

Introduction to Unification Theory

Higher-Order Unification

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Overview

Introduction

Preliminaries

Higher-Order Unification Procedure

Outline

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- ▶ Higher-order equations.



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- ▶ F : Higher-order variable, appears at functional position.
- ▶ Can be solved, e.g., with the identity function or with the constant function a .
- ▶ Higher-order equations.
- ▶ Solving method: Higher-order unification.



Introduction

- ▶ Higher-order unification is fundamental in automating higher-order reasoning.
- ▶ Used in logical frameworks, logic programming, program synthesis, program transformation, type inferencing, computational linguistics, etc.
- ▶ Much more complicated than first-order unification (undecidable, of type zero, nonterminating, . . .).
- ▶ In this lecture: Introduction to higher-order unification.



Outline

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Preliminaries

Higher-Order Unification Procedure

Simply Typed λ -Calculus

- ▶ Simply type λ -calculus is our term language.
- ▶ In this section: Definitions and elementary properties.
 - ▶ Types
 - ▶ Terms
 - ▶ Substitutions
 - ▶ Reduction
 - ▶ Unification



Types

Types

Consider a finite set whose elements are called *atomic types* (or *base types*). Then:

- ▶ Atomic types are types,
- ▶ If T and U are types then $T \rightarrow U$ is a type.

The expression $T_1 \rightarrow T_2 \rightarrow \cdots \rightarrow T_n \rightarrow U$ is a notation for the type $T_1 \rightarrow (T_2 \rightarrow \cdots \rightarrow (T_n \rightarrow U) \dots)$.



Types

Order of a Type

- ▶ $o(T) = 1$ if T is atomic.
- ▶ $o(T \rightarrow U) = \max\{1 + o(T), o(U)\}$.

Example

Let T_1, T_2, T_3 be atomic types, then

- ▶ $o(T_1 \rightarrow T_2 \rightarrow T_3) = 2$.
- ▶ $o((T_1 \rightarrow T_2) \rightarrow T_3) = 3$.



Terms

Assumptions:

- ▶ Consider finite set of constants.
- ▶ To each constant a type is assigned.
- ▶ For each atomic type there is at least one constant.
- ▶ For each type there is an infinite set of variables.
- ▶ Two different types have disjoint sets of variables.

λ -Terms

- ▶ Constants are terms.
- ▶ Variables are terms.
- ▶ If t and s are terms then $(t s)$ is a term.
- ▶ If x is a variable and t is a term then $\lambda x. t$ is a term.

The expression $(t s_1 \dots s_n)$ is a notation for the term
 $(\dots (t s_1) \dots s_n)$



Terms

- ▶ $\lambda x. t$ is a function where λx is the λ -abstraction and t is the body. Intuitively, it is a function $x \mapsto t$.
- ▶ In $\lambda x. t$, λx is a binder for x in t . Occurrences of x in t are *bound*.
- ▶ $(t s)$ is an application where function t is applied to the argument s .



Terms

Type of a Term

A term t is said to have the type T if either

- ▶ t is a constant of type T ,
 - ▶ t is a variable of type T ,
 - ▶ $t = (r s)$, r has type $U \rightarrow T$ and s has type U for some U ,
 - ▶ $t = \lambda x. s$, the variable x has type U , the term s has type V and $T = U \rightarrow V$.
-
- ▶ A term t is said to be *well-typed* if there exists a type T such that t has type T .
 - ▶ In this case T is unique and it is called *the type of t* .
 - ▶ We consider only well-typed terms.



Order

Order of a Symbol, Language

- ▶ The order of a function symbol or a variable is the order of its type.
- ▶ A language of order n is one which allows function symbols of order at most $n + 1$ and variables of order at most n .

Formalization of the conventions:

- ▶ First order term denotes an individual.
- ▶ Second order term denotes a function on individuals.
- ▶ etc.



Free Variables

- ▶ $vars(t)$: The set of variables occurring in the term t .
- ▶ An occurrence of a variable in a term is *free* if it is not bound.
- ▶ The set of variables that occur freely in t , denoted $fvars(t)$:
 - ▶ $fvars(c) = \emptyset$, where c is a constant.
 - ▶ $fvars(x) = \{x\}$.
 - ▶ $fvars((s r)) = fvars(s) \cup fvars(r)$.
 - ▶ $fvars(\lambda x. s) = fvars(s) \setminus \{x\}$.
- ▶ Closed term: A term without free variables.



Free Variables

Example

- ▶ $fvars(\lambda x. x) = \emptyset$.
(Closed term)
- ▶ $fvars(\lambda x. y) = \{y\}$.
- ▶ $fvars(((\lambda x. x) x)) = \{x\}$.
(x has a bound occurrence as well)



Substitution

- ▶ We reuse the definition of substitution as finite mapping from the previous lectures, but in addition require that it preserves types.
- ▶ Hence, if $x \mapsto t$ is a binding of a substitution, x and t have the same type.
- ▶ The definitions of composition, more general substitution, etc. will also be reused.



Replacement in a Term

Replacement in a Term

Let $\sigma = \{x_1 \mapsto t_1, \dots, x_n \mapsto t_n\}$ be a substitution and t be a term, then the term $t\langle\sigma\rangle$ is defined as follows:

- ▶ $c\langle\sigma\rangle = c$.
- ▶ $x_i\langle\sigma\rangle = t_i$.
- ▶ $x\langle\sigma\rangle = x$, if $x \notin \{x_1, \dots, x_n\}$.
- ▶ $(sr)\langle\sigma\rangle = (s\langle\sigma\rangle r\langle\sigma\rangle)$.
- ▶ $(\lambda x. s)\langle\sigma\rangle = (\lambda x. s\langle\sigma\rangle)$.

Example

- ▶ $(\lambda x. x)\langle\{x \mapsto y\}\rangle = \lambda x. y$.
- ▶ $(\lambda y. x)\langle\{x \mapsto y\}\rangle = \lambda y. y$ (variable capture).



Substitution in a Term

Substitution in a Term

Let $\sigma = \{x_1 \mapsto t_1, \dots, x_n \mapsto t_n\}$ be a substitution and t be a term, then the term $t\sigma$ is defined as follows:

- ▶ $c\sigma = c$.
- ▶ $x_i\sigma = t_i$.
- ▶ $x\sigma = x$, if $x \notin \{x_1, \dots, x_n\}$.
- ▶ $(sr)\sigma = (s\sigma r\sigma)$.
- ▶ $(\lambda x. s)\sigma = (\lambda y. s\{x \mapsto y\}\sigma)$, where y is a fresh variable of the same type as x .

Since the choice of fresh variable is arbitrary, the substitution operation is defined on α -equivalence classes.



Substitution in a Term

Example

- ▶ $(\lambda x. x)\{x \mapsto y\} = \lambda z. z.$
- ▶ $(\lambda y. x)\{x \mapsto y\} = \lambda z. y$ (no variable capture).
- ▶ $(x \lambda x. (x y))\{x \mapsto \lambda z. z\} = (\lambda z. z \lambda u. (u y)).$



Reduction

- ▶ Intuition: Function evaluation.
- ▶ For instance, evaluating function $f : x \mapsto x + 1$ at 2:
 $f(2) = 2 + 1$.
- ▶ As λ -terms: $((\lambda x. x + 1) 2) \triangleright x + 1\{x \mapsto 2\} = 2 + 1$.
(β -reduction)



Reduction

Formally:

$\beta\eta$ -Reduction

- ▶ β -reduction: $((\lambda x.s) t) \triangleright s\{x \mapsto t\}$.
- ▶ η -reduction: $(\lambda x.(t x)) \triangleright t$, if $x \notin fvars(t)$.

Propagates into contexts:

- ▶ If $s \triangleright s'$ then $(s t) \triangleright (s' t)$.
- ▶ If $t \triangleright t'$ then $(s t) \triangleright (s t')$.
- ▶ If $t \triangleright t'$ then $\lambda x. t \triangleright \lambda x. t'$.



Reduction

\triangleright^* - reflexive-transitive closure of \triangleright .

Facts:

- ▶ $\beta\eta$ -Reduction preserves types.
- ▶ If $s \triangleright^* t$ then $s\sigma \triangleright^* t\sigma$.
- ▶ Each term has a unique $\beta\eta$ -normal form modulo α -equivalence.



Reduction

Example

$$\begin{aligned}\lambda x.(f((\lambda y.(y x)) \lambda z.z)) &\triangleright_{\beta} \lambda x.(f((\lambda z.z) x)) \\ &\triangleright_{\beta} \lambda x.(f x) \\ &\triangleright_{\eta} f\end{aligned}$$

Long Normal Form

Long Normal Form

Assume

- ▶ $t = \lambda x_1 \dots \lambda x_m. (r s_1 \dots s_k)$ is in the $\beta\eta$ -normal form,
- ▶ $T_1 \rightarrow \dots \rightarrow T_n \rightarrow U$ is a type of t ,
- ▶ U is atomic and $n \geq m$.

Then the long normal form of t is the term

$$t' = \lambda x_1 \dots \lambda x_m. \lambda x_{m+1} \dots \lambda x_n. (r s'_1 \dots s'_k x'_{m+1} \dots x'_n)$$

where

- ▶ s'_j is the long normal form of s_j .
- ▶ x'_j is the long normal form of x_j .



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The long normal form of any term is that of its normal form.

Since t is in the normal form, r (called the *head* of t) is either a constant or a variable.



Long Normal Form

Example

Let the type of f be $T_1 \rightarrow T_2 \rightarrow U$, with U atomic.

Let t be $\lambda x.(f((\lambda y.(y x)) \lambda z.z))$.



Long Normal Form

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Let t be $\lambda x.(f((\lambda y.(y\ x))\ \lambda z.z))$.

- ▶ The long normal form of t is $\lambda x.\lambda y.(f\ x\ y)$.



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Let t be $\lambda x.(f((\lambda y.(y x)) \lambda z.z))$.

- ▶ The long normal form of t is $\lambda x.\lambda y.(f x y)$.
- ▶ $\lambda x.\lambda y.(f x y)$ is a long normal form of $\lambda x.(f x)$ as well, which is a β -normal form of t .



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- ▶ The long normal form of t is $\lambda x.\lambda y.(f x y)$.
- ▶ $\lambda x.\lambda y.(f x y)$ is a long normal form of $\lambda x.(f x)$ as well, which is a β -normal form of t .
- ▶ In general, to compute long normal form, it is not necessary to perform η -reductions.



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Higher Order Unification

Higher-Order Unification Problem, Unifier

- ▶ Higher-Order Unification problem: a finite set of equations

$$\Gamma = \{s_1 \doteq? t_1, \dots, s_n \doteq? t_n\},$$

where s_i, t_i are λ -terms.

- ▶ Unifier of Γ : a substitution σ such that $s_i\sigma$ and $t_i\sigma$ have the same normal form for each $1 \leq i \leq n$.

We will use capital letters to denote free variables in unification problems.



Higher Order Unification

Example

- ▶ $\Gamma = \{F(f(a, b)) \doteq? f(F(a), b)\}.$

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- ▶ $\Gamma = \{F(f(a, b)) \doteq? f(F(a), b)\}$.
- ▶ Unifier: $\sigma_1 = \{F \mapsto \lambda x.f(x, b)\}$.
- ▶ Justification:

$$F(f(a, b))\sigma_1 = ((\lambda x.f(x, b)) f(a, b)) \triangleright_{\beta} f(f(a, b), b).$$



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$$f(F(a), b)\sigma_1 = f(((\lambda x.f(x, b)) a), b) \triangleright_{\beta} f(f(a, b), b).$$



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$$f(F(a), b)\sigma_2 = f(((\lambda x.f(f(x, b), b)) a), b) \triangleright_{\beta} f(f(f(a, b), b), b).$$



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- ▶ Incomparable wrt instantiation quasi-ordering.
- ▶ Minimal complete set of unifiers.
- ▶ There are problems for which this set does not exist!



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$$\sigma_2 = \{F \mapsto \lambda x. \lambda y. G_2(x, x(H_1^2(x, y)), x(H_2^2(x, y))), G \mapsto \lambda x. Y\} \\ G_2(\lambda x. Y, Y, Y)$$



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...

$$\sigma_n = \{F \mapsto \lambda x. \lambda y. G_n(x, x(H_1^n(x, y)), \dots, x(H_n^n(x, y))), G \mapsto \lambda x. Y\} \\ G_n(\lambda x. Y, Y, \dots, Y) \quad (n \text{ } Y\text{'s})$$



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- ▶ No mcsu. For all $i, j > i$: $\sigma_i \not\leq^{\{F, G\}} \sigma_j$, $\sigma \not\leq^{\{F, G\}} \sigma_i$, $\sigma_i \not\leq^{\{F, G\}} \sigma$, and $\sigma_i = \{F, G\} \sigma_{i+1} \vartheta_i$ where

$$\vartheta_i = \{G_{i+1} \mapsto \lambda x. \lambda y_1. \dots \lambda y_{i+1}. G_i(x, y_1, \dots, y_i), \\ H_1^{i+1} \mapsto H_1^i, \dots, H_i^{i+1} \mapsto H_i^i\}$$



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$$\vartheta_i = \{G_{i+1} \mapsto \lambda x. \lambda y_1. \dots \lambda y_{i+1}. G_i(x, y_1, \dots, y_i), \\ H_1^{i+1} \mapsto H_1^i, \dots, H_i^{i+1} \mapsto H_i^i\}$$

- ▶ Infinite descending chain: $\sigma_0 >^{\{F, G\}} \sigma_1 >^{\{F, G\}} \sigma_2 >^{\{F, G\}} \dots$



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- ▶ The problem is of third order.
- ▶ Higher-order unification of the order 3 and above is of type 0.
- ▶ Second order unification is infinitary.

Higher Order Unification Is Undecidable

- ▶ Idea: Reduce Hilbert's 10th problem to a higher-order unification problem.
- ▶ Hilbert's 10th problem is undecidable: There is no algorithm that takes as input two polynomials $P(X_1, \dots, X_n)$ and $Q(X_1, \dots, X_n)$ with natural coefficients and answers if there exist natural numbers m_1, \dots, m_n such that

$$P(m_1, \dots, m_n) = Q(m_1, \dots, m_n).$$

- ▶ Reduction requires to represent
 - ▶ natural numbers,
 - ▶ addition,
 - ▶ multiplicationin terms of higher-order unification.



Higher Order Unification Is Undecidable

Representation (Goldfarb 1981):

- ▶ Natural number n represented as a λ -term denoted by \bar{n} :

$$\lambda x.g(a, g(a, \dots g(a, x) \dots))$$

with n occurrences of g and a . The type of g is $i \rightarrow i \rightarrow i$ and the type of a is i . Such terms are called Goldfarb numbers.

- ▶ Goldfarb numbers are exactly those that solve the unification problem

$$\{g(a, X(a)) \doteq? X(g(a, a))\}$$

and have the type $i \rightarrow i$.



Higher Order Unification Is Undecidable

Representation:

- ▶ Addition is represented by the λ -term *add*:

$$\lambda n. \lambda m. \lambda x. n(m(x)).$$

- ▶ Multiplication is represented by the higher-order unification problem

$$\{ Y(a, b, g(g(X_3(a), X_2(b)), a)) \stackrel{?}{=} g(g(a, b), Y(X_1(a), g(a, b), a)) \\ Y(b, a, g(g(X_3(b), X_2(a)), a)) \stackrel{?}{=} g(g(b, a), Y(X_1(b), g(a, a), a)) \}$$

that has a solution $\{X_1 \mapsto \overline{m}_1, X_2 \mapsto \overline{m}_2, X_3 \mapsto \overline{m}_3, Y \mapsto t\}$
iff $m_1 \times m_2 = m_3$.



Higher Order Unification Is Undecidable

Reduction from Hilbert's 10th problem:

- ▶ Every equation $P(X_1, \dots, X_n) = Q(X_1, \dots, X_n)$ can be decomposed into a system of equations of the form:

$$X_i + X_j = X_k, \quad X_i \times X_j = X_k, \quad X_i = m.$$

- ▶ With each such system associate a unification problem containing
 - ▶ for each X_i an equation $g(a, X_i(a)) \stackrel{?}{=} X_i(g(a, a))$,
 - ▶ for each $X_i + X_j = X_k$ the equation $add(X_i, X_j) \stackrel{?}{=} X_k$,
 - ▶ for each $X_i \times X_j = X_k$ the two equations used to define multiplication,
 - ▶ for each $X_i = m$ the equation $X_i \stackrel{?}{=} \bar{m}$.



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- ▶ Checking is not hard: Apply the substitution to both sides of each equation, normalize, and compare the normal forms.
- ▶ If the problem is solvable, the procedure will detect it after finite steps.
- ▶ Then... why to bother with looking for another unification procedure?



Higher-Order Unification Procedure

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Why to look for a “better” procedure?

- ▶ To find solutions faster.
- ▶ To report failure for many unsolvable cases.
- ▶ To reduce redundancy.
- ▶ etc.



Important Observation

- ▶ Flex-flex equation has a form

$$\lambda x_1 \dots \lambda x_k. F(s_1, \dots, s_n) \stackrel{!}{=} \lambda x_1 \dots \lambda x_k. G(t_1, \dots, t_m).$$

The head of both sides are free variables.

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- ▶ Flex-flex equations may introduce infinite branching in the search tree (very undesirable property).



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- ▶ The appropriate c always exists because for each type we have at least one constant of that type.
- ▶ Flex-flex equations may introduce infinite branching in the search tree (very undesirable property).
- ▶ Idea: Do not try to solve flex-flex equations. Assume them solved. Preunification.



Preunification

Preunifier

- ▶ Let \cong be the least congruence relation on the set of λ -terms that contains the set of flex-flex pairs.
- ▶ A substitution σ is a preunifier for a unification problem $\{s_1 \doteq? t_1, \dots, s_n \doteq? t_n\}$ iff

$$\text{normal-form}(s_i\sigma) \cong \text{normal-form}(t_i\sigma)$$

for each $1 \leq i \leq n$.

Convention

- ▶ $\overline{x_n}$ abbreviates x_1, \dots, x_n .
- ▶ $\lambda\overline{x_n}$ abbreviates $\lambda x_1 \dots \lambda x_n$.



One Technical Notion

Partial Binding

A partial binding of type $T_1 \rightarrow \dots \rightarrow T_n \rightarrow U$ (U atomic) is a term of the form

$$\lambda \overline{x_n}. I(\overline{\lambda y_{m_1}^1} \cdot H_1(\overline{x_n}, \overline{y_{m_1}^1}), \dots, \overline{\lambda y_{m_k}^k} \cdot H_k(\overline{x_n}, \overline{y_{m_k}^k}))$$

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- ▶ the type of x_i is T_i for $1 \leq i \leq n$,
- ▶ the type of l is $S_1 \rightarrow \dots \rightarrow S_k \rightarrow U$, where S_j is $R_j^1 \rightarrow \dots \rightarrow R_{m_j}^j \rightarrow S'_j$ (S'_j atomic) for $1 \leq j \leq k$,



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- ▶ the type of y_j^i is R_j^i for $1 \leq i \leq k$ and $1 \leq j \leq m_i$.
- ▶ the type of H_i is $T_1 \rightarrow \dots \rightarrow T_n \rightarrow R_1^i \rightarrow \dots \rightarrow R_{m_i}^i \rightarrow S'_i$ for $1 \leq i \leq k$.



Partial Binding

$$\lambda \overline{x}_n. I(\lambda \overline{y}_{m_1}^1. H_1(\overline{x}_n, \overline{y}_{m_1}^1), \dots, \lambda \overline{y}_{m_k}^k. H_k(\overline{x}_n, \overline{y}_{m_k}^k))$$

- ▶ Imitation binding: I is a constant or a free variable.
- ▶ (i^{th}) Projection binding: I is x_i .
- ▶ A partial binding t is appropriate to F if t and F have the same types.
- ▶ $F \mapsto t$: Appropriate partial (imitation, projection) binding if t is partial (imitation, projection) binding appropriate to F .



Higher-Order Preunification Procedure

- ▶ The inference system \mathcal{U}_{HOP} consists of the rules:
 - ▶ **Trivial**
 - ▶ **Decomposition**
 - ▶ **Variable Elimination**
 - ▶ **Orient**
 - ▶ **Imitation**
 - ▶ **Projection**
- ▶ The rules transform systems: pairs $\Gamma; \sigma$, where Γ is a higher-order unification problem and σ is a substitution.
- ▶ A system $\Gamma; \sigma$ is in presolved form if Γ is either empty or consists of flex-flex equations only.



Higher-Order Preunification Procedure. Rules

Trivial: $\{t \doteq^? t\} \cup P'; \vartheta \Longrightarrow P'; \vartheta$



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$$\begin{aligned} & \{\lambda \bar{x}_k. l(s_1, \dots, s_n) \doteq^? \lambda \bar{x}_k. l(t_1, \dots, t_n)\} \cup P'; \vartheta \Longrightarrow \\ & \{\lambda \bar{x}_k. s_1 \doteq^? \lambda \bar{x}_k. t_1, \dots, \lambda \bar{x}_k. s_n \doteq^? \lambda \bar{x}_k. t_n\} \cup P'; \vartheta. \end{aligned}$$

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Variable Elimination:

$$\{\lambda x_1 \dots \lambda x_k. F(x_1, \dots, x_k) \doteq^? t\} \cup P'; \vartheta \Longrightarrow P' \{F \mapsto t\}; \vartheta \{F \mapsto t\}.$$

If $F \notin fvars(t)$



Higher-Order Preunification Procedure. Rules

Orient:

$$\{\lambda \bar{x}_k. I(t_1, \dots, t_m) \doteq^? \lambda \bar{x}_k. F(s_1, \dots, s_n)\} \cup P'; \vartheta \implies$$
$$\{\lambda \bar{x}_k. F(s_1, \dots, s_n) \doteq^? \lambda \bar{x}_k. I(t_1, \dots, t_m)\} \cup P'; \vartheta$$

where I is not a free variable.



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Imitation:

$$\begin{aligned} & \{\lambda \bar{x}_k. F(s_1, \dots, s_n) \doteq^? \lambda \bar{x}_k. f(t_1, \dots, t_m)\} \cup P'; \vartheta \implies \\ & \{\lambda \bar{x}_k. f(\lambda \bar{z}_1^1. H_1(s_1, \dots, s_n, \bar{z}_1^1), \dots, \lambda \bar{z}_{r_m}^m. H_m(s_1, \dots, s_n, \bar{z}_{r_m}^m)) \sigma) \\ & \quad \doteq^? \lambda \bar{x}_k. f(t_1, \dots, t_m) \sigma\} \cup P' \sigma; \vartheta \sigma \end{aligned}$$

where

- ▶ $\sigma = \{F \mapsto \lambda \bar{y}_n. f(\lambda \bar{z}_1^1. H_1(\bar{y}_n, \bar{z}_1^1), \dots, \lambda \bar{z}_{r_m}^m. H_m(\bar{y}_n, \bar{z}_{r_m}^m))\}$, appropriate imitation binding.
- ▶ H_1, \dots, H_m are fresh variables.



Higher-Order Preunification Procedure. Rules

Projection:

$$\begin{aligned} & \{\lambda \bar{x}_k. F(s_1, \dots, s_n) \doteq^? \lambda \bar{x}_k. l(t_1, \dots, t_m)\} \cup P'; \vartheta \implies \\ & \{\lambda \bar{x}_k. s_i(\lambda \bar{z}_{r_1}^1. H_1(s_1, \dots, s_n, \bar{z}_{r_1}^1), \dots, \lambda \bar{z}_{r_m}^m. H_m(s_1, \dots, s_n, \bar{z}_{r_m}^m))\sigma \\ & \quad \doteq^? \lambda \bar{x}_k. l(t_1, \dots, t_m)\sigma\} \cup P'\sigma; \vartheta\sigma \end{aligned}$$

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- ▶ Successful leaves contain presolved systems.
- ▶ If $\Delta; \sigma$ is a successful leaf, σ is a solution of Γ computed by the higher-order preunification procedure.



Higher-Order Preunification. Major Results

Theorem (Soundness)

If $\Gamma; \varepsilon \Longrightarrow^ \Delta; \sigma$ and Δ is in presolved form, then $\sigma|_{fvars(\Gamma)}$ is a preunifier of Γ .*

Theorem (Completeness)

If ϑ is a preunifier of Γ , then there exists a sequence of transformations $\Gamma; \varepsilon \Longrightarrow^ \Delta; \sigma$ such that Δ is in presolved form, and $\sigma \leq_{\beta}^{fvars(\Gamma)} \vartheta$.*



Higher-Order Preunification. Examples

Example

- ▶ Unification problem $\{F(f(a)) \doteq? f(F(a))\}$.
- ▶ The preunification procedure enumerates the complete set of (pre)unifiers that is infinite.
- ▶ Here we show only two derivations.



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$$\Longrightarrow_{Tr} \emptyset; \{F \mapsto \lambda x. f(x), G \mapsto \lambda x. x\}$$



Higher-Order Preunification. Examples

Example

- ▶ Problem $\{\lambda x. F(f(x, G)) \doteq? \lambda x. g(f(x, G_1), f(x, G_2))\}$.
- ▶ Here we show only the successful derivation.

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$$\{\lambda x. F(f(x, G)) \doteq? \lambda x. g(f(x, G_1), f(x, G_2))\}; \varepsilon$$



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$$\begin{aligned} & \{\lambda x. F(f(x, G)) \doteq? \lambda x. g(f(x, G_1), f(x, G_2))\}; \varepsilon \\ & \implies_{limit} \{\lambda x. g(H_1(f(x, G)), H_2(f(x, G))) \doteq? \lambda x. g(f(x, G_1), f(x, G_2))\}; \\ & \quad \{F \mapsto \lambda y. g(H_1(y), H_2(y))\} \end{aligned}$$



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$$\begin{aligned} \implies_{\text{Dec, Proj, Proj}} & \{\lambda x. f(x, G) \doteq? \lambda x. f(x, G_1), \lambda x. f(x, G) \doteq? \lambda x. f(x, G_2)\}; \\ & \{F \mapsto \lambda y. g(y, y), H_1 \mapsto \lambda y. y, H_2 \mapsto \lambda y. y\} \end{aligned}$$



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Higher-Order Preunification. Examples

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- ▶ Problem $\{\lambda x. F(x, a) \doteq? \lambda x. f(G(a, x))\}$.
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$\implies_{limit} \{\lambda x. f(H(x, a)) \doteq? \lambda x. f(G(a, x))\}; \{F \mapsto \lambda y_1. \lambda y_2. f(H(y_1, y_2))\}$



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$\implies_{\text{Dec}} \{\lambda x. H(x, a) \doteq? \lambda x. G(a, x)\}; \{F \mapsto \lambda y_1. \lambda y_2. f(H(y_1, y_2))\}$

Flex-flex.



Decidable Subcases

Some decidable subcases of higher-order unification:

- ▶ Monadic second-order unification. Terms do not contain constants of arity greater than 1.
Example: $\{\lambda x.f(F(x)) \doteq? \lambda x.F(f(x))\}$.
- ▶ Second-order unification with linear occurrences of second-order variables.
- ▶ Unification with higher-order patterns. Pattern is a term t such that for every subterm of the form $F(s_1, \dots, s_n)$, the s 's are distinct variables bound in t .
Example: $\{\lambda x.\lambda y.F(x) \doteq? \lambda x.\lambda y.c(G(y, x))\}$.
- ▶ Higher-order matching. One side in the equations is a closed term.
Example. $\{\lambda x.F(x, \lambda y.y) \doteq? \lambda x.f(x, a)\}$.
- ▶ Stratified second-order unification.
- ▶ Bounded second-order unification.

