \text{ to } y :\Leftrightarrow \\ p_0 = x \wedge p_n = y \textbf{ where } n = \text{length}(p).$$

## Path Properties

**Definition:** A path is **simple** if it does not contain any edge twice:

$p$  is simple  $:\Leftrightarrow$

$$\forall i \in \mathbb{N}_n, j \in \mathbb{N}_n : \langle p_i, p_{i+1} \rangle = \langle p_j, p_{j+1} \rangle \Rightarrow i = j$$

**where**  $n = \text{length}(p)$ .

A path is **elementary** if it does not contain any node twice:

$p$  is elementary  $:\Leftrightarrow$

$$(\forall i \in \mathbb{N}_n, j \in \mathbb{N}_n : p_i = p_j \Rightarrow i = j) \text{ **where** } n = 1 + \text{length}(p).$$

A path is a **cycle** or **circuit** if it terminates in its initial node:

$$p \text{ is cycle } :\Leftrightarrow \exists x : p \text{ is path from } x \text{ to } x.$$

## Reachability

**Definition:** A node  $y$  is **reachable** from a node  $x$  in a graph  $G$  if there is a path in  $G$  from  $x$  to  $y$ :

$$y \text{ is reachable from } x \text{ in } G :\Leftrightarrow \\ \exists p : p \text{ is path in } G \wedge p \text{ is path from } x \text{ to } y.$$

- For fixed  $G$ , “is reachable” is a binary relation on  $V$ .
- $E$  is a binary relation on  $V$ .

We are going to construct the reachability relation from  $E$ .

## Reflexive Closure

**Definition:** Let  $R$  be a binary relation on  $S$ . The **reflexive closure** of  $R$  on  $S$  is the smallest relation that contains  $R$  and is reflexive on  $S$ :

$$\begin{aligned} \text{reflexive}_S(R) := \\ \text{such } R' \subseteq S \times S : \\ R \subseteq R' \wedge R' \text{ is reflexive on } S \wedge \\ \forall R'' : (R \subseteq R'' \wedge R'' \text{ is reflexive on } S) \Rightarrow R' \subseteq R''. \end{aligned}$$

**Proposition:**

$$\forall S, R : R \subseteq S \times S \Rightarrow \text{reflexive}_S(R) = R \cup \{\langle x, x \rangle : x \in S\}.$$

Add reflexivity to relation.

## Transitive Closure

**Definition:** The **transitive closure** of  $R$  on  $S$  is the smallest relation that contains  $R$  and is transitive on  $S$ :

$$\begin{aligned} \text{transitive}_S(R) := \\ \text{such } R' \subseteq S \times S : \\ R \subseteq R' \wedge R' \text{ is transitive on } S \wedge \\ \forall R'' : (R \subseteq R'' \wedge R'' \text{ is transitive on } S) \Rightarrow R' \subseteq R''. \end{aligned}$$

Add transitivity to relation (how?).

## Reachability and Edge Relation

**Proposition:** We define the reachability relation

$$R_G := \{ \langle x, y \rangle \in G_0 \times G_0 : y \text{ is reachable from } x \text{ in } G \}.$$

Then, for any directed graph  $\langle V, E \rangle$ ,  $R_{\langle V, E \rangle}$  is the reflexive and transitive closure of  $E$  on  $V$ :

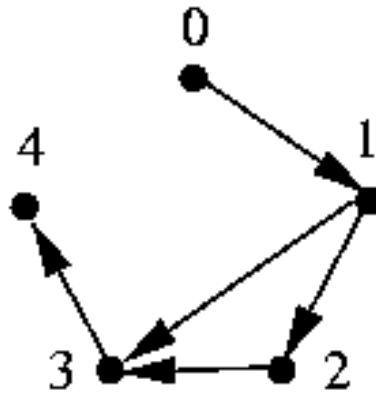
$$\begin{aligned} \forall V, E : \langle V, E \rangle \text{ is directed graph} &\Rightarrow \\ R_{\langle V, E \rangle} &= \text{reflexive}_V(\text{transitive}_V(E)). \end{aligned}$$

Problem reduced to computing the transitive closure of edge relation.



## Example

Graph  $\langle \mathbb{N}_5, E \rangle$  where  $E = \{\langle 0, 1 \rangle, \langle 1, 2 \rangle, \langle 1, 3 \rangle, \langle 2, 3 \rangle, \langle 3, 4 \rangle\}$



$$\text{reflexive}_{\mathbb{N}_5}(E) = E \cup \{\langle 0, 0 \rangle, \langle 1, 1 \rangle, \langle 2, 2 \rangle, \langle 3, 3 \rangle, \langle 4, 4 \rangle\}$$

$$\text{transitive}_{\mathbb{N}_5}(E) = \{\langle 0, 1 \rangle, \langle 0, 2 \rangle, \langle 0, 3 \rangle, \langle 0, 4 \rangle, \langle 1, 2 \rangle, \langle 1, 3 \rangle, \langle 1, 4 \rangle, \langle 2, 3 \rangle, \langle 2, 4 \rangle\}$$

## Exponentiation of Relations

Definition:

$$R_S^0 := \{\langle x, x \rangle : x \in S\}$$
$$R_S^{i+1} := R_S^i \circ R.$$

- $R_S^0$  is the identity relation.
- $R_S^1$  is  $R$ .
- $R_S^3 = R \circ R \circ R$ .

Repeated composition of relation.

## Transitive Closure

Proposition:

$$\forall S, R : R \subseteq S \times S \Rightarrow \\ \text{transitive}_S(R) = \bigcup \{R_S^i : i \in \mathbb{N}_{>0}\}$$

Interpretation: Transitive closure is limit of

$$[R, R \cup (R \circ R), R \cup (R \circ R) \cup (R \circ R \circ R), \dots]$$

Problem: cannot compute infinite sequence!

## Transitive Closure

**Proposition:** Let  $R$  be a binary relation on  $S$  where  $S$  has  $n$  elements. Then  $\bigcup_{1 \leq i \leq n} R_S^i$  is the transitive closure of  $R$ :

$$\begin{aligned} \forall S, R : R \subseteq S \times S &\Rightarrow \\ \text{transitive}_S(R) &= \bigcup_{1 \leq i \leq n} R_S^i \\ \textbf{where } n &= |S|. \end{aligned}$$

**Interpretation:** Transitive closure is limit of

$$[R, R \cup (R \circ R), \dots, R \cup (R \circ R) \cup \dots \cup R^n]$$

Constructive method for computing transitive closure.

## Reachability

Algorithm:

```
reachability( $V, E$ ) :  
   $n = |V|$   
   $R^0 = \{\langle x, x \rangle : x \in V\}$   
  for ( $i = 0; i < n; i++$ )  
     $R^{i+1} = R^i \cup (R^i \circ E)$   
  return  $R^n$ 
```

Can compute reachability relation from edge relation.

## Composition of Relations

Let  $R$  and  $S$  be binary relations on  $\mathbb{N}_n$  for some  $n \in \mathbb{N}$ .

The composition of  $R$  and  $S$  is

$$R \circ S = \{ \langle a, c \rangle : a \in \mathbb{N}_n \wedge c \in \mathbb{N}_n \wedge (\exists b : \langle a, b \rangle \in R \wedge \langle b, c \rangle \in S) \}.$$

For the corresponding adjacency matrix, we thus have

$$\forall i \in \mathbb{N}_n, j \in \mathbb{N}_n :$$

$$\text{adjacency}(\langle \mathbb{N}_n, R \circ S \rangle)_{i,j} = \text{true} \Leftrightarrow$$

$$\exists k \in \mathbb{N}_n : A_{i,k} = \text{true} \wedge B_{k,j} = \text{true}$$

$$\textbf{where } A = \text{adjacency}(\langle \mathbb{N}_n, R \rangle), B = \text{adjacency}(\langle \mathbb{N}_n, S \rangle).$$

## Composition of Relations

Written as a Java method, the composition of two adjacency matrices  $A$  and  $B$  giving a result matrix  $C$  resembles matrix multiplication:

```
void compose(int n, boolean[][] A, boolean[][] B, boolean[][] C)
{
    for (int i=0; i<n; i++)
        for (int j=0; j<n; j++)
            {
                C[i][j] = false;
                for (int k=0; k<n; k++)
                    C[i][j] = C[i][j] || (A[i][k] && B[k][j]);
            }
}
```

# Trees



## Tree

**Definition:** A **tree** is a directed graph such that there is exactly one node, the **root**, that has indegree zero, every other node has indegree one, and every node can be reached from the root.

$T$  is tree  $:\Leftrightarrow$

$T$  is directed graph  $\wedge$

$(\exists r \in V : \text{indeg}(r) = 0 \wedge$

$\forall x \in V - \{r\} :$

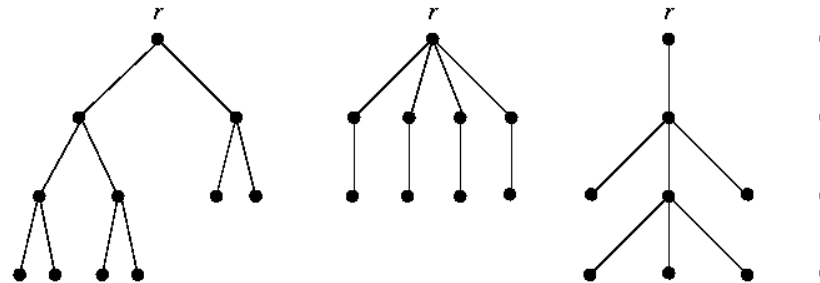
$\text{indeg}(x) = 1 \wedge$

$x$  is reachable from  $r$  in  $T$ ) **where**  $V = T_0$ .

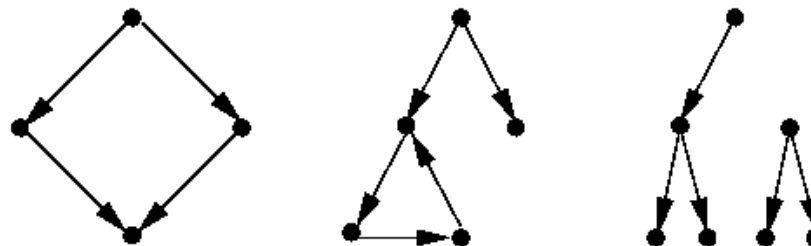
$\text{root}(T) := (\mathbf{such} \ r \in V : \text{indeg}(r) = 0) \mathbf{where} \ V = T_0$ .

## Example

- The following diagrams depict trees with root  $r$ :

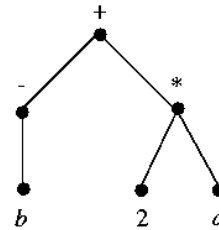


- The following directed graphs are **not** trees:



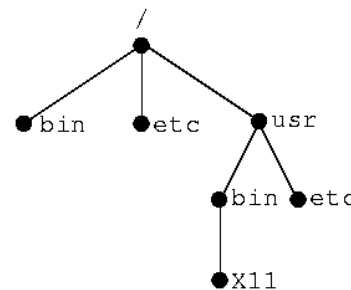
## Example

- The term  $-b + 2a$ :



- A file system with directories

`/, /bin, /etc, /usr, /usr/bin, /usr/bin/X11, /usr/etc`



## Trees and Cycles

**Proposition:** A tree has only cycles of length 0:

$$\forall T : T \text{ is tree} \Rightarrow \\ \neg(\exists p : p \text{ is path in } T \wedge \text{length}(p) > 0 \wedge p \text{ is cycle}).$$

No (non-trivial) path in a tree is a cycle.

## Parents and Children

**Definition:** Let  $T$  be a tree. A node  $y$  is called a **child** of  $x$  if there is an edge from  $x$  to  $y$  in  $T$ :

$$y \text{ is child of } x \text{ in } T :\Leftrightarrow \\ \langle x, y \rangle \in E \text{ where } E = T_1.$$

$x$  is then called the **parent** of  $y$ :

$$\text{parent}_T(y) := \text{such } x \in V : \langle x, y \rangle \in E \\ \text{where } V = T_0, E = T_1.$$

Every node (apart from the root) has a unique parent.

## Other Tree Relations

**Definition:** A node  $x$  is a **leaf**, if it does not have children:

$$x \text{ is leaf in } T :\Leftrightarrow x \in V \wedge \neg \exists y : y \text{ is child of } x \text{ in } T$$

**where**  $V = T_0$ .

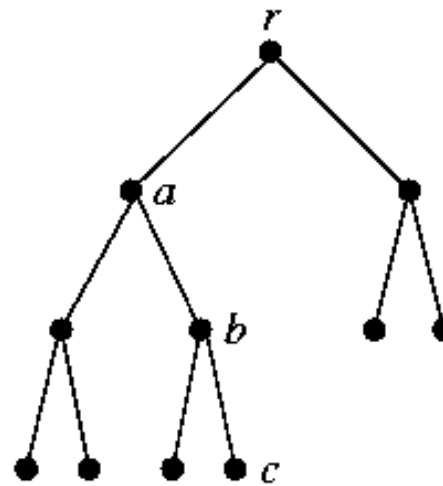
A node  $x$  is an **ancestor** of  $y$  if there is a path from  $x$  to  $y$  in  $T$ :

$$x \text{ is ancestor of } y \text{ in } T :\Leftrightarrow$$
$$\exists p : p \text{ is path in } T \wedge p \text{ is path from } x \text{ to } y.$$

$y$  is then called a **descendant** of  $x$ :

$$y \text{ is descendant of } x \text{ in } T :\Leftrightarrow x \text{ is ancestor of } y \text{ in } T.$$

## Example



$a$  is the parent of  $b$  and an ancestor of leaf  $c$ .

## Levels and Heights

**Definition:** The **level** of a node  $x$  in a tree is the length of the path from the root of the tree to  $x$ :

$$\text{level}_T(x) := \text{length}(p) \text{ **where** } p = \\ \text{ **such** } p : p \text{ is path in } T \wedge p \text{ is path from root}(T) \text{ to } x.$$

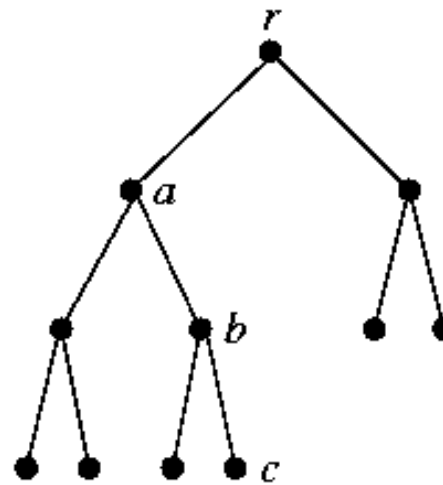
The **height** of a tree is the maximum level of its nodes:

$$\text{height}(T) := \max\{\text{level}_T(x) : x \in V\} \text{ **where** } V = T_0.$$

Root has level 0; level of every other node is one plus the parent level.



## Example



$a$  has level 1,  $b$  has level 2,  $c$  has level 3. The height of the tree is 3.

## Binary Trees

**Proposition:** Let  $T$  be a tree of height  $h$  where every node has an outdegree of at most 2. The number of tree nodes is less than  $2^{h+1}$ :

$$\forall T : (T \text{ is tree} \wedge \forall x \in V : \text{outdeg}(x) \leq 2) \Rightarrow |V| < 2^{h+1}$$

**where**  $V = T_0, h = \text{height}(T)$ .

**Proof:** Let  $T$  be a such a tree. We proceed by complete induction on the height of  $T$ .

1. Assume the height is  $h = 0$ . Then  $|V| = 1 < 2 = 2^{h+1}$ .
2. Assume the height is  $h > 0$ . Consequently the root of  $T$  has a child that is the root of a tree of height  $h - 1$  and possibly a second child that is the root of a tree of height less than or equal  $h - 1$ . By the induction hypothesis, we thus have

$$|V| \leq 1 + (2^h - 1) + (2^h - 1) = 2^{h+1} - 1 < 2^{h+1}.$$

## Summary

- Directed graphs
  - Pair of node set and edge relation.
  - Adjacency matrix.
  - Degree.
- Paths and reachability
  - Closure of relations.
  - Reachability is closure of edge relation.
- Trees
  - Root, parent, children.
  - Levels and heights.