## Introduction to Unification Theory Speeding Up

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### Improving the Recursive Descent Algorithm

Improvement 1: Linear Space, Exponential Time

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- Improvement 2. Linear Space, Quadratic Time
- Improvement 3. Almost Linear Algorithm

#### Unification via $\mathcal{U}$ : Exponential in Time and Space

#### Example

Unifying s and t, where

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$
  
$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

will create an mgu where each  $x_i$  and each  $y_i$  is bound to a term with  $2^{i+1} - 1$  symbols:

$$\{ x_1 \mapsto f(x_0, x_0), x_2 \mapsto f(f(x_0, x_0), f(x_0, x_0)), \dots, \\ y_0 \mapsto x_0, y_1 \mapsto f(x_0, x_0), y_2 \mapsto f(f(x_0, x_0), f(x_0, x_0)), \dots \}$$

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Can we do better?

### Unification via $\mathcal{U}$ : Exponential in Time and Space

First idea: Use triangular substitutions.

#### Example

Triangular unifier of s and t from the previous example:

$$[y_0 \mapsto x_0; y_n \mapsto f(y_{n-1}, y_{n-1}); y_{n-1} \mapsto f(y_{n-2}, y_{n-2}); \dots]$$

- Triangular unifiers are not larger than the original problem.
- However, it is not enough to rescue the algorithm:
  - Substitutions have to be applied to terms in the problem, that leads to duplication of subterms.
  - In the example, unifying x<sub>n</sub> and y<sub>n</sub>, which by then are bound to terms with 2<sup>n+1</sup> − 1 symbols, will lead to exponential number of decompositions.

### Unification via $\mathcal{U}$ : Exponential in Time and Space

- Problem: Duplicate occurrences of the same variable cause the explosion in the size of terms.
- Fix: Represent terms as graphs which share subterms.

#### Term Dag

A term dag is a directed acyclic graph such that

- its nodes are labeled with function symbols or variables,
- its outgoing edges from any node are ordered,
- outdegree of any node labeled with a symbol *f* is equal to the arity of *f*,

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nodes labeled with variables have outdegree 0.

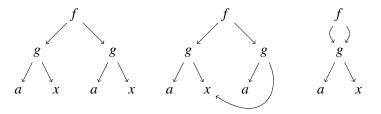
- Convention: Nodes and terms the term dags represent will not be distinguished.
- Example: "node" f(a, x) is a node labeled with f and having two arcs to a and to x.

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The only difference between various dags representing the same term is the amount of structure sharing between subterms.

#### Example

Three representations of the term f(g(a,x),g(a,x)):



- It is possible to build a dag with unique, shared variables for a given term in O(n \* log(n)) where n is the number of symbols in the term.
- There are subtle variations that can improve this result to O(n).
- Assumption for the algorithm we plan to consider:
  - The input is a term dag representing the two terms to be unified, with unique, shared occurrences of all variables.

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Representing substitutions involving only subterms of a term dag:

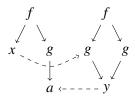
- Directly by a relation on the nodes of the dag, either
  - stored explicitly as a list of pairs, or
  - by storing a link ("substitution arcs") in the graph itself, and maintaining a list of variables (nodes) bound by the substitution.

Substitution application.

 Implicit: Identifies two nodes connected with a substitution arc, without actually moving any of the subterm links.

#### Example

A term dag for the terms f(x,g(a)) and f(g(y),g(y)), with the implicit application of their mgu  $\{x \mapsto g(a), y \mapsto a\}$ .



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 With implicit application, the binding for a variable can be determined by traversing the graph depth first, left to right.

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# Improvement 1: Linear Space, Exponential Time

Assumptions:

- Dags consist of nodes.
- Any node in a given dag defines a unique subdag (consisting of the nodes which can be reached from this node), and thus a unique subterm.
- Two different types of nodes: variable nodes and function nodes.
- Information at function nodes:
  - The name of the function symbol.
  - The arity n of this symbol.
  - The list (of length n) of successor nodes (corresponds to the argument list of the function)
- Both function and variable nodes may be equipped with one extra pointer (dashed arrow in diagrams) to another node.

#### ▶ Find:

Takes a node of a dag as input, and follows the additional pointers until it reaches a node without such a pointer. This node is the output of Find.

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#### Example

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#### Example

- Find(3)=(3)
- ▶ Find(2)=

 $f_{(1)}$   $f_{(4)}$ / \ \_ \_ · · \ ( )  $x_{(2)} a_{(3)} y_{(5)}$ 

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 $f_{(1)}$   $f_{(4)}$ x<sub>(2)</sub> a<sub>(3)</sub> y<sub>(5)</sub>

#### Union:

Takes as input a pair of nodes u, v that do not have additional pointers and creates such a pointer from u to v.

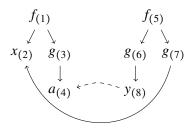
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#### Occur:

Takes as input a variable node u and another node v (both without additional pointers) and performs the occur check, i.e. it tests whether the variable is contained in the term corresponding to v. The test is performed on the virtual term expressed by the additional pointer structure, i.e. one applies Find to all nodes that are reached during the test.

▶ Occur

Example



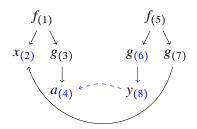
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Example

• Occur(2,6)=False



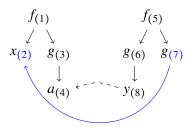
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▶ Occur

#### Example

- Occur(2,6)=False
- Occur(2,7)=True



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Input: A pair of nodes k<sub>1</sub> and k<sub>2</sub> in a dag
Output: *True* if the terms corresponding to k<sub>1</sub> and k<sub>2</sub> are unifiable. *False* Otherwise.
Side Effect: A pointer structure which allows to read off an mgu and the unified term.

**Procedure** Unify1. Unification of term dags. (Continues on the next slide)

Unifyl  $(k_1, k_2)$ 

if  $k_1 = k_2$  then return *True* 

/\* Trivial \*/

#### else

if function-node( $k_2$ ) then |  $u := k_1; v := k_2$ else |  $u := k_2; v := k_1$ end

/\* Orient \*/

#### Procedure Unify1. Unification of term dags. (Continues on the next slide)

```
if variable-node(u) then
   if Occurs (u, v)
                                         /* Occur-check */
    then
    return False
   else
      Union(u,v)
                                   /* Variable elimination */
      return True
   end
else if function-symbol(u) \neq function-symbol(v)
then
   return False
                                         /* Symbol clash */
```

Procedure Unify1. Unification of term dags. Continued. (Continues on the next slide)

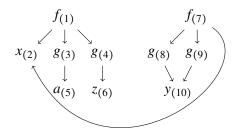
#### else

```
n := arity(function-symbol(u))
(u_1,\ldots,u_n) \coloneqq \mathsf{succ-list}(u)
(v_1,\ldots,v_n) \coloneqq succ-list(v)
i := 0; bool := True
while i < n and bool do
    i := i + 1; bool := Unify1(Find(u_i), Find(v_i))
     / * Decomp. */
end
return bool
```

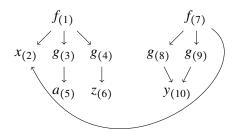
Procedure Unify1. Unification of term dags. Finished.

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- Unify f(x,g(a),g(z)) and f(g(y),g(y),x).
- First, create dags.
- Numbers indicate nodes.



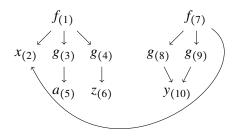
Algorithm run starts with Unify1(1,7) and continues:



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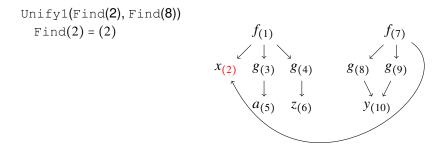
Algorithm run starts with Unify1(1,7) and continues:

Unify1(Find(2), Find(8))



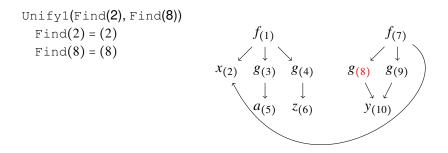
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Algorithm run starts with Unify1(1,7) and continues:



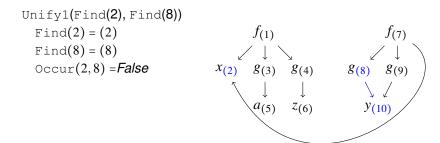
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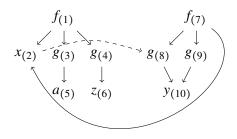
Algorithm run starts with Unify1(1,7) and continues:



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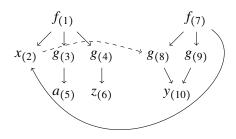
```
Unify1(Find(2), Find(8))
Find(2) = (2)
Find(8) = (8)
Occur(2,8) =False
Union(2,8)
```



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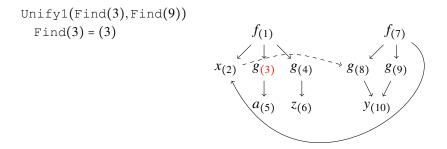
Algorithm run starts with Unify1(1,7) and continues:

Unify1(Find(3),Find(9))



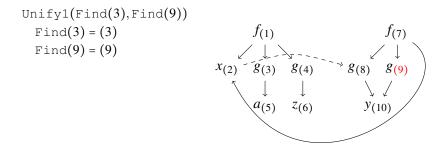
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Algorithm run starts with Unify1(1,7) and continues:



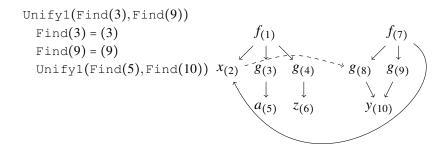
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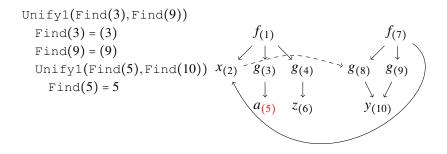
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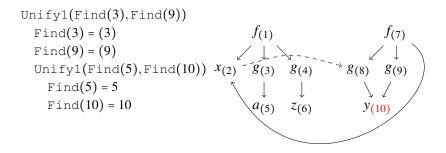
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Algorithm run starts with Unify1(1,7) and continues:



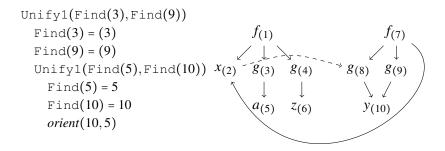
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Algorithm run starts with Unify1(1,7) and continues:



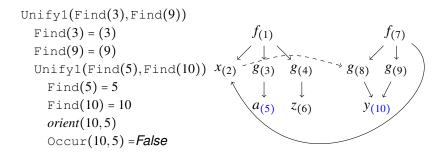
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Algorithm run starts with Unify1(1,7) and continues:



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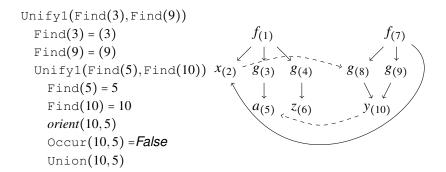
Algorithm run starts with Unify1(1,7) and continues:



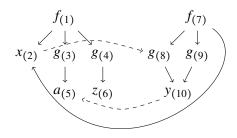
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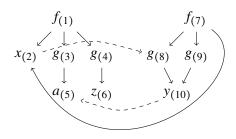


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Algorithm run starts with Unify1(1,7) and continues:

Unify1(Find(4),Find(2))



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Algorithm run starts with Unify1(1,7) and continues:

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Algorithm run starts with Unify1(1,7) and continues:

```
Unify1(Find(4), Find(2))

Find(4) = 4

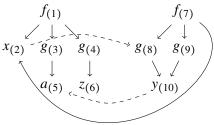
Find(2) = 8

x_{(2)} = g_{(3)} = g_{(4)} = g_{(8)} = g_{(9)} = g_{(1)} = g_{(3)} = g_{(4)} = g_{(8)} = g_{(9)} = g_{(1)} = g_{(1)} = g_{(1)} = g_{(2)} = g_{(2)} = g_{(3)} = g_{(3)} = g_{(4)} = g_
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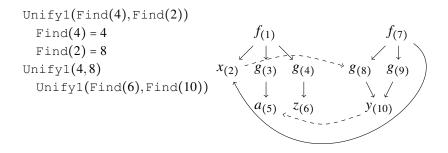
Algorithm run starts with Unify1(1,7) and continues:

```
Unify1(Find(4),Find(2))
Find(4) = 4
Find(2) = 8
Unify1(4,8)
```

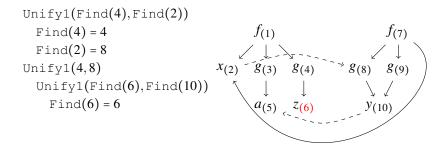


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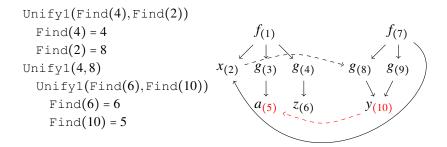
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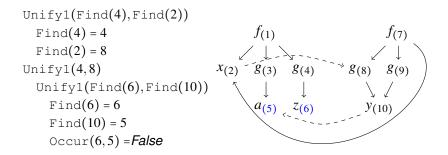
Algorithm run starts with Unify1(1,7) and continues:



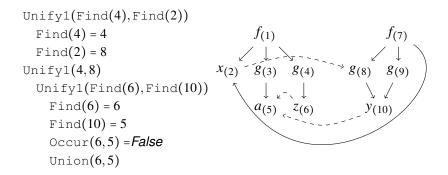
Algorithm run starts with Unify1(1,7) and continues:



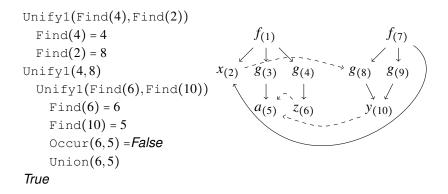
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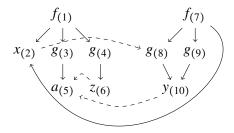


Algorithm run starts with Unify1(1,7) and continues:



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# Unification of Term Dags. Example 1 (Cont.)



- From the final dag one can read off:
  - The unified term f(g(a), g(a), g(a)).
  - The mgu in triangular form  $[x \mapsto g(y); y \mapsto a; z \mapsto a]$ .
- No new nodes. Only one extra pointer for each variable node.
- Needs linear space.
- Time is still exponential. See the next example.

Consider again the problem  $s \doteq t$ , where

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$
  
$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to  $x_n$  and  $y_n$ :

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$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to  $x_n$  and  $y_n$ :

$$\begin{array}{cccc} x_n & - \rightarrow f & f & f & \langle - & y_n \\ & & & & \langle & \rangle \\ & & & & \chi_{n-1} & \rightarrow f & f & f & \langle - & y_{n-1} \\ & & & & & \\ & & & & & \chi_1 & - \rightarrow f & f & \langle - & - & y_1 \\ & & & & & & \\ & & & & & & \chi_0 & & y_0 \end{array}$$

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A dag representation of the term bound to  $x_n$  and  $y_n$ :

$$\begin{array}{cccc} x_n & - & \rightarrow f & & f \leftarrow - & y_n \\ \begin{pmatrix} & & \\ & &$$

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A dag representation of the term bound to  $x_n$  and  $y_n$ :

$$\begin{array}{cccc} x_n & - \rightarrow f & f & \langle - y_n \\ & \langle \rangle & & \langle \rangle \\ x_{n-1} & \rightarrow f & f & \langle - y_{n-1} \\ & \vdots & & \vdots \\ & x_1 & - \rightarrow f & f & \langle - - y_1 \\ & \langle \rangle & & \langle \rangle \\ & & x_0 & y_0 \end{array}$$

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A dag representation of the term bound to  $x_n$  and  $y_n$ :

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A dag representation of the term bound to  $x_n$  and  $y_n$ :

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Consider again the problem  $s \doteq t$ , where

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## Unification of Term Dags: Correctness

<code>Unify1</code> can be simulated by  $\mathcal U$  such that

- If the call to Unify1 ends in failure, then the corresponding transformation sequence in U ends in 1.
- If the call to Unify1 terminates with success, with a substitution *σ* read from the pointer structure, then the corresponding transformation sequence *U* ends in Ø; *S* where *σ<sub>S</sub>* = *σ*.

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# Unification of Term Dags: Complexity

- Linear space: terms are not duplicated anymore.
- Exponential time: Calls Unify1 recursively exponentially often.

# Unification of Term Dags: Complexity

- Linear space: terms are not duplicated anymore.
- Exponential time: Calls Unify1 recursively exponentially often.
- Fortunately, with an easy trick one can make the running time quadratic.
- Idea: Keep from revisiting already-solved problems in the graph.
- The algorithm of Corbin and Bidoit:
  - J. Corbin and M. Bidoit.

A rehabilitation of Robinson's unification algorithm. In R. Mason, editor, *Information Processing 83*, pages 909–914. Elsevier Science, 1983.

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Improvement 2. Linear Space, Quadratic Time

Input: A pair of nodes k<sub>1</sub> and k<sub>2</sub> in a dag.
Output: *True* if the terms corresponding to k<sub>1</sub> and k<sub>2</sub> are unifiable. *False* Otherwise.
Side Effect: A pointer structure which allows to read off an mgu and the unified term.

#### Procedure Unify2. Quadratic Algorithm.

(No difference from Unify1 so far. Continues on the next slide)

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# **Quadratic Algorithm**

Unify2  $(k_1, k_2)$ 

if  $k_1 = k_2$  then return *True* 

/\* Trivial \*/

#### else

if function-node( $k_2$ ) then |  $u := k_1; v := k_2$ else |  $u := k_2; v := k_1$ end

/\* Orient \*/

#### **Procedure** Unify2. Quadratic Algorithm. (No difference from Unify1 so far. Continues on the next slide)

# **Quadratic Algorithm**

**Procedure** Unify2. Quadratic Algorithm. Continued. (No difference from Unify1 so far. Continues on the next slide)

# **Quadratic Algorithm**

```
else
   n := arity(function-symbol(u))
   (u_1,\ldots,u_n) \coloneqq succ-list(u)
   (v_1,\ldots,v_n) \coloneqq succ-list(v)
   i := 0: bool := True
   Union(U,V)
   while i < n and bool do
       i := i + 1; bool := Unify2(Find(u_i), Find(v_i))
         / * Decomp. * /
   end
    return bool
```

**Procedure** Unify2. Quadratic Algorithm. Finished. (The only difference from Unify1 is Union(u,v).)

The same example that revealed exponential behavior of RDA:

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# Why is it Quadratic?

- The algorithm is quadratic in the number of symbols in original terms:
  - Each call of Unify2 either returns immediately, or makes one more node unreachable for the Find operation.
  - Therefore, there can be only linearly many calls of Unify2.
  - Quadratic complexity comes from the fact that Occur and Find operations are linear.

## Improvement 3. Almost Linear Algorithm

How to eliminate two sources of nonlinearity of Unify2?

- Occur: Just omit the occur check during the execution of the algorithm.
  - · Consequence: The data structure may contain cycles.
  - Since the occur-check failures are not detected immediately, at the end an extra check has to be performed to find out whether the generated structure is cyclic or not.
  - Detecting cycles in a directed graph can be done by linear search.
- Find: Use more efficient union-find algorithm from
  - 🔋 R. Tarjan.

Efficiency of a good but not linear set union algorithm.

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J. ACM, 22(2):215–225, 1975.

- Collapsing-find:
  - Like Find it takes a node k of a dag as input, and follows the additional pointers until the node Find(k) is reached.
  - In addition, Collapsing-find relocates the pointer of all the nodes reached during this process to Find(k).

Example

- Collapsing-find:
  - Like Find it takes a node k of a dag as input, and follows the additional pointers until the node Find(k) is reached.
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#### Example

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- ► CF(3)=(3)
- ► CF(2)=

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$$\begin{array}{cccc}
f_{(1)} & f_{(4)} \\
\swarrow & & & & \\
x_{(2)} & a_{(3)} & & & y_{(5)} \\
& & & & & \\
\end{array}$$

- Union-with-weight:
  - Takes as input a pair of nodes u, v that do not have additional pointers.
  - If the set {k | Find(k) = u} larger than the set {k | Find(k) = v} then it creates an additional pointer from v to u.
  - Otherwise, it creates an additional pointer from u to v.
  - Hence, the link is created from the smaller tree to the larger one, increasing the path to the root (the result of Find) for fewer nodes.

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Weighted union does not apply when we have a variable node and a function node.

## Almost Linear Algorithm

One more auxiliary procedure:

- Not-cyclic:
  - Takes a node k as input, and tests the graph which can be reached from k for cycles.
  - The test is performed on the virtual graph expressed by the additional pointer structure, i.e. one first applies
     Collapsing-find to all nodes that are reached during the test.

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**Input:** A pair of nodes  $k_1$  and  $k_2$  in a directed graph. **Output:** *True* if  $k_1$  and  $k_2$  correspond unifiable terms. *False* Otherwise.

# Side Effect: A pointer structure which allows to read off an mgu and the unified term.

```
Unify3 (k_1, k_2)

if Cyclic-unify (k_1, k_2) and Not-cyclic (k_1) then

| return True

else

| return False

end
```

Procedure Unify3. Almost Linear Algorithm. (Continues on the next slide)

```
Cyclic-unify (k_1, k_2)
if k_1 = k_2 then return True
                                                        /* Trivial */
else
   if function-node(k_2) then
| u := k_1; v := k_2
   else
u := k_2; v := k_1
                                                        /* Orient */
   end
                     Procedure Cyclic-unify.
```

(Continues on the next slide)

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```
if variable-node(u) then
    if variable-node(v) then
        Union-with-weight(u,v)
    else
        Union(u,v); /* No occur-check. Variable elimination */
        return True
    end
else if function-symbol(u) ≠ function-symbol(v) then
    return False; /* Symbol clash */
```

**Procedure** Cyclic-unify. (Continues on the next slide)

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```
else
   n := arity(function-symbol(u))
   (u_1,\ldots,u_n) \coloneqq succ-list(u)
   (v_1,\ldots,v_n) \coloneqq succ-list(v)
   i := 0; bool := True
   Union-with-weight (U,V)
   while i < n and bool do
       i := i + 1
       bool :=
         Cyclic-unify(Collapsing-find(u_i)
            Collapsing-find(v_i) /* Decomposition */
   end
   return bool
```

Procedure Cyclic-unify. Finished.

The algorithm is very similar to the one described in Gerard Huet's thesis:

G. Huet.
 Résolution d'Équations dans des Langages d'ordre 1, 2, ..., ω.
 Thèse d'État, Université de Paris VII, 1976.

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  - Each call of Cyclic-unify either returns immediately, or makes one more node unreachable for the Collapsing-find operation.
  - Therefore, there can be only linearly many calls of Cyclic-unify.
  - A sequence of *n* Collapsing-find and Union-with-weight operations can be done in  $O(n * \alpha(n))$  time, where  $\alpha$  is an extremely slowly growing function (functional inverse of Ackerman's function) never exceeding 5 for practical input.

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  - A sequence of *n* Collapsing-find and Union-with-weight operations can be done in  $O(n * \alpha(n))$  time, where  $\alpha$  is an extremely slowly growing function (functional inverse of Ackerman's function) never exceeding 5 for practical input.
  - The use of nonoptimal Union can increase the time complexity at most by a summand O(m) where m is the number of different variable nodes.

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  - Each call of Cyclic-unify either returns immediately, or makes one more node unreachable for the Collapsing-find operation.
  - Therefore, there can be only linearly many calls of Cyclic-unify.
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  - Hence, complexity of Unify3 is O(n \* α(n)).

#### Implementation: Matching vs. Unification

 Unlike matching, efficient unification algorithms require sophisticated data structures.

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 When efficiency is an issue, matching should be implemented separately from unification.

#### Summary

- Recursive Descent Algorithm for unification is exponential in time and space.
- Using term dags reduces space complexity to linear.
- Making the union pointer between function nodes before unifying their arguments reduces time complexity to quadratic.

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 Using collapsing-find and union-with-weight further reduces time complexity to almost linear.