## Rewriting Part 5. Confluence of Term Rewriting Systems

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## Confluence Is Undecidable

The following problem is undecidable:

Given: A finite TRS R. Question: Is R confluent or not?

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Proof.

Idea:

- Given a set of identities E such that  $Var(l) \approx Var(l)$  for all  $l \approx r \in E$ , l and r not being variables.
- ► Construct a TRS whose confluence problem is equivalent to the ground word problem for *E*.
- Undecidability of the ground word problem for E (see e.g. Example 4.1.4 from the book of Baader and Nipkow) will imply undecidability of the confluence problem.

## Confluence Is Undecidable

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Given: A finite TRS R. Question: Is R confluent or not?

Proof.

Construction of a TRS:

- 1.  $R := E \cup E^{-1}$  is a confluent TRS.
- 2.  $R_{st} := R \cup \{a \to s, a \to t\}$ , where s and t are given ground terms and a is a new constant.
- 3.  $R_{st}$  is confluent iff  $s \approx_E t$ .

Hence, the ground word problem for E reduces to the confluence problem for  $R_{s,t}$ .

## A Decidable Subcase

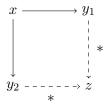
#### Theorem 5.1

For terminating TRSs, confluence is decidable.

Proof idea:

- By Newman's lemma, if a TRS is terminating and locally confluent, then it is confluent.
- To prove the theorem, we need to prove that local confluence is decidable for terminating TRSs.

Local confluence:



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To test for local confluence of  $\rightarrow_R$ , consider reductions:

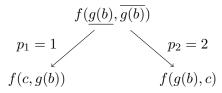
$$\begin{array}{c} l_1 \to r_1 \swarrow s \\ t_1 & t_2 \end{array} \xrightarrow{s} l_2 \to r_2 \\ t_2 & t_2 \end{array}$$

That means, there are rules  $l_1 \rightarrow r_1, l_2 \rightarrow r_2 \in R$ , positions  $p_1, p_2 \in \mathcal{P}os(s)$ , and substitutions  $\sigma_1, \sigma_2$  such that

• 
$$s|_{p_1} = \sigma_1(l_1)$$
 and  $t_1 = s[\sigma_1(r_1)]_{p_1}$ .  
•  $s|_{p_2} = \sigma_2(l_2)$  and  $t_2 = s[\sigma_2(r_2)]_{p_2}$ .

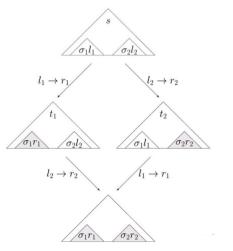
Consider several cases, depending on the relative positions of  $p_1$  and  $p_2$ .

Case 1:  $p_1$  and  $p_2$  are parallel positions. Example:  $R := \{f(a, g(x)) \rightarrow f(x, x), g(b) \rightarrow c\}$ Peak:



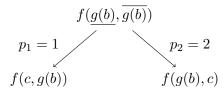
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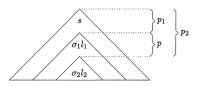


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Joinability:

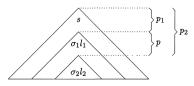
$$\begin{aligned} &f(c,\underline{g(b)}) \to f(c,c) \\ &f(\underline{g(b)},c) \to f(c,c) \end{aligned}$$

Case 2: One position is a prefix of another. Say,  $p_1$  is a prefix of  $p_2$ :  $p_2 = p_1 p$  for some p.

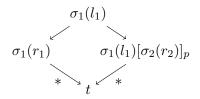


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Case 2: One position is a prefix of another. Say,  $p_1$  is a prefix of  $p_2$ :  $p_2 = p_1 p$  for some p.



We restrict our attention to  $\sigma_1(l_1)$ , because



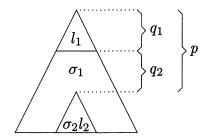
 $\text{implies } s[\sigma_1(r_1)]_{p_1} \xrightarrow{*} s[t] \xleftarrow{*} s[\sigma_1(l_1)[\sigma_2(r_2)]_p]_{p_1} = s[\sigma_2(r_2)]_{p_2}.$ 

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Case 2.1: The redex  $\sigma_2(l_2)$  does not overlap with  $l_1$  itself, but is contained in  $\sigma_1$ .

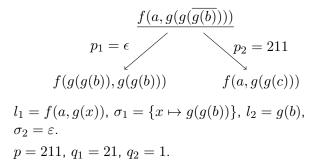
 $p = q_1 q_2$  such that  $q_1$  is a variable position in  $l_1$ .

 $\sigma_1(l_1)$  has the form:



Non-critical overlap.

Case 2.1: The redex  $\sigma_2(l_2)$  does not overlap with  $l_1$  itself, but is contained in  $\sigma_1$ .  $p = q_1q_2$  such that  $q_1$  is a variable position in  $l_1$ . Example:  $R := \{f(a, g(x)) \rightarrow f(x, x), g(b) \rightarrow c\}$ Peak:



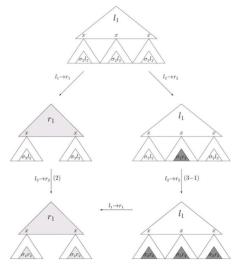
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 $p = q_1q_2$  such that  $q_1$  is a variable position in  $l_1$ .

#### Outcome: The reducts are joinable.

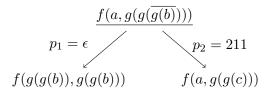
The analysis is complicated by the fact that  $x = l_1|_{q_1}$ may occur repeatedly both in  $l_1$  and  $r_1$ .

Case 2.1: Instance: x appears three times in  $l_1$  and twice in  $r_1$ .



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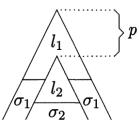
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The reducts are joinable.

$$\begin{split} &f(g(g(b)),g(g(b)) \xrightarrow{2} f(g(c),g(c)). \\ &f(a,g(g(c))) \to f(g(c),g(c)). \end{split}$$

Case 2.2: Two left-hand sides  $l_1$  and  $l_2$  overlap.  $p \in \mathcal{P}os(l_1), \ l_1|_p$  is not a variable, and  $\sigma_1(l_1|_p) = \sigma_2(l_2).$  $\sigma_1(l_1)$  has the form:

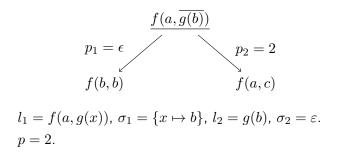


Critical overlap.

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 $p \in \mathcal{P}os(l_1)$ ,  $l_1|_p$  is not a variable, and  
 $\sigma_1(l_1|_p) = \sigma_2(l_2)$ .

In the case of critical overlap, local confluence need not hold.

 $\mbox{Example: } R \ := \ \{f(a,g(x)) \rightarrow f(x,x), \ g(b) \rightarrow c\}$ 



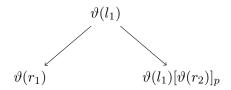
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- Problem: Critical overlaps must be checked for local confluence. How to do that?
  - Answer: It is enough to check finitely many critical pairs.

#### Definition 5.1

Let

- ▶  $l_1 \rightarrow r_1$  and  $l_2 \rightarrow r_2$  be two rules which do not share variables,
- $p \in \mathcal{P}os(l_1)$  be a position such that  $l_1|_p$  is not a variable, and
- $\vartheta$  be an mgu of  $l_1|p$  and  $l_2$

Then the pair  $\langle \vartheta(r_1), \vartheta(l_1)[\vartheta(r_2)]_p \rangle$  is called a critical pair.

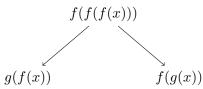


► The critical pairs of a TRS R are the critical pairs between any of two of its renamed rules and are denoted by CP(R).

Includes overlaps of a rule with a renamed copy of itself.

#### Example 5.1

- Let  $R := \{f(f(x)) \rightarrow g(x)\}.$
- $\blacktriangleright$  Take a critical pair between the rule and its renamed copy,  $f(f(x)) \to g(x)$  and  $f(f(y)) \to g(y)$

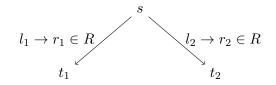


► The terms in the critical pair, g(f(x)) and f(g(x)), are not joinable.

▶ *R* is not locally confluent.

- Hence, local confluence test reduces to checking joinability of critical pairs.
- The analysis of the cases on the previous slides leads to the Critical Pair Lemma.

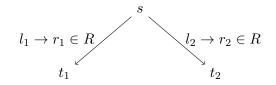
Lemma 5.1 (Critical Pair Lemma) If R is a TRS and



then  $t_1 \downarrow_R t_2$ , or  $t_1 = s[u_1]_{p_1}$  and  $t_2 = s[u_2]_{p_2}$  for some  $p_1, p_2$ , where  $\langle u_1, u_2 \rangle$  or  $\langle u_2, u_1 \rangle$  is an instance of a critical pair of R. Proof.

- When there is no overlap or a non-critical overlap, then  $t_1 \downarrow_R t_2$ .
- ▶ When there is a critical overlap, then  $s|_{p_1} = \sigma(l_1)$  and  $\sigma(l_1|_p) = \sigma(l_2)$ .

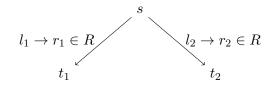
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- ► Hence, σ unifies l<sub>1</sub>|<sub>p</sub> and l<sub>2</sub> and, therefore, is an instance of their mgu ϑ.
- ▶ Therefore,  $\langle \sigma(r_1), \sigma(l_1) [\sigma(r_2)]_p \rangle$  is an instance of the critical pair  $\langle \vartheta(r_1), \vartheta(l_1) [\vartheta(r_2)]_p \rangle$

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Proof (cont.)

► 
$$t_1 = s[\sigma(r_1)]_{p_1}$$
,  $t_2 = s[\sigma(l_1)[\sigma(r_2)]_p]_{p_1}$ ,  $p_2 = p_1 p$ .

#### Theorem 5.2 (Critical Pair Theorem)

A TRS is locally confluent iff all its critical pairs are joinable.

Proof.

( $\Leftarrow$ ) Using the Critical Pair Lemma: Given  $t_i = s[u_i]_p$ , i = 1, 2, where  $\langle u_1, u_2 \rangle$  (wlog) is an instance of some critical pair  $\langle v_1, v_2 \rangle$  under a substitution  $\varphi$ , then  $v_i \stackrel{*}{\to} t$  for some term timplies  $u_i \stackrel{*}{\to} \varphi(t)$  and, hence,  $t_i \stackrel{*}{\to} s[\varphi(t)]_p$ , i = 1, 2.

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- $\begin{array}{l} (\Rightarrow) \mbox{ Every critical pair is the product of a fork} \\ \vartheta(r_1) \leftarrow \vartheta(l_1) \rightarrow \vartheta(l_1) [\vartheta(r_2)]_p. \mbox{ Joinability follows from local confluence.} \end{array}$

#### Theorem 5.2 (Critical Pair Theorem)

A TRS is locally confluent iff all its critical pairs are joinable.

Corollary 5.1

A terminating TRS is confluent iff all its critical pairs are joinable.

- The problem of testing local confluence reduces to critical pair joinability test.
- For terminating TRSs, the problem whether two terms are joinable can be decided.
- ► For finite TRSs, the number of critical pairs is finite.
- Hence, for terminating and finite TRSs local confluence is decidable.
- Therefore, for terminating and finite TRSs confluence is decidable.

Let R be a terminating finite TRS.

Decision procedure:



Let  ${\cal R}$  be a terminating finite TRS.

Decision procedure:

▶ For each pair of rules  $l_1 \rightarrow r_1$  and  $l_2 \rightarrow r_2$  (there are  $|R|^2$  of them) and for every  $p \in \mathcal{P}os(l_1)$  with a nonvariable  $l_1|_p$  (there are at most  $|l_1|$  of them) try to generate critical pairs.

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• It involves unification of  $l_1|_p$  and  $l_2$  (decidable, unitary).

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- For each critical pair  $\langle u_1, u_2 \rangle$ , reduce  $u_i$ , to some *R*-normal form  $\hat{u}_i$ , i = 1, 2.

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- ▶ If  $\hat{u}_1 \neq \hat{u}_2$  for such a pair, we have a non-confluent situation:  $\hat{u}_1 \stackrel{*}{\leftarrow} u_1 \leftarrow u \rightarrow u_2 \stackrel{*}{\rightarrow} \hat{u}_2.$

#### Example 5.2

Recall the TRS  $\{f(f(x)) \rightarrow g(x)\}$ , which is not locally confluent. The only critical pair  $\langle g(f(x)), f(g(x)) \rangle$  is not joinable.

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- ► Rules are to be renamed. Otherwise f(f(x)) and f(x) are not unifiable.
- The critical pair of a rule and (a renamed copy of) itself has to be taken into account. Otherwise all one-rule systems would appear to be locally-confluent.

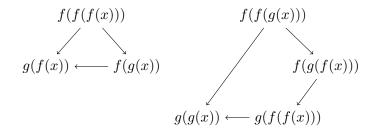
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- The critical pair of a rule and (a renamed copy of) itself has to be taken into account. Otherwise all one-rule systems would appear to be locally-confluent.
- ▶ Critical pairs can be helpful lemmas:  $g(f(x)) \approx_R f(g(x))$  is an interesting consequence of  $f(f(x)) \rightarrow_R g(x)$  which may not be apparent at first sight.

Example 5.3 The TRS  $\{f(f(x)) \rightarrow g(x), f(g(x)) \rightarrow g(f(x))\}$  is locally confluent. Both critical pairs are joinable:



Since the TRS is also terminating (use LPO with f > g), it is also confluent.

- Because critical pairs are equational consequences, adding a critical pair as a new rewrite rule does not change the induced equality.
- If R is a TRS and R' is obtained from R by adding a critical pair as a new rule, then ≈<sub>R</sub> = ≈<sub>R'</sub>.

The idea of adding a critical pair as a new rule is called "completion".